

On Gradings Modulo 2 of Simple Lie Algebras in Characteristic 2

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Abstract. The ground field in the text is of characteristic 2. The classification of modulo 2 gradings of simple Lie algebras is vital for the classification of simple finite-dimensional Lie superalgebras: with each grading, a simple Lie superalgebra is associated, see arXiv:1407.1695. No classification of gradings was known for any type of simple Lie algebras, bar restricted Jacobson–Witt algebras (i.e., the first derived of the Lie algebras of vector fields with truncated polynomials as coefficients) on not less than 3 indeterminates. Here we completely describe gradings modulo 2 for several series of Lie algebras and their simple relatives: of special linear series, its projectivizations, and projectivizations of the derived Lie algebras of two inequivalent orthogonal series (except for $\mathfrak{o}_{\Pi}(8)$). The classification of gradings is new, but all of the corresponding superizations are known. For the simple derived Zassenhaus algebras of height $n > 1$, there is an $(n - 2)$ -parametric family of modulo 2 gradings; all but one of the corresponding simple Lie superalgebras are new. Our classification also proves non-triviality of a deformation of a simple 3|2-dimensional Lie superalgebra (new result).

Key words: modular vectorial Lie algebra; characteristic 2; simple Lie algebra; simple Lie superalgebra

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1 Introduction

1.1 Basic definitions

Hereafter \mathbb{K} is an algebraically closed field of characteristic $p = 2$, unless otherwise specified; all algebras are finite-dimensional; for a review of simple vectorial Lie (super)algebras over \mathbb{K} and basic background, see [3].

Lie superalgebras in characteristic 2. A *Lie superalgebra* is a superspace $\mathfrak{g} = \mathfrak{g}_0 \oplus \mathfrak{g}_1$ such that the even part \mathfrak{g}_0 is a Lie algebra, the odd part \mathfrak{g}_1 is a \mathfrak{g}_0 -module, and on \mathfrak{g}_1 , a squaring (roughly speaking, the halved bracket) is defined as a map

$$x \mapsto x^2 \quad \text{such that } (ax)^2 = a^2x^2 \text{ for any } x \in \mathfrak{g}_1 \text{ and } a \in \mathbb{K}, \text{ and} \\ (x + y)^2 - x^2 - y^2 \text{ is a bilinear form on } \mathfrak{g}_1 \text{ with values in } \mathfrak{g}_0.$$

Then the bracket of odd elements is defined to be

$$[x, y] := (x + y)^2 - x^2 - y^2.$$

The Jacobi identity involving odd elements takes the following form:

$$[x^2, y] = [x, [x, y]] \quad \text{for any } x \in \mathfrak{g}_1, y \in \mathfrak{g}_0, \quad [x^2, x] = 0 \quad \text{for any } x \in \mathfrak{g}_1.$$

Divided powers. There are two natural integer bases of the commutative algebra $\mathbb{C}[x]$ of polynomials in m indeterminates $x = (x_1, \dots, x_m)$: the monomial one and the basis of divided powers, constructed as follows. For any multi-index $\underline{r} = (r_1, \dots, r_m)$, where r_1, \dots, r_m are non-negative integers, we set

$$u_i^{(r_i)} := \frac{x_i^{r_i}}{r_i!} \quad \text{and} \quad u^{(\underline{r})} := \prod_{1 \leq i \leq m} u_i^{(r_i)}.$$

These $u^{(\underline{r})}$ form an integer basis of $\mathbb{C}[x]$. Their multiplication relations are

$$u^{(\underline{r})} \cdot u^{(\underline{s})} = \binom{\underline{r} + \underline{s}}{\underline{r}} u^{(\underline{r} + \underline{s})}, \quad \text{where} \quad \binom{\underline{r} + \underline{s}}{\underline{r}} = \prod_{1 \leq i \leq m} \binom{r_i + s_i}{r_i}. \quad (1.1)$$

Being interested in simple Lie algebras, observe that every simple \mathbb{Z} -graded Lie algebra $\mathfrak{g} = \bigoplus \mathfrak{g}_i$ of vector fields is *transitive*, i.e., such that

$$[\mathfrak{g}_{\leq 0}, x] = 0 \quad \text{for a given } x \in \mathfrak{g}_{>0} \text{ implies } x = 0, \text{ where } \mathfrak{g}_{\leq 0} = \bigoplus_{i \leq 0} \mathfrak{g}_i, \mathfrak{g}_{>0} = \bigoplus_{i > 0} \mathfrak{g}_i.$$

For an arbitrary field \mathbb{K} of characteristic $p > 0$, it is easy to see that the Lie algebra $\mathfrak{der} \mathbb{K}[x]$ is not transitive in the \mathbb{Z} -grading induced by the standard \mathbb{Z} -grading of $\mathbb{K}[x]$, i.e., $\deg x_i = 1$ for all i . The situation is remedied if we consider the commutative algebra $\mathbb{K}[u]$ spanned by all the elements $u^{(\underline{r})}$ with multiplication relations (1.1). For any m -tuple $\underline{N} = (N_1, \dots, N_m)$, where N_i are either positive integers, or infinity, denote (we set $p^\infty := \infty$)

$$\mathcal{O}(m; \underline{N}) := \mathbb{K}[u; \underline{N}] = \text{Span}_{\mathbb{K}} (u^{(\underline{r})} \mid r_i < p^{N_i}).$$

The algebra $\mathbb{K}[u]$ and its subalgebras $\mathbb{K}[u; \underline{N}]$ are called the *algebras of divided powers*; they are analogs of the polynomial algebra. Let $\mathbf{1} := (1, \dots, 1)$ denote the shearing vector \underline{N} with the smallest values of heights N_i of the indeterminates.

Clearly, if $N_i \neq 1$ for at least one i , then $\mathcal{O}(m; \underline{N})$ has more than m generators: namely $y_{i,j} := u_i^{(p^{j-1})}$. Any derivation D of a given algebra is determined by the values of D on the generators, so $\mathfrak{der} \mathcal{O}(m; \underline{N})$ has more than m analogs of partial derivations: one for each generator, with a functional parameter $f_{ij}(u) \in \mathcal{O}(m; \underline{N})$ – coefficient of each partial derivative $\partial_{y_{i,j}}$, whereas the coefficients of $\partial_{y_{i,j}} \in \mathfrak{vect}(\sum N_i; \mathbf{1})$ belong to $\mathcal{O}(\sum N_i; \mathbf{1})$. Following the definitions over \mathbb{C} we are interested in subalgebras of $\mathfrak{der} \mathcal{O}(m; \underline{N})$ such that the dimension of the nonpositive part (in the standard \mathbb{Z} -grading) is equal to m .

Solution was found long ago: one has to introduce *distinguished* partial derivatives ∂_i , each of them serving as several partial derivatives (corresponding to $u_i, u_i^{(p)}, u_i^{(p^2)}, \dots$) at once (if instead of the usual powers we use divided ones, the sign $(-1)^{j-1}$ is not needed):

$$\partial_i(u_j^{(k)}) := \delta_{ij} u_j^{(k-1)} \quad \text{for all } k, \text{ i.e., } \partial_i = \sum_{j \geq 1} (-1)^{j-1} y_{i,1}^{p-1} \cdots y_{i,j-1}^{p-1} \partial_{y_{i,j}}.$$

The *general vectorial Lie algebra of distinguished derivations*¹

$$\mathfrak{vect}(m; \underline{N}) = \text{Span}_{\mathbb{K}} (f \partial_k \mid f \in \mathcal{O}(m; \underline{N}), k = 1, \dots, m)$$

is simple (except for $m = 1$ and $p = 2$).

¹For $p > 0$, the Lie algebra $\mathfrak{vect}(m; \underline{N})$ is called *Jacobson–Witt algebra* if $\underline{N} \neq \mathbf{1}$; it is usually denoted $W(m; \underline{N})$ for any m and \underline{N} ; if $m = 1$, it is called *Zassenhaus algebra*. Jacobson–Witt algebras are simple if $m > 1$; there is no special name for the simple derived $\mathfrak{vect}^{(1)}(1; \underline{n})$, see a discussion in [14]. The Lie algebra of *divergence-free*, or “special”, vector fields is denoted $\mathfrak{svect}(m; \underline{N})$, usually abbreviated to $S(m; \underline{N})$.

p -structure. If \mathfrak{g} is a Lie algebra, then for every $x \in \mathfrak{g}$, the operator $(\text{ad}_x)^p$ is a derivation of \mathfrak{g} . If this derivation is inner for every $x \in \mathfrak{g}$, then the Lie algebra \mathfrak{g} is said to be *restricted* or having a p -structure. More specifically, a p -structure on \mathfrak{g} is a map $[p]: \mathfrak{g} \rightarrow \mathfrak{g}$, $x \mapsto x^{[p]}$ such that

$$[x^{[p]}, y] = (\text{ad}_x)^p(y) \quad \text{for any } x, y \in \mathfrak{g}, \quad (1.2)$$

$$(ax)^{[p]} = a^p x^{[p]} \quad \text{for any } a \in \mathbb{K}, x \in \mathfrak{g},$$

$$(x + y)^{[p]} = x^{[p]} + y^{[p]} + \sum_{1 \leq i \leq p-1} s_i(x, y) \quad \text{for any } x, y \in \mathfrak{g}, \quad (1.3)$$

where $s_i(x, y)$ is the coefficient of λ^{i-1} in $(\text{ad}_{\lambda x + y})^{p-1}(x)$.

Remark 1.1.

- 1) If the Lie algebra \mathfrak{g} is without center, then the last two conditions of (1.3) follow from the first one. There might be more than one p -structure on one Lie algebra; all of them are equal modulo center. Hence, on any simple Lie algebra, there is at most one p -structure.
- 2) The following condition is sufficient for a Lie algebra \mathfrak{g} to possess a p -structure: for a basis $\{g_i\}_{i \in I}$ of \mathfrak{g} , there exist elements $g_i^{[p]}$ such that

$$[g_i^{[p]}, y] = (\text{ad}_{g_i})^p(y) \quad \text{for any } y \in \mathfrak{g}.$$

We consider the following problem.

Problem 1.2. For any finitely generated commutative group G , classify G -gradings of simple finite-dimensional Lie algebras over \mathbb{K} .

Lie algebras for which a solution of Problem 1.2 is known. Although we are interested in a particular case of Problem 1.2, let us briefly review the known general results.

- For $p = 0$, for a clear exposition of the solution (for the \mathbb{Z} - and \mathbb{Z}/n -gradings), see the book [17, around p. 500], and also [13].
- For $p \neq 2$, [18] is a very lucid review of the cases where the solution of Problem 1.2 has been found; for further details, see [1, 19]; for examples of applications of certain G -gradings, see [20].
- For $p = 2$, the result of [1] is as follows: all G -gradings of the Jacobson–Witt algebra $W(m; \mathbb{1})$ (it is $\mathbf{vect}(m; \mathbb{1})$ in our notation) for $m \geq 3$ are given by G -gradings of the corresponding algebra of divided powers $\mathcal{O}(m; \mathbb{1})$ due to an isomorphism of their automorphism group schemes [27]. The classification of such gradings is given. Any G -grading of $\mathcal{O}(m; \mathbb{1})$ is equivalent, up to an algebra automorphism, to one that can be described as follows. For a given s such that $0 \leq s \leq m$, and $a_1, \dots, a_m \in G$, set

$$\mathcal{O}_g = \text{Span} \left\{ (1 + x_1)^{j_1} \cdots (1 + x_s)^{j_s} x_{s+1}^{j_{s+1}} \cdots x_m^{j_m} \mid j_i = 0 \text{ or } 1, \sum_{1 \leq i \leq m} j_i a_i = g \right\}, \quad (1.4)$$

where $a_1, \dots, a_m \in G$ are the respective degrees of the indeterminates generating $\mathcal{O}(m; \mathbb{1})$, i.e.,

$$1 + x_1, \dots, 1 + x_s, x_{s+1}, \dots, x_m.$$

For $p > 0$ and the *restricted* Lie algebras considered in [1] (for $p = 2$: Jacobson–Witt algebras $\mathbf{vect}(m; \underline{N})$ for $m \geq 3$; for $p > 2$: Jacobson–Witt algebras, simple relatives of Hamiltonian algebras and algebras of divergence-free vector fields), the only possible $\mathbb{Z}/2$ -gradings are generated by those described in equation (1.4). For *non-restricted* Lie algebras, we know several examples of $\mathbb{Z}/2$ -gradings of Kaplansky algebras, see [8].

1.2 Problem 1.2 for $G = \mathbb{Z}/2$ and $p = 2$: an application of the solution

In [7], there are offered two methods for constructing a simple finite-dimensional Lie superalgebra from every simple finite-dimensional Lie algebra *over a field of characteristic 2*; it is proved that every simple finite-dimensional Lie superalgebra can be obtained by one of these two methods (queerification and “method 2”). The “method 2” depends on the $\mathbb{Z}/2$ -gradings of the simple Lie algebra which is being superized. Let us recall the method:

Let $\mathfrak{g} = \mathfrak{g}_{\bar{0}} \oplus \mathfrak{g}_{\bar{1}}$ be a simple Lie algebra with a $\mathbb{Z}/2$ -grading gr . Let the 1-step restricted closure of \mathfrak{g} associated with the grading gr be

$$\begin{aligned} \mathfrak{g}^{(1)} := & \text{the minimal Lie subalgebra of the restricted closure } \bar{\mathfrak{g}} \text{ containing } \mathfrak{g} \\ & \text{and all the elements } x^{[2]}, \text{ where } x \in \mathfrak{g}_{\bar{1}}. \end{aligned} \quad (1.5)$$

Clearly, there is a single way to extend the grading gr from \mathfrak{g} to $\mathfrak{g}^{(1)}$; we assume this extension performed. On the space of $\mathfrak{g}^{(1)}$, define the structure of a Lie superalgebra denoted (in what follows, we often omit indicating the grading gr since it enters the definition of $\mathfrak{g}^{(1)}$)

$$\mathfrak{s}(\mathfrak{g}^{(1)}, \text{gr}) \quad \text{by setting } x^2 := x^{[2]} \text{ for any } x \in \mathfrak{g}_{\bar{1}}, \quad (1.6)$$

and retaining the bracket of any even element with any other element. The Lie superalgebra $\mathfrak{s}(\mathfrak{g}^{(1)})$ is simple, see [7]. Our strategic goal is classification of simple Lie (super)algebras, so we formulate our description of $\mathbb{Z}/2$ -gradings gr of \mathfrak{g} in terms of superizations $\mathfrak{s}(\mathfrak{g}^{(1)})$ whenever we can.

1.3 How we seek $\mathbb{Z}/2$ -gradings

Let \mathfrak{g} be a Lie algebra, and let $\mathfrak{g} = \mathfrak{g}_{\bar{0}} \oplus \mathfrak{g}_{\bar{1}}$ be its $\mathbb{Z}/2$ -grading. For an any $x \in \mathfrak{g}$, we denote by $x_{\bar{0}}$ its even part and by $x_{\bar{1}}$ its odd part. We have

$$[x, y] = [x_{\bar{0}} + x_{\bar{1}}, y_{\bar{0}} + y_{\bar{1}}] = [x_{\bar{0}}, y_{\bar{0}}] + [x_{\bar{1}}, y_{\bar{1}}] + [x_{\bar{0}}, y_{\bar{1}}] + [x_{\bar{1}}, y_{\bar{0}}] \quad \text{for any } x, y \in \mathfrak{g}.$$

This implies

$$([x, y])_{\bar{0}} = [x_{\bar{0}}, y_{\bar{0}}] + [x_{\bar{1}}, y_{\bar{1}}] \quad \text{and} \quad ([x, y])_{\bar{1}} = [x_{\bar{0}}, y_{\bar{1}}] + [x_{\bar{1}}, y_{\bar{0}}].$$

Finally, let $U \in \text{End}(\mathfrak{g})$, where \mathfrak{g} is considered as a vector space, be the projection to the $\mathfrak{g}_{\bar{1}}$, i.e., $Ux = x_{\bar{1}}$ and $(I - U)x = x_{\bar{0}}$, where I is the identity operator. A linear operator U is such a projection to the odd part of \mathfrak{g} in some $\mathbb{Z}/2$ -grading if and only if it satisfies the following conditions for all $x, y \in \mathfrak{g}$:

$$U^2 = U, \quad (1.7a)$$

$$U[x, y] = [Ux, (I - U)y] + [(I - U)x, Uy] = -2[Ux, Uy] + [Ux, y] + [x, Uy]. \quad (1.7b)$$

Having fixed a basis in \mathfrak{g} , we express these conditions in terms of structure constants c_k^{ij} as (summation over repeated indices is assumed)

$$U_j^k U_k^i = U_j^i, \quad (1.8a)$$

$$c_l^{ij} U_k^l = c_k^{il} U_l^j + c_k^{lj} U_l^i - 2c_k^{lm} U_l^i U_m^j. \quad (1.8b)$$

For $p = 2$, equation (1.8b) becomes linear and easy (for example, for *Mathematica*-based computer package *SuperLie*, see [15]) to solve. There remains, however, a problem to be solved:

condition (1.8a) is still quadratic,

we need equivalence classes of solutions $U \text{ mod } \text{Aut}(\mathfrak{g})$, not individual operators.

A comment: gradings and derivations. For a general discussion of relation between gradings and derivations, and interesting examples for $p = 2$, see [8]. For $p = 3$, an example illustrating the said discussion is the $\mathbb{Z}/4$ -grading of the Skryabin algebra \mathfrak{bn} , see [16].

The Lie algebra $\mathfrak{der\ vect}(m; \underline{N})$ of all derivations of $\mathfrak{vect}(m; \underline{N})$ coincides with the p -envelope of $\mathfrak{vect}(m; \underline{N})$. So the problem of classification of equivalence classes of \mathbb{Z}/p -gradings of $\mathfrak{vect}(m; \underline{N})$ reduces to the classification of equivalence classes of toral elements in $\mathfrak{der\ vect}(m; \underline{N})$. The equivalence classes of maximal tori with respect to the group of automorphisms are described in [21, 29], and the answer depends on $N_1 - 2$ parameters for $m = 1$.

1.4 Our results

- 1) We classify the $\mathbb{Z}/2$ -gradings of the Lie algebras of series \mathfrak{sl} , their simple subquotients, and simple derived or subquotients of both orthogonal series – \mathfrak{o}_I and \mathfrak{o}_{II} , – except for $\mathfrak{o}_{II}(8)$. In all the cases considered, these gradings yield the known superizations of the corresponding Lie algebras. Note that one of the gradings of $\mathfrak{o}^{(1)}(3)$ has no analogs among the $\mathbb{Z}/2$ -gradings of the simple 3-dimensional Lie algebras for $p \neq 2$. This unusual grading has analogs among $\mathbb{Z}/2$ -gradings of $\mathfrak{vect}^{(1)}(1; \underline{n})$, of which $\mathfrak{o}^{(1)}(3) \simeq \mathfrak{vect}^{(1)}(1; \underline{2})$ is a particular case.
- 2) The classification of $\mathbb{Z}/2$ -gradings of $\mathfrak{o}^{(1)}(3)$ has one more application: it gives the shortest known proof of the fact that the deform of $\mathfrak{oo}_{II}^{(1)}(1|2)$, one of the two superizations of $\mathfrak{o}^{(1)}(3)$, found in [5], is a “true” one, not “semitrivial”, see Remark 6.6; this fact is new and unexpected (although the deform itself, $\mathfrak{oo}_{II}^{(1)}(1|2)$, is known).
- 3) We describe an $(n - 2)$ -parametric collection of $\mathbb{Z}/2$ -gradings of $\mathfrak{vect}^{(1)}(1; \underline{n})$. For $n = 2$, these gradings yield three non-isomorphic Lie superalgebras.

For $n > 2$, these $\mathbb{Z}/2$ -grading yield

- a) purely even Lie superalgebra $\mathfrak{vect}^{(1)}(1; \underline{n}|0)$;
- b) an $(n - 2)$ -parametric family of filtered deforms of $\mathfrak{k}(1; \underline{n - 1}|1)$;
- c) a filtered deform of $\mathfrak{q}(\mathfrak{vect}(1; \underline{n - 1}))$.

Examples where $\mathbb{Z}/2$ -gradings of “the same algebra” for $p \neq 2$ and $p = 2$ differ or where previously unknown $\mathbb{Z}/2$ -gradings have been found. These are the most interesting of our results.

- 1) It is known that for any p , there is only one simple Lie algebra of dimension 3: for $p \neq 2$, it is $\mathfrak{o}(3) \simeq \mathfrak{sl}(2)$; for $p = 2$, it is $\mathfrak{o}^{(1)}(3)$, the derived of $\mathfrak{o}(3)$.

For $p \neq 2$, it is also known that there is only one (as always, up to an automorphism) nontrivial $\mathbb{Z}/2$ -grading, and hence if the superization procedure had been defined for $p \neq 2$, the superization of $\mathfrak{sl}(2)$ would have been unique, $\mathfrak{sl}(1|1)$.

For $p = 2$, there are 2 inequivalent nontrivial $\mathbb{Z}/2$ -gradings of $\mathfrak{o}^{(1)}(3)$, as we will see below. The corresponding non-isomorphic, see [22], Lie superalgebras are $\mathfrak{oo}_{II}^{(1)}(1|2)$ and $\mathfrak{oo}_{II}^{(1)}(1|2)$. (It is an interesting open problem to find out if the Lie superalgebra $\mathfrak{oo}_{II}^{(1)}(1|2n)$ is a deform of $\mathfrak{oo}_{II}^{(1)}(1|2n)$ for $n > 1$; this requires to consider $\mathbb{Z}/2$ -gradings and deforms of $\mathfrak{k}(2n + 1; \underline{1})$ for $n > 0$.)

- 2) For $p \neq 2$, the $\mathbb{Z}/2$ -gradings of the Zassenhaus algebra $\mathfrak{vect}(1; \underline{n})$ were only known for $n = 1$, i.e., for the restricted algebras, see [1] (and, for $n > 1$, obvious $\mathbb{Z}/2$ -gradings with some of either x or $x + 1$ declared odd). We have found new $(n - 2)$ -parametric family of $\mathbb{Z}/2$ -gradings in the non-restricted case. These gradings yield superizations which have no known analogs in the case $p \neq 2$.

Remark 1.3. Describing $\mathfrak{der} \mathfrak{g}$ for various Lie algebras \mathfrak{g} , we heavily rely on Permyakov's results [23] used in [2]. Consider, for example, $\mathfrak{sl}(2n)$ for $n > 1$. Actually, Permyakov [23] does not explicitly describe $\mathfrak{der} \mathfrak{sl}(2n)$, he just shows that $\dim H^1(\mathfrak{sl}(2n), \mathfrak{sl}(2n)) = 1$, this is the codimension of the subalgebra of inner derivations in $\mathfrak{der} \mathfrak{sl}(2n)$. However, it is easy to see that every element of $\mathfrak{pgl}(2n)$ described here represents a derivation of $\mathfrak{sl}(2n)$; different elements represent different derivations; every inner derivation is represented by some element, and the codimension of the subalgebra of inner derivations of $\mathfrak{sl}(2n)$ is equal to 1; therefore, $\mathfrak{pgl}(2n)$ is isomorphic to $\mathfrak{der} \mathfrak{sl}(2n)$. Similar considerations apply when we refer to [2, 23] while describing algebras of derivations of other Lie algebras.

1.5 Open questions

For $G = \mathbb{Z}/2$, the gradings (1.4) with $s = 0$ of $\mathfrak{vect}(m; \mathbb{1})$ for $m > 2$ yield $\mathfrak{vect}(k; \mathbb{1}|m-k)$, where the vectors $\mathbb{1}$ have m and k coordinates, respectively. These are known superizations. If $s \neq 0$ in (1.4) and $a_i = \bar{1}$ for some of the indices $i \leq s$, then the corresponding indeterminates $1 + x_i$ are odd; at the moment we are unable to identify the resulting Lie superalgebra.

The list of simple Lie algebras for which Problem 1.2 is open:

- For $p > 3$, the simple vectorial Lie algebras for the shearing vector $\underline{N} \neq \mathbb{1}$, and the deforms (results of deformations) thereof (for their classification and description, see [20, 25, 28]).
- For $p = 3$, the simple vectorial Lie algebras; in particular, exceptional ones, mainly discovered by Skryabin and lucidly described in [16], and their deforms to be described (for a review, see [5]); the deforms of $\mathfrak{o}(5)$ and Brown algebras described in [9].
- For $p = 2$, there are many examples of simple Lie algebras of types not existing for $p \neq 2$, see [2, 3, 4, 8, 12, 14, 26], and [5, 6].
- We also have to consider the simple relative of $\mathfrak{o}_{\Pi}(8)$.

Conjecture 1.4 (D. Leites). *For (the simple derived of) Lie algebras with indecomposable Cartan matrix not considered in this note, i.e., parametric families of Weisfeiler–Kac algebras, all their $\mathbb{Z}/2$ -gradings correspond, conjecturally, to their known superizations listed in [6].*

2 The $\mathfrak{sl}(n)$ and $\mathfrak{psl}(2n)$ for $n > 2$: same answer as for $p \neq 2$

Clearly, $\mathfrak{sl}(0|n) = \mathfrak{sl}(n)$ and $\mathfrak{psl}(0|2n) = \mathfrak{psl}(2n)$.

Theorem 2.1. *All $\mathbb{Z}/2$ -gradings of the Lie algebras $\mathfrak{sl}(n)$ for $n > 2$ and $\mathfrak{psl}(2n)$ for $n > 2$ are analogous to those for $p = 0$, i.e., correspond to $\mathfrak{sl}(k|n-k)$ for $k = 0, \dots, \lfloor \frac{n}{2} \rfloor$ and $\mathfrak{psl}(k|2n-k)$ for $k = 0, \dots, n$.*

Remark 2.2. The algebra $\mathfrak{psl}(2)$ is not simple, so we do not consider algebras $\mathfrak{sl}(2)$ and $\mathfrak{psl}(2)$. We do not consider the algebra $\mathfrak{psl}(4)$ in this section either, since its algebra of derivations is more complicated than the algebra of derivations of $\mathfrak{psl}(2n)$ for $n > 2$; however, $\mathfrak{psl}(4)$ is isomorphic to $\mathfrak{o}_{\Pi}^{(2)}(6)$, and the answer in this case is given in Remark 5.2.

Proof. *The $\mathfrak{sl}(2n+1)$ series ($n > 0$).* All derivations of $\mathfrak{sl}(2n+1)$ are inner ones, see [23], so the general solution of the linear equation (1.7b) is $U = \text{ad}_A$, where $A \in \mathfrak{sl}(2n+1)$. The nonlinear equation (1.7a) reduces then to $\text{ad}_A = (\text{ad}_A)^2$. Now recall that there is the 2-structure on $\mathfrak{sl}(2n+1)$ given by $A^{[2]} = A^2$, see [6, 7]. Therefore

$$\text{ad}_A = (\text{ad}_A)^2 = \text{ad}_{A^{[2]}} = \text{ad}_{A^2},$$

and since $\mathfrak{sl}(2n+1)$ has no center, we have $A = A^2$, i.e., A is a projection. Since $\text{tr } A$ is equal to the dimension of the subspace onto which A projects (just look at the normal form of the matrix of the projection), it follows that

$$\begin{aligned} &\text{a given projection } A \text{ belongs to } \mathfrak{sl} \text{ if and only if it is a projection} \\ &\text{onto a subspace of even dimension.} \end{aligned} \tag{2.1}$$

If $A \in \mathfrak{sl}(2n+1)$ is a projection, then the Lie superalgebra obtained from it by “method 2” of [7] is isomorphic to

$$\mathfrak{sl}(\dim \text{Ker } A \mid \dim \text{Im } A) \cong \mathfrak{sl}(\dim \text{Im } A \mid \dim \text{Ker } A).$$

So we see there are $n+1$ equivalence classes of $\mathbb{Z}/2$ -gradings of $\mathfrak{sl}(2n+1)$ and $n+1$ of its nonisomorphic superizations (including the trivial purely even one). We can enumerate them either as

$$\mathfrak{sl}(2n+1-2k \mid 2k) \cong \mathfrak{sl}(2k \mid 2n+1-2k), \quad \text{where } k = 0, \dots, n,$$

or, more simply, as $\mathfrak{sl}(k \mid 2n+1-k)$, where $k = 0, \dots, n$. So the answer is the same as for $p \neq 2$.

The $\mathfrak{sl}(2n)$ series ($n \geq 2$). The Lie algebra $\mathfrak{der } \mathfrak{sl}(2n)$ can be identified, see [23], with $\mathfrak{pgl}(2n)$ in the sense that for any $D \in \mathfrak{der } \mathfrak{sl}(2n)$, there is $A_D \in \mathfrak{gl}(2n)$ such that D coincides with the restriction of ad_{A_D} to $\mathfrak{sl}(2n)$.

These elements A_D are defined modulo center; in particular, one can take A_{D^2} to be $(A_D)^2$. Therefore, D satisfies the condition (1.7a) if and only if $(A_D)^2 = A_D + cI_{2n}$ for some $c \in \mathbb{K}$. Let $d \in \mathbb{K}$ be a root of the equation $d^2 = d + c$; set $A'_D = A_D + dI_{2n}$, then $(A'_D)^2 = A'_D$. So we see that an operator U on $\mathfrak{sl}(2n)$ satisfies the conditions (1.7a) if and only if it can be represented as a restriction of ad_A to $\mathfrak{sl}(2n)$ for some projection $A \in \mathfrak{gl}(2n)$, and then the Lie superalgebra obtained from U by “method 2” is isomorphic to

$$\mathfrak{sl}(\dim \text{Ker } A \mid \dim \text{Im } A) \cong \mathfrak{sl}(\dim \text{Im } A \mid \dim \text{Ker } A).$$

So there are $n+1$ nonisomorphic superizations of $\mathfrak{sl}(2n)$ (including the trivial purely even one): $\mathfrak{sl}(k \mid 2n-k)$, where $k = 0, \dots, n$. Again, the answer is the same as for $p \neq 2$.

The $\mathfrak{psl}(2n)$ series, $n > 2$. The algebra $\mathfrak{der } \mathfrak{psl}(2n)$ is isomorphic to $\mathfrak{der } \mathfrak{sl}(2n)$ when $n > 2$, see [23]. So the arguments from the previous subsection apply. There are $n+1$ non-isomorphic superizations of $\mathfrak{psl}(2n)$ (including the purely even one), which can be enumerated as $\mathfrak{psl}(k \mid 2n-k)$, where $k = 0, \dots, n$. ■

Remark 2.3. A $\mathbb{Z}/2$ -grading of $\mathfrak{gl}(2n+1)$ for $n > 2$ can produce a Lie superalgebra which is not isomorphic to any superalgebra of the form $\mathfrak{gl}(k \mid 2n+1-k)$. More specifically, such a superalgebra would be isomorphic to the direct sum of a Lie superalgebra of the form $\mathfrak{sl}(k \mid 2n+1-k)$, where $0 \leq k \leq n$, and 0|1-dimensional center (i.e., 1-dimensional odd center). Namely, represent $\mathfrak{gl}(2n+1)$ as $\mathfrak{sl}(2n+1) \oplus \mathfrak{c}$; since it is a direct sum, you can introduce gradings on the summands independently. On $\mathfrak{sl}(2n+1)$, introduce some grading which produces $\mathfrak{sl}(k \mid 2n+1-k)$, then declare the center odd. The resulting algebra is not isomorphic to $\mathfrak{gl}(k \mid 2n+1-k)$ for any k , since the center of $\mathfrak{gl}(k \mid 2n+1-k)$ is even. But since this grading does not result in any new *simple* Lie superalgebra, we do not consider gradings of \mathfrak{gl} here.

3 The $\mathfrak{o}^{(1)}(2n+1)$ series

Clearly, $\mathfrak{oo}_{B_1 B_2}(0 \mid n) = \mathfrak{o}_{B_2}(n)$ and $\mathfrak{oo}_{B_1 B_2}(n \mid 0) = \mathfrak{o}_{B_1}(n)$.

Example 3.1 ($\mathfrak{o}^{(1)}(3)$). Observe the occasional isomorphism $\mathfrak{o}^{(1)}(3) \simeq \mathfrak{vect}^{(1)}(1; \underline{2})$, so this case is considered in more details in Section 6.1. In [6], the deforms of the superization of $\mathfrak{o}^{(1)}(3)$ associated with one of the three $\mathbb{Z}/2$ -gradings of $\mathfrak{o}^{(1)}(3)$ are described; but until now it was unclear if these deforms are *true* ones, i.e., the deformed algebra is not isomorphic to the initial algebra, as is the case for *semitrivial* deformations corresponding to certain integrable cocycles from nontrivial cohomology class, for examples, see [8, 24]. The results of Section 6.1 prove that one of the deforms found in [6] is a true one.

Theorem 3.2. *For any $n \geq 1$, all $\mathbb{Z}/2$ -gradings of the Lie algebra $\mathfrak{o}^{(1)}(2n+1)$ correspond to Lie superalgebras $\mathfrak{oo}_{II}^{(1)}(2n+1-2k|2k)$, where $0 \leq k \leq n$ (or, which is the same but looks simpler, $\mathfrak{oo}_{II}^{(1)}(k|2n+1-k)$, where $0 \leq k \leq n$), and $\mathfrak{oo}_{III}^{(1)}(2n+1-2k|2k)$, where $1 \leq k \leq n$.*

Proof. Since any nondegenerate symmetric bilinear form over a space of dimension $2n+1$ is equivalent to I_{2n+1} , the algebra of derivations of $\mathfrak{o}^{(1)}(2n+1)$ is isomorphic to $\mathfrak{o}(2n+1)/\mathfrak{c}$, the quotient of $\mathfrak{o}(2n+1)$ modulo center, or the subalgebra of traceless elements of $\mathfrak{o}(2n+1)$, see [2, Statement 3.8.1a] and Appendix A.

Again, an element $A \in \mathfrak{der} \mathfrak{o}^{(1)}(2n+1)$ describes a $\mathbb{Z}/2$ -grading of $\mathfrak{o}^{(1)}(2n+1)$ if and only if $A^2 = A$, i.e., A is a projection.

By definition, an operator $A \in \mathfrak{gl}(V)$ belongs to $\mathfrak{o}_B(V)$, where B is a nondegenerate symmetric bilinear form, if and only if

$$B(Ax, y) + B(x, Ay) = 0 \quad \text{for all } x, y \in V. \quad (3.1)$$

In what follows, we assume that A is a projection. It is easy to check that (3.1) is automatically satisfied if $x, y \in \text{Im } A$ or if $x, y \in \text{Ker } A$. If $x \in \text{Im } A$ and $y \in \text{Ker } A$, then (3.1) is equivalent to $B(x, y) = 0$. So $A \in \mathfrak{o}_B(V)$ if and only if $\text{Im } A$ and $\text{Ker } A$ are orthogonal with respect to B . For A to be traceless, $\dim \text{Im } A$ must be even, see condition (2.1).

Let A be a projection belonging to $\mathfrak{der} \mathfrak{o}_B^{(1)}(2n+1)$ with $\dim \text{Im } A = 2k > 0$. Denote restrictions of B to $\text{Im } A$ and $\text{Ker } A$ by $B_{\text{Im } A}$ and $B_{\text{Ker } A}$, respectively.

Since B is nondegenerate, $\text{Im } A \oplus \text{Ker } A = V$ and $\text{Im } A \perp \text{Ker } A$ with respect to B , it follows that these restrictions are nondegenerate.

Since $\dim \text{Ker } A = 2n+1-2k$ is odd, $B_{\text{Ker } A}$ is equivalent to $I_{2n+1-2k}$. Since $\dim \text{Im } A = 2k$ is even, it follows that $B_{\text{Im } A}$ may be equivalent to either I_{2k} , or Π_{2k} . In the latter case, the resulting Lie superalgebra is isomorphic to $\mathfrak{oo}_{III}^{(1)}(2n+1-2k|2k)$; in the former case, it is isomorphic to $\mathfrak{oo}_{II}^{(1)}(2k|2n+1-2k)$. Note that the collection “ $\mathfrak{oo}_{II}^{(1)}(2k|2n+1-2k)$, where $0 \leq k \leq n$ ” can be described more simply as “ $\mathfrak{oo}_{II}^{(1)}(k|2n+1-k)$, where $0 \leq k \leq n$ ”.

So we get $2n+1$ nonisomorphic Lie superalgebras from $\mathfrak{o}^{(1)}(2n+1)$, including the purely even case. To see that all these cases are really realizable with some projection A , the following approach can be used. Recall that in an odd-dimensional space, all nondegenerate symmetric forms are equivalent, so for any such form B and any symmetric invertible matrix, there is a basis in which the matrix of B is equal to the given one. In particular, for a given k , there are bases in which the Gram matrix of B is either I_{2n+1} (call it *the first basis*) or $\text{diag}(I_{2n+1-2k}, \Pi_{2k})$ (call it *the second basis* for this value of k).

Take the operator A whose matrix in the *first* basis is $\text{diag}(0_{2n+1-2k}, I_{2k})$; clearly, $A^2 = A$ and $\dim \text{Im } A = 2k$. The space $\text{Im } A$, which is spanned by the last $2k$ vectors of the basis, is, clearly, orthogonal, relative the form B , to $\text{Ker } A$, which is spanned by the first $2n+1-2k$ vectors of the basis. So $A \in \mathfrak{der} \mathfrak{o}_B$, and hence determines a grading of $\mathfrak{o}_B^{(1)}$. It is easy to see that the Lie superalgebra obtained from $\mathfrak{o}_B^{(1)}$ by “method 2” of [7] is $\mathfrak{oo}_{II}^{(1)}(2n+1-2k|2k)$.

Analogously, an operator A with the same matrix $\text{diag}(0_{2n+1-2k}, I_{2k})$ in the *second* basis (it does not matter what is the matrix of A in the first basis) determines a grading that corresponds to the Lie superalgebra $\mathfrak{oo}_{III}^{(1)}(2n+1-2k|2k)$.

It is possible to show that there are $2n + 1$ equivalence classes of $\mathbb{Z}/2$ -gradings. It could have happened that there were more gradings than nonisomorphic superizations if two inequivalent gradings would have yielded isomorphic Lie superalgebras. This, however, does not happen; we skip the details. ■

Remark 3.3. Similarly to $\mathfrak{gl}(2n + 1)$, see Remark 2.3, it is clear that certain $\mathbb{Z}/2$ -gradings of $\mathfrak{o}(2n + 1)$ can produce Lie superalgebras not isomorphic to any superalgebra of the form $\mathfrak{o}\mathfrak{o}_{II}(2n + 1 - 2k|2k)$ or $\mathfrak{o}\mathfrak{o}_{III}(2n + 1 - 2k|2k)$. For example, certain $\mathbb{Z}/2$ -gradings can yield a direct sum of $\mathfrak{o}\mathfrak{o}_{II}^{(1)}(2n + 1 - 2k|2k)$ and 0|1-dimensional center. But again, such gradings do not produce any new *simple* Lie superalgebras, so, being actually interested in new simple Lie superalgebras, we do not consider such gradings of $\mathfrak{o}(2n + 1)$ in full generality in this paper.

4 The $\mathfrak{o}_I^{(1)}(2n)$ series

Theorem 4.1. *For $n > 2$, all $\mathbb{Z}/2$ -gradings of the Lie algebra $\mathfrak{o}_I^{(1)}(2n)$ correspond to Lie superalgebras $\mathfrak{o}\mathfrak{o}_{II}^{(1)}(m|2n - m)$, where $1 \leq m \leq n$, and $\mathfrak{o}\mathfrak{o}_{III}^{(1)}(2n - 2k|2k)$, where $0 \leq k \leq n - 1$.*

Proof. If a bilinear form B on vector space V of dimension $2n$ is equivalent to I_{2n} , then the algebra $\mathfrak{der}\mathfrak{o}_B^{(1)}(2n)$ can be identified, see [2, Statement 3.8.1a] and Appendix A, with $\mathfrak{o}_B(2n)/\mathfrak{c}$ in the sense that for any $D \in \mathfrak{der}\mathfrak{o}_B^{(1)}(2n)$, there is $A_D \in \mathfrak{o}_B(2n)$ such that D coincides with the restriction of ad_{A_D} to $\mathfrak{o}_B^{(1)}(2n)$. These elements A_D are defined up to a central element; in particular, one can take A_{D^2} to be $(A_D)^2$. By arguments similar to the ones we used in the case of $\mathfrak{sl}(2n)$, one can show that an operator U on $\mathfrak{o}_B^{(1)}(2n)$ satisfies the conditions (1.7a) if and only if it can be represented as a restriction of ad_A to $\mathfrak{o}_B^{(1)}(2n)$ for some projection $A \in \mathfrak{o}_B(2n)$.

By arguments we used in the previous section, a projection A belongs to $\mathfrak{o}_B(2n)$ if and only if $\text{Im } A$ and $\text{Ker } A$ are orthogonal with respect to B . We denote restrictions of B to $\text{Im } A$ and $\text{Ker } A$ by $B_{\text{Im } A}$ and $B_{\text{Ker } A}$, respectively. These restrictions have to be nondegenerate.

If $\dim \text{Im } A = 2k + 1$, where $0 \leq k \leq n - 1$, then these restrictions are equivalent to I_{2k+1} and $I_{2n-2k-1}$, respectively, and the resulting Lie superalgebra is isomorphic to

$$\mathfrak{o}_{II}^{(1)}(2k + 1|2n - 2k - 1) \simeq \mathfrak{o}_{II}^{(1)}(2n - 2k - 1|2k + 1).$$

If $\dim \text{Im } A = 2k$, where $1 \leq k \leq n - 1$, then $B_{\text{Im } A}$ can be equivalent to either I_{2k} , or Π_{2k} , while $B_{\text{Ker } A}$ can be equivalent to either I_{2n-2k} , or Π_{2n-2k} . However, it is impossible for $B_{\text{Im } A}$ to be equivalent to Π_{2k} while $B_{\text{Ker } A}$ is equivalent to Π_{2n-2k} at the same time, because the direct sum of these two forms is equivalent to Π_{2n} . All the other combinations are possible, and, depending on them, the resulting Lie superalgebra can be isomorphic to either $\mathfrak{o}_{II}^{(1)}(2k|2n - 2k)$, or $\mathfrak{o}_{III}^{(1)}(2k|2n - 2k)$, or $\mathfrak{o}_{III}^{(1)}(2k|2n - 2k) \simeq \mathfrak{o}_{III}^{(1)}(2n - 2k|2k)$.

If $\dim \text{Im } A = 0$ or $2n$, then the resulting Lie superalgebra is purely even. So, as described above, $\mathfrak{o}_B^{(1)}(2n)$ has $2n + 1$ nonisomorphic superizations. ■

Remark 4.2. The algebras $\mathfrak{o}_I^{(1)}(2)$ and $\mathfrak{o}_I^{(1)}(4)$ are not simple, so we do not consider them here.

5 The simple relatives of $\mathfrak{o}_{II}(2n)$ series

The algebras $\mathfrak{o}_{II}(2)$ and $\mathfrak{o}_{II}(4)$ do not have simple relatives, so we do not consider them. We have been unable to classify $\mathbb{Z}/2$ -gradings of the simple relative of $\mathfrak{o}_{II}(8)$ so far.

Convention. We will denote the simple relative of $\mathfrak{o}_{\Pi}(2n)$ by $\mathfrak{o}_{\Pi}^{(2)}(2n)/\mathfrak{c}$ for both even and odd values of n , keeping in mind that the center might be trivial. Similarly, we will denote the simple relatives of $\mathfrak{so}_{\text{III}}(2k|2n-2k)$ and $\mathfrak{pe}^{(2)}(n)$ by $\mathfrak{so}_{\text{III}}^{(2)}(2k|2n-2k)/\mathfrak{c}$ and $\mathfrak{pe}^{(2)}(n)/\mathfrak{c}$, respectively, for both even and odd values of n .

Theorem 5.1. *For $n = 3$ or $n \geq 5$, all $\mathbb{Z}/2$ -gradings of the simple relative of $\mathfrak{o}_{\Pi}(2n)$ (that is, of $\mathfrak{o}_{\Pi}^{(2)}(2n)$, if n is odd, or of $\mathfrak{o}_{\Pi}^{(2)}(2n)/\mathfrak{c}$, if n is even) correspond to the simple relatives of the corresponding superizations, i.e., $\mathfrak{so}_{\text{III}}^{(2)}(2k|2n-2k)$, where $0 \leq k \leq \lfloor \frac{n}{2} \rfloor$, and $\mathfrak{pe}^{(2)}(n)$, if n is odd, or $\mathfrak{so}_{\text{III}}^{(2)}(2k|2n-2k)/\mathfrak{c}$, where $0 \leq k \leq \lfloor \frac{n}{2} \rfloor$, and $\mathfrak{pe}^{(2)}(n)/\mathfrak{c}$, if n is even.*

Proof. If n is odd, then the center of $\mathfrak{o}_{\Pi}^{(2)}(2n)$ is trivial, so in this case $\mathfrak{o}_{\Pi}^{(2)}(2n)/\mathfrak{c} \simeq \mathfrak{o}_{\Pi}^{(2)}(2n)$.

For a symmetric bilinear form B on space V , consider the Lie algebra

$$\begin{aligned} \tilde{\mathfrak{o}}_B(V) := \{M \in \mathfrak{gl}(V) \mid \text{there is } c_M \in \mathbb{K} \text{ such that} \\ B(Mx, y) + B(x, My) = c_M B(x, y) \text{ for all } x, y \in V\}. \end{aligned} \quad (5.1)$$

As is not difficult to see, for $B \sim \Pi_{2n}$ we have

$$\tilde{\mathfrak{o}}_{\Pi_{2n}}(V) = \mathfrak{o}_{\Pi_{2n}}(V) \rtimes \mathbb{K}d_n, \quad \text{where } d_n = \text{diag}(0_n, 1_n) \text{ or } \text{diag}(1_n, 0_n).$$

Then, according to [2, 23]

$$\mathfrak{der}(\mathfrak{o}_{\Pi_{2n}}^{(2)}(V)/\mathfrak{c}) \simeq \tilde{\mathfrak{o}}_{\Pi_{2n}}(V)/\mathfrak{c}.$$

(To compare with our previous results, observe that if $B \sim I_{2n}$, then $\tilde{\mathfrak{o}}_{I_{2n}}(V) = \mathfrak{o}_{I_{2n}}(V)$.)

As before, a given operator $U \in \mathfrak{der}(\mathfrak{o}_B^{(2)}(V)/\mathfrak{c}) \simeq \tilde{\mathfrak{o}}_B(V)/\mathfrak{c}$ satisfies the condition $U^2 = U$ if and only if the corresponding element (equivalence class) of $\tilde{\mathfrak{o}}_B(V)$ contains a projection A . Let us consider the values c_A , see (5.1), can take.

$c_A = \bar{0}$: In this case, the definition (5.1) is equivalent to the statement that $\text{Im } A$ and $\text{Ker } A$ are orthogonal with respect to B . It means that the restrictions of B to $\text{Im } A$ and $\text{Ker } A$ have to be nondegenerate. Since B is anti-symmetric (i.e., $B(x, x) = 0$ for any $x \in V$), these restrictions are anti-symmetric as well, which means that dimensions of $\text{Im } A$ and $\text{Ker } A$ are even. The resulting Lie superalgebra in this case is isomorphic to

$$\mathfrak{so}_{\text{III}}^{(2)}(\dim \text{Im } A \mid \dim \text{Ker } A)/\mathfrak{c} \simeq \mathfrak{so}_{\text{III}}^{(2)}(\dim \text{Ker } A \mid \dim \text{Im } A)/\mathfrak{c}.$$

$c_A = \bar{1}$: In this case, the condition (5.1) is equivalent to the statement that both $\text{Im } A$ and $\text{Ker } A$ are isotropic with respect to B . Since $\text{Im } A \oplus \text{Ker } A = V$, this means that

$$\dim \text{Im } A = \dim \text{Ker } A = n$$

and there is an invertible linear map $f: \text{Ker } A \rightarrow (\text{Im } A)^*$ such that

$$B(x, y) = (f(y))(x) \quad \text{for all } x \in \text{Im } A, y \in \text{Ker } A.$$

The resulting Lie superalgebra in this case is isomorphic to $\mathfrak{pe}^{(2)}(n)/\mathfrak{c}$.

$c_A \neq \bar{0}, \bar{1}$: This is impossible, because in this case, (5.1) would mean that $\text{Im } A$ and $\text{Ker } A$ are both isotropic and orthogonal to each other with respect to B , i.e., $B(x, y) = 0$ for all $x, y \in V$.

So we get $\lfloor \frac{n}{2} \rfloor + 2$ nonisomorphic superizations of $\mathfrak{o}_{\Pi}^{(2)}(2n)/\mathfrak{c}$ (including the purely even one), which are $\mathfrak{so}_{\text{III}}^{(2)}(2k|2n-2k)/\mathfrak{c}$, where $0 \leq k \leq \lfloor \frac{n}{2} \rfloor$, and $\mathfrak{pe}^{(2)}(n)/\mathfrak{c}$. ■

Remark 5.2. The algebra $\mathfrak{o}_{\Pi}^{(2)}(6)$ is isomorphic to $\mathfrak{psl}(4)$, $\mathfrak{h}_{\Pi}^{(1)}(4; \mathbb{1})$ and $\mathfrak{svect}^{(1)}(3; \mathbb{1})$, see [10]. The fact that it has exactly three superizations implies two facts: 1) the following superizations of these algebras are isomorphic, and 2) these algebras have no other non-trivial superizations non-isomorphic to these ones:

$$\begin{aligned} \mathfrak{oo}_{\Pi\Pi}^{(2)}(2|4) &\simeq \mathfrak{svect}^{(1)}(0|3) \simeq \mathfrak{psl}(3|1) \simeq \mathfrak{svect}^{(1)}(2; \mathbb{1}|1), & \text{here } \text{sdim} = 8|6, \\ \mathfrak{pe}^{(2)}(3) &\simeq \mathfrak{h}_{\Pi}^{(1)}(0|4) \simeq \mathfrak{psl}(2|2) \simeq \mathfrak{h}_{\Pi\Pi}^{(1)}(2; \mathbb{1}|2) \simeq \mathfrak{svect}^{(1)}(1; \mathbb{1}|2), & \text{here } \text{sdim} = 6|8. \end{aligned}$$

6 The $\mathfrak{vect}^{(1)}(1; \underline{n})$ series

We describe the $\mathbb{Z}/2$ -gradings of $\mathfrak{vect}^{(1)}(1; \underline{n-1})$ in Theorem 6.2. First, we need some definitions.

Let \mathfrak{v}_n be the minimal Lie subalgebra of the restricted closure of $\mathfrak{vect}^{(1)}(1; \underline{n-1})$ that contains $\mathfrak{vect}^{(1)}(1; \underline{n-1})$ and all the elements $\mathcal{X}^{[2]}$, where $\mathcal{X} \in \mathfrak{vect}^{(1)}(1; \underline{n-1})$. As a vector space, \mathfrak{v}_n can be written as a direct sum

$$\mathfrak{v}_n = \mathfrak{vect}(1; \underline{n-1}) \oplus \mathbb{K}\partial^2. \quad (6.1)$$

Thus, $\dim \mathfrak{v}_n = 2^{n-1} + 1$. Observe that $\mathfrak{v}_n = (\mathfrak{vect}^{(1)}(1; \underline{n-1}))^{(1)}$, see equation (1.5), associated with the $\mathbb{Z}/2$ -grading induced by the standard \mathbb{Z} -grading of $\mathfrak{vect}^{(1)}(1; \underline{n-1})$.

For $n > 2$, consider the Lie superalgebra $\mathfrak{q}(\mathfrak{vect}(1; \underline{n-1}))$. As a vector space, it can be written as a direct sum $\mathfrak{v}_n \oplus \Pi(\mathfrak{vect}(1; \underline{n-1}))$, where Π is the change of parity functor. Consider the Lie algebra $\mathfrak{vect}(1; \underline{n})$ in an indeterminate z in order to distinguish it from the indeterminate x in equation (6.3). Let

$$X_{-2} = \partial^2, \quad X_{-1} = \partial, \quad X_0 = z\partial, \quad \dots, \quad X_{2^{n-1}-2} = z^{2^{n-1}-1}\partial,$$

be the basis in the even part \mathfrak{v}_n of $\mathfrak{q}(\mathfrak{vect}(1; \underline{n-1}))$ and

$$Y_{-1} = \Pi\partial, \quad Y_0 = \Pi(z\partial), \quad \dots, \quad Y_{2^{n-1}-2} = \Pi(z^{2^{n-1}-1}\partial),$$

be the basis in the odd part of $\mathfrak{q}(\mathfrak{vect}(1; \underline{n-1}))$. The Lie superalgebra structure in $\mathfrak{q}(\mathfrak{vect}(1; \underline{n-1}))$ is given by following formulas

$$\begin{aligned} [X_{-2}, X_k] &= [\partial^2, z^{(k-1)}\partial] = X_{k-2} & \text{for } k = 1, \dots, 2^{n-1} - 2, \\ [X_{-2}, Y_k] &= \Pi[\partial^2, z^{(k-1)}\partial] = Y_{k-2} & \text{for } k = 1, \dots, 2^{n-1} - 2, \\ [X_{-2}, X_{-1}] &= [X_{-2}, X_0] = [X_{-2}, Y_{-1}] = [X_{-2}, Y_0] = [X_{-1}, Y_{-1}] = 0, \\ [X_k, X_m] &= [z^{(k-1)}\partial, z^{(m-1)}\partial] = \binom{k+m+2}{k+1} X_{k+m} \\ & \text{for } k, m = -1, \dots, 2^{n-1} - 2, \text{ except for } m = k = -1, \\ [X_k, Y_m] &= \Pi[z^{(k-1)}\partial, z^{(s-1)}\partial] = \binom{k+m+2}{k+1} Y_{k+m} \\ & \text{for } k, m = -1, \dots, 2^{n-1} - 2, \text{ except for } m = k = -1, \\ [Y_k, Y_m] &= [z^{(k-1)}\partial, z^{(m-1)}\partial] = \binom{k+m+2}{k+1} X_{k+m} \\ & \text{for } k, m = -1, \dots, 2^{n-1} - 2, \text{ except for } m = k = -1, \\ (Y_{-1})^2 &= X_{-2}, \\ (Y_k)^2 &= (z^{(k+1)}\partial)^{[2]} = \binom{2k+1}{k} X_{2k} & \text{for } k = 0, \dots, 2^{n-1} - 2. \end{aligned}$$

On the superspace of $\mathfrak{q}(\mathbf{vect}(1; \underline{n-1}))$, define another Lie superalgebra structure, call it $\widetilde{\mathfrak{qv}}_{n-1}$, by the following formulas:

$$\begin{aligned}
[X_{-2}, X_{-1}] &:= 0, & [X_{-2}, X_0] &:= 0, \\
[X_{-2}, X_m] &:= X_{m-2} & \text{for } m = 0, \dots, 2^{n-1} - 2, \\
[X_k, X_m] &:= \binom{k+m+2}{k+1} X_{k+m} & \text{for } m, k = -1, \dots, 2^{n-1} - 2, \text{ except for } m = k = -1, \\
[Y_k, Y_m] &:= \binom{k+m+2}{k+1} X_{k+m} & \text{for } m, k = -1, \dots, 2^{n-1} - 2, \text{ except for } m = k = -1, \\
[X_{-1}, Y_{-1}] &:= Y_{-1}, & [X_{-2}, Y_{-1}] &= Y_{-1}, & [X_{-2}, Y_0] &= Y_0, \\
[X_{-2}, Y_m] &= Y_m + Y_{m-2}, & m = 1, \dots, 2^{n-1} - 2 \\
[X_k, Y_m] &:= \binom{k+m+2}{k+1} Y_{k+m} + \binom{k+m+2}{k+1} Y_{k+m+1} \\
& \text{for } k, m = -1, \dots, 2^{n-1} - 2, \text{ except for } m = k = -1, \\
(Y_{-1})^2 &:= X_{-2} + X_0, & (Y_k)^2 &:= \binom{2k+1}{k} X_{2k} & \text{for } k = 0, \dots, 2^{n-1} - 2.
\end{aligned}$$

I. Shchepochkina observed that the Lie superalgebra $\widetilde{\mathfrak{qv}}_{n-1}$ is a filtered deform of the Lie superalgebra $\mathfrak{q}(\mathbf{vect}(1; \underline{n-1}))$.

Lemma 6.1. *Lie superalgebras $\widetilde{\mathfrak{qv}}_{n-1}$ and $\mathfrak{q}(\mathbf{vect}(1; \underline{n-1}))$ are not isomorphic.*

Proof. Let us prove that $\widetilde{\mathfrak{qv}}_{n-1}$ is not isomorphic to any Lie superalgebra of the form $\mathfrak{q}(\mathfrak{g})$, where \mathfrak{g} is a Lie algebra. Any superalgebra of the form $\mathfrak{q}(\mathfrak{g})$ possesses the following property: if $x \in \mathfrak{q}(\mathfrak{g})_{\bar{0}}$ acts nilpotently on $\mathfrak{q}(\mathfrak{g})_{\bar{0}}$, then it acts nilpotently on $\mathfrak{q}(\mathfrak{g})_{\bar{1}}$ as well. Indeed, if $(\text{ad}_x)^k|_{\mathfrak{q}(\mathfrak{g})_{\bar{0}}} = 0$ for some positive integer k , then $(\text{ad}_x)^k \Pi y = \Pi((\text{ad}_x)^k y) = 0$ for any $y \in \mathfrak{g}$.

On the other hand, from the relations above one can see that X_{-1} acts nilpotently on $(\widetilde{\mathfrak{qv}}_{n-1})_{\bar{0}}$ (more specifically, $(\text{ad}_{X_{-1}})^{2^{n-1}+1}|_{(\widetilde{\mathfrak{qv}}_{n-1})_{\bar{0}}} = 0$), but $[X_{-1}, Y_{-1}] = Y_{-1}$, so the action of X_{-1} on $(\widetilde{\mathfrak{qv}}_{n-1})_{\bar{1}}$ is not nilpotent. \blacksquare

Consider the Lie algebra $\mathbf{vect}(1; \underline{n})$ in an indeterminate x . For a basis of $\mathbf{vect}(1; \underline{n})$ we take $e_i := x^{(i+1)}\partial$ for $i = -1, 0, \dots, 2^n - 2$.

Theorem 6.2. *All $\mathbb{Z}/2$ -gradings of the Lie algebra $\mathbf{vect}^{(1)}(1; \underline{n})$ correspond to the one of the following Lie superalgebras:*

- 1) purely even $\mathbf{vect}^{(1)}(1; \underline{n}|0)$;
- 2) $\mathfrak{k}(1; \underline{n-1}|1)$, described in [3], and its $(n-2)$ -parametric family of filtered deforms described below in the proof;
- 3) the Lie superalgebra $\widetilde{\mathfrak{qv}}_{n-1}$ for $n > 2$.

Proof. Let $u \in \mathcal{O}(1; \underline{n})$ be a linear combination of only even powers of the indeterminate x , and let a be its constant term². In other words, let $u, a \in \mathcal{O}(1; \underline{n})$ be such that

$$x \cdot (\partial u) = 0, \quad \partial a = 0, \quad u^2 = a^2. \quad (6.2)$$

²The notation $u(0)$ we use for brevity in what follows is meaningless, strictly speaking, because the divided power polynomials can not be evaluated at any $x \in \mathbb{K}$ for $p > 0$; by writing like this we mean $a \in \mathbb{K} \cdot 1$ which is the value of u modulo the maximal ideal of $\mathcal{O}(1; \underline{n})$; this is a standard abuse of notation.

Consider any derivation $D_u \in \mathfrak{der} \mathcal{O}(1; \underline{n})$ of the form

$$D_u = \left(u + x + xu \sum_{1 \leq i \leq n-1} a^{2^i-2} (\partial^{2^i} u) \right) \partial + \sum_{1 \leq i \leq n-1} a^{2^i} \partial^{2^i}.$$

Properties (6.2) imply (after rather lengthy calculations we omit) that $(D_u)^2 = D_u$, so D_u describes a $\mathbb{Z}/2$ -grading of $\mathcal{O}(1; \underline{n})$.

Consider the linear map ad_{D_u} on the Lie algebra $\mathfrak{der} \mathcal{O}(1; \underline{n})$ given by $D \mapsto [D_u, D]$. Due to the Jacobi identity, we see that $\text{ad}_{D_u} \in \mathfrak{der}(\mathfrak{der} \mathcal{O}(1; \underline{n}))$, where the outer \mathfrak{der} is for derivations of the Lie algebra $\mathfrak{der} \mathcal{O}(1; \underline{n})$. Since the Lie algebra $\mathfrak{der} \mathcal{O}(1; \underline{n})$ has a 2-structure given by $D^{[2]} = D^2$, we have $(\text{ad}_{D_u})^2 = \text{ad}_{D_u}$. Thus, ad_{D_u} describes a $\mathbb{Z}/2$ -grading of $\mathfrak{der} \mathcal{O}(1; \underline{n})$.

The linear map ad_{D_u} sends elements of $\mathfrak{vect}(1; \underline{n})$ to $\mathfrak{vect}^{(1)}(1; \underline{n})$ because D_u is a linear combination of a vector field and elements of the form ∂^{2^i} , and

$$[\partial^{2^i}, f\partial] = (\partial^{2^i} f)\partial = [\partial, (\partial^{2^i-1} f)\partial] \in \mathfrak{vect}^{(1)}(1; \underline{n}) \quad \text{for any } f \in \mathcal{O}(1; \underline{n}).$$

This means that the restriction $(\text{ad}_{D_u})|_{\mathfrak{vect}(1; \underline{n})}$ describes a $\mathbb{Z}/2$ -grading of $\mathfrak{vect}(1; \underline{n})$ and the restriction $(\text{ad}_{D_u})|_{\mathfrak{vect}^{(1)}(1; \underline{n})}$ describes a $\mathbb{Z}/2$ -grading of $\mathfrak{vect}^{(1)}(1; \underline{n})$. In what follows, we will denote the latter restriction by D_u as well. Different polynomials u correspond to different gradings, as $[D_u, x\partial] = u\partial$. We need, however, not individual gradings, but their equivalence classes. We were unable to solve this problem completely so far.

In notation of [29], any torus of the restricted closure of $\mathfrak{vect}(1; \underline{n})$ lying in the maximal subalgebra of elements of non-negative degree (assuming $\deg x = 1$) is called an *inner* one, the other tori are called *outer* ones.

If $u(0) = a \neq 0$, the derivation D_u is an outer toroidal derivation of $\mathcal{O}(1; \underline{n})$ (i.e., it spans an outer torus of 2-closure of $\mathfrak{vect}(1; \underline{n})$). The automorphism group of $\mathfrak{vect}^{(1)}(1; \underline{n})$ acts transitively on the set of outer toroidal derivations, see [29].³ Hence, any derivation D_u with $a \neq 0$ is conjugate by an automorphism of $\mathfrak{vect}^{(1)}(1; \underline{n})$ to the derivation

$$D_1 = (1+x)\partial + \sum_{1 \leq i \leq n-1} \partial^{2^i}.$$

Recall that $(u+v)^{(k)} = \sum_{0 \leq i \leq k} u^{(k-i)}v^{(i)}$ and for $k = -2, \dots, 2^{n-1}-2$, define $e_k \in (\mathfrak{vect}^{(1)}(1; \underline{n}); D_1)^{(1)}$

by setting

$$\begin{aligned} e_{-2} &= \partial^2 + (1+x)\partial, \\ e_k &= \partial((x+x^{(2)})^{(k+2)})\partial = (1+x)(x+x^{(2)})^{(k+1)}\partial \quad \text{for } k > -2, \end{aligned} \tag{6.3}$$

and for $k = -1, \dots, 2^{n-1}-2$, define o_k by formulas

$$o_k = (x+x^{(2)})^{(k+1)}\partial, \quad \text{where } k = -1, \dots, 2^{n-1}-2. \tag{6.4}$$

³In [29], Tyurin proved that, for any two outer toroidal derivations O_1 and O_2 of $\mathfrak{vect}(1; \underline{n})$, there exists an $A \in \text{Aut}(\mathfrak{vect}(1; \underline{n}))$ such that $O_2 = A^{-1}O_1A$. Instead, we need “for any two outer toroidal derivations O_1 and O_2 of $\mathfrak{vect}^{(1)}(1; \underline{n})$, there exists an $A \in \text{Aut}(\mathfrak{vect}^{(1)}(1; \underline{n}))$ such that $O_2 = A^{-1}O_1A$ ”. This is so because “our” $D_u = (D_u^T)|_{\mathfrak{vect}^{(1)}} \in \mathfrak{der} \mathfrak{vect}^{(1)}(1; \underline{n})$ is the restriction of the corresponding “Tyurin’s” $D_u^T \in \mathfrak{der} \mathfrak{vect}(1; \underline{n})$ to $\mathfrak{der} \mathfrak{vect}^{(1)}(1; \underline{n})$.

If D_u and D_v are outer toroidal derivations of $\mathfrak{vect}^{(1)}(1; \underline{n})$, then D_u^T and D_v^T are outer toroidal derivations of $\mathfrak{vect}(1; \underline{n})$, and therefore there exists an $A \in \text{Aut}(\mathfrak{vect}(1; \underline{n}))$ such that $D_v^T = A^{-1}D_u^T A$. Any automorphism of $\mathfrak{vect}(1; \underline{n})$ preserves $\mathfrak{vect}^{(1)}(1; \underline{n})$, and hence $D_v = (A)^{-1}D_u A$, where $A := A|_{\mathfrak{vect}^{(1)}(1; \underline{n})}$ is an automorphism of $\mathfrak{vect}^{(1)}(1; \underline{n})$.

Direct computations show that $D_1(e_k) = 0$ and $D_1(o_m) = o_m$. Let $e_{-2}, \dots, e_{2^{n-1}-2}$ and $\Pi o_{-1}, \dots, \Pi o_{2^{n-2}}$ form a basis in the Lie superalgebra corresponding to the $\mathbb{Z}/2$ -grading defined by D_1 . The formulas

$$\begin{aligned} e_k &\mapsto X_k, & \text{where } k &= -2, \dots, 2^{n-1} - 2, \\ o_m &\mapsto Y_m, & \text{where } m &= -1, \dots, 2^{n-1} - 2, \end{aligned}$$

establish an isomorphism between this Lie superalgebra, spanned by the e_i and o_j , and $\widetilde{\mathfrak{q}\mathfrak{v}}_{n-1}$.

If $u(0) = a = 0$, the derivation D_u spans an inner torus. Hence, see [29], the derivation D_u is conjugate to the derivation D_f , where $f = \sum_{1 \leq i \leq n-1} c_i x^{(2^i)}$ and the summands $c_i x^{(2^i)}$ are the

corresponding terms of u . This gives us an $(n-1)$ -parametric family of $\mathbb{Z}/2$ -gradings. Let the automorphism σ_ε of $\mathcal{O}(1; \underline{n})$ be given on its generators by the formulas

$$\sigma_\varepsilon(x) = \varepsilon x, \quad \sigma_\varepsilon(x^{(2)}) = \varepsilon^2 x^{(2)}, \quad \dots, \quad \sigma_\varepsilon(x^{(2^{n-1})}) = \varepsilon^{2^{n-1}} x^{(2^{n-1})},$$

where $\varepsilon \in \mathbb{K}^\times$. Then

$$\sigma_\varepsilon \left(\left(\sum_{1 \leq i \leq n-1} c_i x^{(2^i)} \right) \partial \right) = \left(\sum_{1 \leq i \leq n-1} c_i \varepsilon^{2^i - 1} x^{(2^i)} \right) \partial.$$

Hence, the conjugacy class of the derivation D_u is defined by a tuple of parameters $(c_1, c_2, \dots, c_{n-1})$ up to an equivalence of the form

$$(c_1, c_2, \dots, c_{n-1}) \sim (\varepsilon c_1, \varepsilon^3 c_2, \dots, \varepsilon^{2^{n-1}-1} c_{n-1}). \quad (6.5)$$

Therefore, the number of parameters of $\mathbb{Z}/2$ -gradings reduces to $n-2$. In particular, for $n=2$, we do not, indeed, have parametric families of $\mathbb{Z}/2$ -gradings, see Section 6.1.

Observe that $x \cdot \partial u = 0$, so

$$0 = \partial(x\partial u) = \partial u + x\partial^2 u, \quad \text{which implies } x\partial^2 u = \partial u.$$

Then

$$D_u = (u + x + xu\partial^2 u)\partial = (u + x + u\partial u)\partial.$$

Desuperization of any superization of $\mathbf{vect}^{(1)}(1; \underline{n})$ can be considered as a Lie subalgebra in $\mathbf{v}_{n+1} := (\mathbf{vect}^{(1)}(1; \underline{n}))^{(1)}$, see (6.1). The operator ad_{D_u} preserves \mathbf{v}_{n+1} , so the grading it defines on $\mathbf{vect}^{(1)}(1; \underline{n})$ can be extended to \mathbf{v}_{n+1} with the same definition: $D \mapsto [D_u, D]$. This extended operator describes a $\mathbb{Z}/2$ -grading of \mathbf{v}_{n+1} . The elements of \mathbf{v}_{n+1} are said to be u -even or u -odd if they are even or odd, respectively, in this grading.

In particular, for the grading on \mathbf{v}_{n+1} given by the function $u = 0$, we have $D_0 = x\partial$, and the resulting superization is isomorphic to $\mathfrak{k}(1; \underline{n-1}|1)$, see [7, Section 7].

Consider the linear maps $T_u, A_u: \mathbf{v}_{n+1} \rightarrow \mathbf{v}_{n+1}$ defined as follows (their action on other elements being extended by linearity):

$$\begin{aligned} T_u(f\partial) &= (f + u(1 + \partial u)\partial f)(1 + \partial u + u\partial^2 u)\partial & \text{for any } f \in \mathcal{O}(1; \underline{n}), \\ T_u\partial^2 &= (T_u\partial)^2 = \partial^2 + (\partial^2 u + u\partial^3 u + u(\partial^2 u)^2 + u\partial u(\partial^2 u)^2)\partial, \\ A_u(f\partial) &= (f + u\partial u\partial f)\partial & \text{for any } f \in \mathcal{O}(1; \underline{n}), \quad A_u\partial^2 = \partial^2. \end{aligned}$$

For any $X \in \mathbf{v}_{n+1}$, one can check that $T_u X$ is u -even (resp. u -odd) if and only if X is 0-even (resp. 0-odd). We omit the calculations that show it, but the idea is as follows: ∂ is 0-odd,

while $(1 + \partial u + u\partial^2 u)\partial$ is u -odd. Besides, if we extend the concept of u -evenness/ u -oddness to $\mathcal{O}(1; \underline{n})$, then $f + u(1 + \partial u)\partial f$ is u -even (resp. u -odd) for any $f \in \mathcal{O}(1; \underline{n})$ if and only if f is 0-even (resp. 0-odd).

Also, the following is true for any $X, Y \in \mathbf{vect}(1; \underline{n})$:

$$\begin{aligned} [T_u X, T_u Y] &= T_u A_u [X, Y], & (T_u X)^2 &= T_u A_u X^2 & \text{for any 0-odd } X, \\ [T_u \partial^2, T_u X] &= T_u ((1 + u\partial^2 u) \cdot [\partial^2, X]). \end{aligned}$$

Note also that the operator T_u is invertible, so its image is the whole \mathfrak{v}_{n+1} . The invertibility of T_u follows from the fact that the matrix of T_u is upper triangular with 1's on the main diagonal in the basis $\partial^2, \partial, x\partial, \dots, x^{(2^n-1)}\partial$.

This means that the superization given by any function u such that $u(0) = 0$ can be considered as a deform of the superization given by $u = 0$ with the deformation parametrized by the polynomial u or, which is the same, the coefficients of u as follows:

$$\begin{aligned} [X, Y]_u &= \begin{cases} A_u [X, Y] & \text{if } X, Y \in \mathbf{vect}(1; \underline{n}), \\ (1 + u\partial^2 u) \cdot [X, Y] & \text{if } X = \partial^2 \text{ and } Y \in \mathbf{vect}(1; \underline{n}), \\ \text{defined by linearity and anti-symmetry} & \text{in other cases,} \end{cases} \\ (X^2)_u &= A_u X^2 \quad \text{for 0-odd } X. \end{aligned} \tag{6.6}$$

This deformation is filtered relative the decreasing filtration in which $\mathcal{L}_{-2} = \mathfrak{s}(\mathfrak{v}_{n+1})$, see (1.6), while \mathcal{L}_{k-1} for $k \geq -1$ consists of vector fields of the form $f\partial$, where $f \in \mathcal{O}(1; \underline{n})$ does not contain term of degree $< k$. Such superizations are listed in heading 2) of Theorem 6.2.

Finally, observe that these formulas do not capture the trivial $\mathbb{Z}/2$ -grading given by the derivation $U = 0$; the even part \mathfrak{g}_0 of this grading is the whole Lie algebra $\mathbf{vect}^{(1)}(1; \underline{n})$. Since any torus in $\mathbf{der}(\mathbf{vect}^{(1)}(1; \underline{n}))$ is of the form D_u , see [21, 29] and footnote 3 on p. 13, we completely described all $\mathbb{Z}/2$ -gradings of $\mathbf{vect}^{(1)}(1; \underline{n})$ and the corresponding superizations. ■

Remark 6.3. Observe an unpredicted fact: according to equations (6.6), if $X, Y \in \mathbf{vect}(1; \underline{n})$, then $[X, Y]_u$ can be expressed in terms of $[X, Y]$ and u .

In particular, concerning the 0-even part of $\mathbf{vect}(1; \underline{n})$, this implies the following fact:

Corollary 6.4. *If $u(0) = 0$, then the even part of the superization corresponding to D_u is a solvable Lie algebra.*⁴

For $n = 2$, any outer torus is conjugate to an inner one, see (6.10). This is not so for $n > 2$.

Lemma 6.5. *Let $n > 2$, consider the superization $\widetilde{\mathfrak{q}}\mathfrak{v}_{n-1} = \mathfrak{g}_0 \oplus \mathfrak{g}_1$ corresponding to the outer torus D_1 . Its even part $\mathfrak{g}_0 \simeq \mathfrak{v}_n$ is spanned by the elements (6.3), and \mathfrak{g}_1 is spanned by the elements (6.4). The odd part \mathfrak{g}_1 is a reducible \mathfrak{g}_0 -module with no lowest weight vector and with the two highest weight vectors $\Pi_{\mathcal{O}_{2^n-1-3}}$ and $\Pi_{\mathcal{O}_{2^n-1-2}}$ with respect to the standard \mathbb{Z} -grading of \mathfrak{g}_0 , namely $(\mathfrak{g}_0)_k = \mathbb{K}e_k$ for $k = -2, \dots, 2^{n-1} - 2$.*

Proof. Using (6.3) and (6.4), for positive generators e_{2^k-1} , where $k = 1, \dots, n-2$, of \mathfrak{g}_0 we have

$$\begin{aligned} [e_{2^k-1}, \Pi_{\mathcal{O}_{2^n-1-2}}] &= \Pi[(\partial w)w^{(2^k)}\partial, w^{(2^{n-1}-1)}\partial] \\ &= \Pi(w^{(2^k)}w^{(2^{n-1}-2)} + w^{(2^k)}w^{(2^{n-1}-1)} + w^{(2^k-1)}w^{(2^{n-1}-1)})\partial, \end{aligned}$$

⁴For more examples of simple Lie superalgebras whose even parts are solvable, see [6]. This is a phenomenon indigenous to $p = 2$.

where $w = (x + x^{(2)})$. Note that

$$\begin{aligned} 2^{n-1} - 1 &= 1 \cdot 2^{n-2} + 1 \cdot 2^{n-3} + \dots + 1 \cdot 2 + 1, \\ 2^{n-1} - 2 &= 1 \cdot 2^{n-2} + 1 \cdot 2^{n-3} + \dots + 1 \cdot 2 + 0. \end{aligned}$$

Then by Lucas theorem for $k < n - 1$, we have the following equalities, where the marked factor occupies $(k+1)$ st position from the right in the first two lines, while it stands in the k th position from the right in the third line, where the mark is under the place at which the 1s in the bottom of the binomial coefficients start to appear

$$\begin{aligned} \binom{2^{n-1} - 2 + 2^k}{2^k} \bmod 2 &= \binom{1}{0} \binom{0}{0} \cdots \binom{0}{0} \underbrace{\binom{0}{1}} \binom{1}{0} \cdots \binom{1}{0} \binom{0}{0} = 0, \\ \binom{2^{n-1} - 1 + 2^k}{2^k} \bmod 2 &= \binom{1}{0} \binom{0}{0} \cdots \binom{0}{0} \underbrace{\binom{0}{1}} \binom{1}{0} \cdots \binom{1}{0} \binom{1}{0} = 0, \\ \binom{2^{n-1} - 1 + 2^k - 1}{2^k - 1} \bmod 2 &= \binom{1}{0} \binom{0}{0} \cdots \binom{0}{0} \underbrace{\binom{1}{1}} \cdots \binom{1}{1} \binom{0}{1} = 0. \end{aligned}$$

Thus, we have $w^{(2^k)}w^{(2^{n-1}-2)} = 0$, $w^{(2^k)}w^{(2^{n-1}-1)} = 0$, and $w^{(2^k-1)}w^{(2^{n-1}-1)} = 0$. Finally, we see that $[e_{2^k-1}, \Pi o_{2^{n-1}-2}] = 0$ for $k = 1, \dots, n-2$. Computations of the same kind show that $[e_{2^k-1}, \Pi o_{2^{n-1}-3}] = 0$ for any $k = 1, \dots, n-2$. Therefore, $o_{2^{n-1}-2}$ and $o_{2^{n-1}-3}$ are highest weight vectors in $\mathfrak{g}_{\bar{1}}$.

Now, let us prove that there are no lowest weight vectors in $\mathfrak{g}_{\bar{1}}$. Consider the action of e_{-1} on elements of $\mathfrak{g}_{\bar{1}}$. Using (6.3) and (6.4), we obtain

$$[e_{-1}, \Pi o_{-1}] = o_1, \quad [e_{-1}, \Pi o_k] = \Pi o_k + \Pi o_{k-1} \quad \text{for any } k = 0, \dots, 2^{n-1} - 2. \quad (6.7)$$

Therefore, the equation

$$\left[e_{-1}, \sum_{-1 \leq k \leq 2^{n-1}-2} q_k \Pi o_k \right] = 0$$

for lowest weight vectors reduces to the following system of linear equations

$$q_{-1} + q_0 = 0, \quad q_0 + q_1 = 0, \quad \dots, \quad q_{2^{n-1}-3} + q_{2^{n-1}-2} = 0, \quad q_{2^{n-1}-2} = 0.$$

Clearly, this system has only one solution: $q_i = 0$ for $i = -1, \dots, 2^{n-1} - 2$. Hence, there are no lowest weight vectors in $\mathfrak{g}_{\bar{1}}$.

Observe that the highest weight vector $\Pi o_{2^{n-1}-2}$ generates the whole $\mathfrak{g}_{\bar{0}}$ -module $\mathfrak{g}_{\bar{1}}$ and the highest weight vector $\Pi o_{2^{n-1}-3}$ generates a $\mathfrak{g}_{\bar{0}}$ -submodule of codimension 1 in $\mathfrak{g}_{\bar{1}}$, as follows from (6.7). \blacksquare

In what follows we consider only generating functions of the form

$$u(c) = c_0 + \sum_{1 \leq k \leq n-1} c_k x^{(2^k)}, \quad (6.8)$$

where $c = (c_0, c_1, \dots, c_{n-1})$ is a set of free parameters, cf. (6.5). In what follows by ‘‘grading $c = (c_0, c_1, \dots, c_{n-1})$ ’’ we mean the grading given by the corresponding $D_{u(c)}$. One should bear in mind that we call these parameters *free* by an abuse of the language, since they are classes modulo equivalence (6.5).

Let us consider the classification of $\mathbb{Z}/2$ -gradings of $\mathbf{vect}^{(1)}(1; \underline{2})$ in more detail.

6.1 Superizations of $\mathfrak{g} = \mathbf{vect}^{(1)}(1; \underline{2})$

The general solution U_{lin} of linear equations (1.8b), where $c_{1,1}, c_{1,2}, c_{1,3}, c_{2,1}, c_{3,1}$ are free parameters, and the general solution U of equation (1.8), where c_0, c_1 are free parameters, and the schematic form of U are as follows:

$$U_{\text{lin}} = \begin{pmatrix} c_{1,1} & c_{1,2} & c_{1,3} \\ c_{2,1} & 0 & c_{1,2} \\ c_{3,1} & c_{2,1} & c_{1,1} \end{pmatrix}, \quad U = \begin{pmatrix} c_0 c_1 + 1 & c_0 & c_0^2 \\ c_1 & 0 & c_0 \\ c_1^2 & c_1 & c_0 c_1 + 1 \end{pmatrix}, \quad \begin{pmatrix} * & * & * \\ * & * & * \\ * & * & * \end{pmatrix}.$$

This solution corresponds to the derivation D_u with $u(c) = c_0 + c_1 x^{(2)}$.

Parameters and Aut \mathfrak{g} . We denote by (see (6.8))

$$\mathfrak{g}_{\bar{0}}(c) := \text{Ker } D_{u(c)} \tag{6.9}$$

the even part of the corresponding $\mathbb{Z}/2$ -grading. For example, for $\mathfrak{g} = \mathbf{vect}^{(1)}(1; \underline{3})$, by $\mathfrak{g}_{\bar{0}}(c_0, c_1)$ we mean the even part of the $\mathbb{Z}/2$ -grading D_u where $u = c_0 + c_1 x^{(2)}$.

Certain automorphisms and their actions:

$$\begin{aligned} & \begin{pmatrix} \frac{1}{c_0} & 0 & 0 \\ 0 & 1 & 0 \\ \frac{c_1 + c_0 c_1}{c_0} & 0 & c_0 \end{pmatrix} && \text{maps } D_{u(c_0, c_1)} \text{ to } D_{u(1, c_1)} \text{ for all } c_0 \neq 0, \\ & \begin{pmatrix} 1 + c_1 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} && \text{maps } D_{u(1, c_1)} \text{ to } D_{u(1, 1)} \text{ for all } c_1 \in \mathbb{K}, \\ & \begin{pmatrix} c_1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & \frac{1}{c_1} \end{pmatrix} && \text{maps } D_{u(0, c_1)} \text{ to } D_{u(0, 1)} \text{ for all } c_1 \neq 0, \\ & \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} && \text{maps } D_{u(1, 1)} \text{ to } D_{u(0, 1)}. \end{aligned} \tag{6.10}$$

Observe that the automorphism (6.10) sends the outer derivation $D_{1+x^{(2)}}$ to the inner derivation $D_{x^{(2)}}$.

The final answer: there are *three* inequivalent $\mathbb{Z}/2$ -gradings of $\mathbf{vect}^{(1)}(1; \underline{2}) \simeq \mathfrak{o}^{(1)}(3)$; their $\mathfrak{g}_{\bar{0}}$'s are

$$\mathfrak{g}_{\bar{0}}(0, 0) = \mathbb{K}e_0 \quad \text{and} \quad \mathfrak{g}_{\bar{0}}(1, 1) = \mathbb{K}(e_{-1} + e_0 + e_1), \tag{6.11}$$

and the trivial $\mathbb{Z}/2$ -grading with $\mathfrak{g}_{\bar{0}} = \mathbf{vect}^{(1)}(1; \underline{2})$, not *two* as is the case for $\mathbb{Z}/2$ -gradings of $\mathfrak{o}^{(1)}(3) = \mathfrak{o}(3)$ for any $p \neq 2$.

Lie superalgebras corresponding to the gradings (6.11).

Grading $c = (0, 0)$. The minimal Lie subsuperalgebra

$$\mathfrak{g}^{(1)} := (\mathfrak{g}^{(1)})_{\bar{0}} \oplus (\mathfrak{g}^{(1)})_{\bar{1}} \tag{6.12}$$

of the restricted closure $\bar{\mathfrak{g}}$ containing all elements $v^{[2]}$, where $v \in \mathfrak{g}_{\bar{1}} = (\mathfrak{g}^{(1)})_{\bar{1}}$, see equation (1.5), is as follows:

$$\begin{aligned} (\mathfrak{g}^{(1)})_{\bar{0}} &= \text{Span}(e_{-2} = \partial^2, e_0 = x\partial, e_2 = x^{(3)}\partial), \\ (\mathfrak{g}^{(1)})_{\bar{1}} &= \text{Span}(o_{-1} = \partial, o_1 = x^{(2)}\partial). \end{aligned}$$

The squaring in $\mathfrak{s}(\mathfrak{g}^{(1)})$ is given by the following formulas:

$$o_{-1}^2 = (\partial)^2 = e_{-2} = \partial^2, \quad o_1^2 = (x^{(2)}\partial)^2 = e_2 = x^{(3)}\partial.$$

The commutation relations in $(\mathfrak{g}^{(1)})_{\bar{0}}$ are defined by the following formulas:

$$[e_0, e_{-2}] = 0, \quad [e_0, e_2] = 0, \quad [e_{-2}, e_2] = e_0.$$

Observe that $(\mathfrak{g}^{(1)})_{\bar{0}}$ is the Heisenberg algebra. The $(\mathfrak{g}^{(1)})_{\bar{0}}$ -module structure in $(\mathfrak{g}^{(1)})_{\bar{1}}$ is given by the following formulas:

$$\begin{aligned} [e_{-2}, o_{-1}] &= 0, & [e_0, o_{-1}] &= o_{-1}, & [e_2, o_{-1}] &= o_1, \\ [e_{-2}, o_1] &= o_{-1}, & [e_0, o_1] &= o_1, & [e_2, o_1] &= 0. \end{aligned}$$

It is easy to see that $\mathfrak{s}(\mathfrak{g}^{(1)}) \simeq \mathfrak{so}_{III}^{(1)}(1|2) \simeq \mathfrak{k}(1; \underline{1}|1)$; for the (non-obvious) definition of the $\mathfrak{k}(1; \underline{n}|1)$, see [3]. The Lie superalgebra $\mathfrak{so}_{III}^{(1)}(1|2)$ is given by supermatrices of the form

$$\begin{pmatrix} 0 & b_2 & b_1 \\ b_1 & a_1 & a_2 \\ b_2 & a_3 & a_1 \end{pmatrix}, \quad \text{where } a_i, b_i \in \mathbb{K}.$$

The correspondence between the abstract and matrix representations of the elements of $\mathfrak{so}_{III}^{(1)}(1|2)$ is as follows

$$e_{-2} = e_{2,3}, \quad e_0 = e_{2,2} + e_{3,3}, \quad e_2 = e_{3,2}, \quad o_{-1} = e_{1,3} + e_{2,1}, \quad o_1 = e_{1,2} + e_{3,1}.$$

Grading $c = (1, 1) \simeq (1, 0)$. The Lie subsuperalgebra $\mathfrak{g}^{(1)}$, see equation (6.12), is as follows

$$\begin{aligned} (\mathfrak{g}^{(1)})_{\bar{0}} &= \text{Span}(e_1 = (1 + x + x^{(2)})\partial, e_2 = \partial^2 + (1 + x)\partial, e_3 = \partial^2 + (x + x^{(3)})\partial), \\ (\mathfrak{g}^{(1)})_{\bar{1}} &= \text{Span}(o_1 = (1 + x)\partial, o_2 = (1 + x^{(2)})\partial). \end{aligned}$$

The squaring in $\mathfrak{s}(\mathfrak{g}^{(1)})$ is given by the following formulas:

$$o_1^2 = e_2, \quad o_2^2 = e_3.$$

The commutation relations in $(\mathfrak{g}^{(1)})_{\bar{0}}$ are defined by the following formulas:

$$[e_1, e_2] = e_1, \quad [e_1, e_3] = 0, \quad [e_2, e_3] = e_1. \quad (6.13)$$

The $(\mathfrak{g}^{(1)})_{\bar{0}}$ -module structure in $(\mathfrak{g}^{(1)})_{\bar{1}}$ is given by the following formulas:

$$\begin{aligned} [e_1, o_1] &= o_1 + o_2, & [e_2, o_1] &= 0, & [e_3, o_1] &= o_2, \\ [e_1, o_2] &= o_2, & [e_2, o_2] &= o_1 + o_2, & [e_3, o_2] &= 0. \end{aligned}$$

Let us show that $\mathfrak{s}(\mathfrak{g}^{(1)}) \simeq \mathfrak{so}_{II}^{(1)}(1|2)$. The Lie superalgebra $\mathfrak{so}_{II}^{(1)}(1|2)$ consists of symmetric supermatrices with supertrace 0. For a basis of its even part we take

$$E_1 = e_{1,1} + e_{2,2}, \quad E_2 = e_{2,2} + e_{3,3}, \quad E_3 = e_{2,3} + e_{3,2}.$$

For a basis of its odd part we take $O_1 = e_{1,2} + e_{2,1}$, $O_2 = e_{1,3} + e_{3,1}$. The commutation relations are given by the following formulas:

$$[E_1, E_2] = 0, \quad [E_1, E_3] = E_3, \quad [E_2, E_3] = 0.$$

The squaring in $\mathfrak{g}^{(1)}$ is given by the following formulas:

$$O_1^2 = E_1, \quad O_2^2 = E_1 + E_2.$$

The $(\mathfrak{g}^{(1)})_0$ -module structure is as follows

$$[E_2, O_1] = O_1, \quad [E_2, O_2] = O_2.$$

The multiplication by elements E_1 and E_3 is given by the following formulas:

$$[E_1, O_1] = 0, \quad [E_1, O_2] = O_2, \quad [E_3, O_1] = O_2, \quad [E_3, O_2] = O_1.$$

The isomorphism between $\mathfrak{so}_{II}^{(1)}(1|2)$ and $\mathfrak{g}^{(1)}$ is given by the following formulas:

$$e_1 = E_3, \quad e_2 = E_1, \quad e_3 = E_2 + E_3, \quad o_1 = O_1, \quad o_2 = O_1 + O_2.$$

Remark 6.6.

- 1) Observe that the even parts of both superizations are solvable Lie algebras, but the corresponding Lie superalgebras are simple. For more details and examples of this phenomenon indigenous to $p = 2$, see Shchepochkina's comment (the last section) in [6].
- 2) Observe that due to Theorem 6.2 the Lie superalgebra $\mathfrak{so}_{II}^{(1)}(1|2)$ is a filtered deform of the Lie superalgebra $\mathfrak{so}_{III}^{(1)}(1|2)$.

6.2 Superizations corresponding to inner tori

Consider a superization of $\mathfrak{vect}^{(1)}(1; \underline{n})$ given by a generating function u such that $u(0) = 0$. For such a function u , the derivation D_u spans an inner torus. According to [29], the derivation D_u is conjugate to the derivation D_f in $\mathfrak{vect}^{(1)}(1; \underline{n})$, where $f = \sum_{1 \leq i \leq n-1} c_i x^{(2^i)}$ and the $c_i x^{(2^i)}$ are

the corresponding terms of u , so the superizations corresponding to D_u and D_f are isomorphic. For this reason, in the rest of this section we consider only generating functions of the form $\sum_{1 \leq i \leq n-1} c_i x^{(2^i)}$. This gives us an $(n-1)$ -parametric family of $\mathbb{Z}/2$ -gradings.

Conjecture 6.7. *Let $u_1 = \sum_{1 \leq k \leq n-1} c_k x^{(2^k)}$ and $u_2 = \sum_{1 \leq k \leq n-1} b_k x^{(2^k)}$ be generating functions, then the superizations corresponding to D_{u_1} and D_{u_2} are isomorphic if and only if there exists $\varepsilon \in \mathbb{K}^\times$ such that $c_k = \varepsilon^{2^k-1} b_k$ for all $k = 1, \dots, n-1$.*

The following is a sketch of a proof of this conjecture, including a complete computer-aided proof for $2 \leq n \leq 6$.

First of all, if there is an $\varepsilon \neq 0$ such that $c_k = \varepsilon^{2^k-1} b_k$ for all $k = 1, \dots, n-1$, then D_{u_1} and D_{u_2} are conjugate by the automorphism of $\mathfrak{vect}^{(1)}(1; \underline{n})$ given by $x^{(m)} \partial \mapsto \varepsilon^{m-1} x^{(m)} \partial$ (this automorphism is generated by the automorphism of $\mathcal{O}(1; \underline{n})$ given by $x^{(m)} \mapsto \varepsilon^m x^{(m)}$), and therefore the corresponding superizations are isomorphic.

By Theorem 6.2, the superization given by u_1 is isomorphic to a deform of $\mathfrak{k}(1; \underline{n-1}|1)$. Consider the even part of such a deform. According to (6.6), it contains a commutative subalgebra of codimension 1, which is the 0-even part of $\mathfrak{vect}(1; \underline{n})$. The element ∂^2 acts on this commutative subalgebra, and its action is given by

$$v\partial \mapsto (1 + u\partial^2 u)\partial^2 v\partial \quad \text{for any 0-odd } v \in \mathcal{O}(1; \underline{n}). \quad (6.14)$$

Conjecture 6.8 (proved by computer for $n = 2, 3, 4, 5, 6$). *The characteristic polynomial of the linear operator (6.14) on the 0-even part of $\mathbf{vect}(1; \underline{n})$ for $n \geq 2$ is defined by the formula*

$$\lambda^{2^{n-1}} + \sum_{0 \leq k \leq n-2} c_{n-1-k}^{2^{k+1}} \lambda^{2^k}.$$

For two deforms given by u_1 and u_2 to be isomorphic to each other, their even parts have to be isomorphic, which means that the two actions of ∂^2 on the 0-even part of $\mathbf{vect}(1; \underline{n})$ have to be conjugate (similar) up to a non-zero scalar factor, i.e., if A and A' are such operators, then $A' = \alpha M A M^{-1}$ for some non-zero $\alpha \in \mathbb{K}$ and an invertible linear map M . If two operators are conjugate up to a scalar multiple α , the roots of their characteristic polynomials differ by the same multiple, so if the dimension of the space they act on is d (in our case, $d = 2^{n-1}$) and one polynomial is equal to $\sum_{0 \leq i \leq d} z_i \lambda^i$, where $z_i \in \mathbb{K}$ and $z_d = 1$, then the other polynomial would have the form $\sum_{0 \leq i \leq d} z_i \alpha^{d-i} \lambda^i$. So, if Conjecture 6.8 is correct, then for the superizations given by u_1 and u_2 to be isomorphic, there must exist a non-zero $\alpha \in \mathbb{K}$ such that

$$\lambda^{2^{n-1}} + \sum_{0 \leq k \leq n-2} c_{n-1-k}^{2^{k+1}} \lambda^{2^k} = \lambda^{2^{n-1}} + \sum_{0 \leq k \leq n-2} \alpha^{2^{n-1}-2^k} b_{n-1-k}^{2^{k+1}} \lambda^{2^k},$$

or, equivalently, $c_k = \varepsilon^{2^k-1} b_k$, where $\varepsilon = \sqrt{\alpha}$, for all $k = 1, \dots, n-1$. Thus, Conjecture 6.7 follows from Conjecture 6.8.

So, assuming that Conjecture 6.8 is true, the set of equivalence classes of superizations of $\mathbf{vect}^{(1)}(1; \underline{n})$ corresponding to generating functions u such that $u(0) = 0$ consist of the following two types:

- A) the superization corresponding to $u = 0$, which is isomorphic to $\mathfrak{k}(1; \underline{n-1}|1)$,
- B) an $(n-2)$ -parametric family of its pairwise non-isomorphic deforms. Note, though, that it is not a result of $(n-2)$ -parametric deformation of $\mathfrak{k}(1; \underline{n-1}|1)$; to obtain all these deforms, an $(n-1)$ -parametric deformation is needed, but the deforms obtained from some sets of parameters are isomorphic: parameters (c_1, \dots, c_{n-1}) and (b_1, \dots, b_{n-1}) produce isomorphic deformations if and only if there exists an $\varepsilon \in \mathbb{K}^\times$ such that $c_k = \varepsilon^{2^k-1} b_k$ for all $k \in 1, \dots, n-1$.

6.3 Superizations of $\mathbf{vect}^{(1)}(1; \underline{3})$

Let $\mathfrak{g} = \mathbf{vect}^{(1)}(1; \underline{3})$.

Grading $c = (0, 0, 0)$. Recall our notation (6.9). The Lie subsuperalgebra $\mathfrak{g}^{(1)}$, see equation (6.12), is as follows:

$$\begin{aligned} (\mathfrak{g}^{(1)})_{\bar{0}} &= \text{Span}(e_{-2} = \partial^2, e_0 = x\partial, e_2 = x^{(3)}\partial, e_4 = x^{(5)}\partial, e_6 = x^{(7)}\partial), \\ (\mathfrak{g}^{(1)})_{\bar{1}} &= \text{Span}(o_{-1} = \partial, o_1 = x^{(2)}\partial, o_3 = x^{(4)}\partial, o_5 = x^{(6)}\partial). \end{aligned}$$

The squaring in $\mathfrak{s}(\mathfrak{g}^{(1)})$ is given by the following formulas:

$$o_{-1}^2 = e_{-2}, \quad o_1^2 = e_2, \quad o_3^2 = e_6, \quad o_5^2 = 0.$$

The nonzero commutation relations in $(\mathfrak{g}^{(1)})_{\bar{0}}$ are given by the following formulas:

$$[e_2, e_{-2}] = e_0, \quad [e_4, e_{-2}] = e_2, \quad [e_{-2}, e_6] = e_4.$$

The $(\mathfrak{g}^{(1)})_{\bar{0}}$ -module structure in $(\mathfrak{g}^{(1)})_{\bar{1}}$ is given by the following formulas:

$$\begin{aligned} [e_{-2}, o_{-1}] &= 0, & [e_0, o_{-1}] &= o_{-1}, & [e_2, o_{-1}] &= o_1, & [e_4, o_{-1}] &= o_3, & [e_6, o_{-1}] &= o_5, \\ [e_{-2}, o_1] &= o_{-1}, & [e_0, o_1] &= o_1, & [e_2, o_1] &= 0, & [e_4, o_1] &= o_5, & [e_6, o_1] &= 0, \\ [e_{-2}, o_3] &= o_1, & [e_0, o_3] &= o_3, & [e_2, o_3] &= o_5, & [e_4, o_3] &= 0, & [e_6, o_3] &= 0, \\ [e_{-2}, o_5] &= o_3, & [e_0, o_5] &= o_5, & [e_2, o_5] &= 0, & [e_4, o_5] &= 0, & [e_6, o_5] &= 0. \end{aligned}$$

Let L_k and $L^{(k)}$ be given by the formulas

$$L_0 = L^0 = (\mathfrak{g}^{(1)})_{\bar{0}}, \quad L_k = [L_0, L_{k-1}], \quad L^{(k)} = [L^{(k-1)}, L^{(k-1)}] \quad \text{for } k > 0. \quad (6.15)$$

We have

$$L_1 = \text{Span}(e_0, e_2, e_4), \quad L_2 = \text{Span}(e_0, e_2), \quad L_3 = \mathbb{K}e_0, \quad L_4 = 0.$$

Grading $c = (0, 1, 0)$. The Lie subsuperalgebra $\mathfrak{g}^{(1)}$, see equation (6.12), is as follows:

$$\begin{aligned} (\mathfrak{g}^{(1)})_{\bar{0}} &= \text{Span}(e_1 = (x + x^{(2)})\partial, e_2 = x^{(3)}\partial, e_3 = (x^{(5)} + x^{(6)})\partial, \\ &\quad e_4 = \partial^2 + (1 + x)\partial, e_5 = x^{(7)}\partial), \\ (\mathfrak{g}^{(1)})_{\bar{1}} &= \text{Span}(o_1 = (1 + x)\partial, o_2 = x^{(2)}\partial, o_3 = (x^{(4)} + x^{(5)})\partial, o_4 = x^{(6)}\partial). \end{aligned}$$

The squaring in $\mathfrak{s}(\mathfrak{g}^{(1)})$ is given by the following formulas:

$$o_1^2 = e_4, \quad o_2^2 = e_2, \quad o_3^2 = e_5, \quad o_4^2 = 0.$$

The non-zero commutation relations in $(\mathfrak{g}^{(1)})_{\bar{0}}$ are given by the following formulas:

$$[e_1, e_4] = e_1, \quad [e_2, e_4] = e_1, \quad [e_3, e_4] = e_2 + e_3, \quad [e_4, e_5] = e_3.$$

The $(\mathfrak{g}^{(1)})_{\bar{0}}$ -module structure in $(\mathfrak{g}^{(1)})_{\bar{1}}$ is given by the following formulas:

$$\begin{aligned} [e_1, o_1] &= o_1 + o_2, & [e_2, o_1] &= o_2, & [e_3, o_1] &= o_3 + o_4, & [e_4, o_1] &= 0, & [e_5, o_1] &= o_4, \\ [e_1, o_2] &= o_2, & [e_2, o_2] &= 0, & [e_3, o_2] &= o_4, & [e_4, o_2] &= o_1 + o_2, & [e_5, o_2] &= 0, \\ [e_1, o_3] &= o_3 + o_4, & [e_2, o_3] &= o_4, & [e_3, o_3] &= 0, & [e_4, o_3] &= o_2, & [e_5, o_3] &= 0, \\ [e_1, o_4] &= o_4, & [e_2, o_4] &= 0, & [e_3, o_4] &= 0, & [e_4, o_4] &= o_3 + o_4, & [e_5, o_4] &= 0. \end{aligned}$$

Grading $c = (0, 1, \beta)$, where $\beta \neq 0$. The Lie subsuperalgebra $\mathfrak{g}^{(1)}$, see equation (6.12), is as follows:

$$\begin{aligned} (\mathfrak{g}^{(1)})_{\bar{0}} &= \text{Span}(e_1 = (x + x^{(2)} + \beta x^{(4)})\partial, e_2 = (x^{(3)} + \beta x^{(5)})\partial, e_3 = (x^{(5)} + x^{(6)})\partial, \\ &\quad e_4 = \partial^2 + (1 + x + \beta x^{(2)})\partial, e_5 = (x^{(3)} + \beta x^{(5)} + \beta^2 x^{(7)})\partial), \\ (\mathfrak{g}^{(1)})_{\bar{1}} &= \text{Span}(o_1 = (1 + x + \beta x^{(3)})\partial, o_2 = (x^{(2)} + \beta x^{(4)})\partial, \\ &\quad o_3 = (x^{(4)} + x^{(5)})\partial, o_4 = x^{(6)}\partial). \end{aligned}$$

The squaring in $\mathfrak{s}(\mathfrak{g}^{(1)})$ is given by the following formulas:

$$o_1^2 = e_4, \quad o_2^2 = e_5, \quad o_3^2 = \frac{1}{\beta^2}e_2 + \frac{1}{\beta^2}e_5, \quad o_4^2 = 0.$$

The non-zero commutation relations in $(\mathfrak{g}^{(1)})_{\bar{0}}$ are defined by the following formulas:

$$\begin{aligned} [e_1, e_4] &= e_1 + \beta e_2, \\ [e_2, e_4] &= e_1 + \beta e_2 + \beta^2 e_3, & [e_3, e_4] &= e_2 + (1 + \beta)e_3, & [e_4, e_5] &= e_1 + \beta e_2. \end{aligned}$$

The $(\mathfrak{g}^{(1)})_{\bar{0}}$ -module structure in $(\mathfrak{g}^{(1)})_{\bar{1}}$ is given by the following formulas:

$$\begin{aligned} [e_1, o_1] &= o_1 + o_2 + \beta^2 o_4, & [e_2, o_1] &= o_2, & [e_3, o_1] &= o_3 + o_4, & [e_4, o_1] &= 0, \\ [e_1, o_2] &= o_2, & [e_2, o_2] &= 0, & [e_3, o_2] &= o_4, \\ [e_4, o_2] &= o_1 + (1 + \beta)o_2 + \beta^2 o_3, \\ [e_1, o_3] &= o_3 + o_4, & [e_2, o_3] &= o_4, & [e_3, o_3] &= 0, \\ [e_4, o_3] &= o_2 + \beta(o_3 + o_4), \\ [e_1, o_4] &= o_4, & [e_2, o_4] &= 0, & [e_3, o_4] &= 0, & [e_4, o_4] &= o_3 + o_4, \\ [e_5, o_1] &= o_2 + \beta^2 o_4, & [e_5, o_2] &= 0, & [e_5, o_3] &= o_4, & [e_5, o_4] &= 0. \end{aligned}$$

Grading $c = (0, 0, 1)$. The Lie subsuperalgebra $\mathfrak{g}^{(1)}$, see equation (6.12), is as follows:

$$\begin{aligned} (\mathfrak{g}^{(1)})_{\bar{0}} &= \text{Span}(e_1 = (x + x^{(4)})\partial, e_2 = x^{(5)}\partial, \\ &\quad e_3 = (x^{(3)} + x^{(6)})\partial, e_4 = \partial^2 + x^{(2)}\partial, e_5 = x^{(7)}\partial), \\ (\mathfrak{g}^{(1)})_{\bar{1}} &= \text{Span}(o_1 = (1 + x^{(3)})\partial, o_2 = x^{(4)}\partial, o_3 = (x^{(2)} + x^{(5)})\partial, o_4 = x^{(6)}\partial). \end{aligned}$$

The squaring in $\mathfrak{s}(\mathfrak{g}^{(1)})$ is given by the following formulas:

$$o_1^2 = e_4, \quad o_2^2 = e_5, \quad o_3^2 = e_3, \quad o_4^2 = 0.$$

The non-zero commutation relations in $(\mathfrak{g}^{(1)})_{\bar{0}}$ are given by the following formulas:

$$[e_1, e_4] = e_2, \quad [e_2, e_4] = e_3, \quad [e_3, e_4] = e_1, \quad [e_4, e_5] = e_2.$$

The $(\mathfrak{g}^{(1)})_{\bar{0}}$ -module structure in $(\mathfrak{g}^{(1)})_{\bar{1}}$ is given by the following formulas:

$$\begin{aligned} [e_1, o_1] &= o_1 + o_4, & [e_2, o_1] &= o_2, & [e_3, o_1] &= o_3, & [e_4, o_1] &= 0, & [e_5, o_1] &= o_4, \\ [e_1, o_2] &= o_2, & [e_2, o_2] &= 0, & [e_3, o_2] &= o_4, & [e_4, o_2] &= o_3, & [e_5, o_2] &= 0, \\ [e_1, o_3] &= o_3, & [e_2, o_3] &= o_4, & [e_3, o_3] &= 0, & [e_4, o_3] &= o_1 + o_4, & [e_5, o_3] &= 0, \\ [e_1, o_4] &= o_4, & [e_2, o_4] &= 0, & [e_3, o_4] &= 0, & [e_4, o_4] &= o_2, & [e_5, o_4] &= 0. \end{aligned}$$

Grading $c = (1, 0, 0)$. The Lie subsuperalgebra $\mathfrak{g}^{(1)}$, see equation (6.12), is as follows:

$$\begin{aligned} (\mathfrak{g}^{(1)})_{\bar{0}} &= \text{Span}(e_{-2} = \partial^2 + (1 + x)\partial, e_{-1} = (1 + x)\partial, e_0 = (x + x^{(2)} + x^{(3)})\partial, \\ &\quad e_1 = (x^{(2)} + x^{(4)} + x^{(5)})\partial, e_2 = (x^{(3)} + x^{(5)} + x^{(6)} + x^{(7)})\partial), \\ (\mathfrak{g}^{(1)})_{\bar{1}} &= \text{Span}(o_1 = \partial, o_2 = (x + x^{(2)})\partial, \\ &\quad o_3 = (x^{(2)} + x^{(3)} + x^{(4)})\partial, o_4 = (x^{(3)} + x^{(5)} + x^{(6)})\partial). \end{aligned}$$

The squaring in $\mathfrak{s}(\mathfrak{g}^{(1)})$ is given by the following formulas:

$$o_1^2 = e_{-2}, \quad o_2^2 = e_0, \quad o_3^2 = e_2, \quad o_4^2 = 0.$$

The non-zero commutation relations in $(\mathfrak{g}^{(1)})_{\bar{0}} \simeq (\mathbf{vect}(1; \underline{3}))^{(1)}$ are given by the following formulas:

$$[e_{-1}, e_0] = e_{-1}, \quad [e_{-1}, e_1] = e_0, \quad [e_{-1}, e_2] = e_1, \quad [e_1, e_{-2}] = e_{-1}, \quad [e_0, e_1] = e_1.$$

The $(\mathfrak{g}^{(1)})_{\bar{0}}$ -module structure in $(\mathfrak{g}^{(1)})_{\bar{1}}$ is given by the following formulas:

$$[e_{-1}, o_1] = o_1, \quad [e_0, o_1] = o_1 + o_2, \quad [e_1, o_1] = o_2 + o_3, \quad [e_2, o_1] = o_3 + o_4,$$

$$\begin{aligned}
[e_{-2}, o_1] &= o_1, \\
[e_{-1}, o_2] &= o_1 + o_2, & [e_0, o_2] &= 0, & [e_1, o_2] &= o_3 + o_4, & [e_2, o_2] &= 0, \\
[e_{-2}, o_2] &= o_2, \\
[e_{-1}, o_3] &= o_2 + o_3, & [e_0, o_3] &= o_3 + o_4, & [e_1, o_3] &= 0, & [e_2, o_3] &= 0, \\
[e_{-2}, o_3] &= o_1 + o_3, \\
[e_{-1}, o_4] &= o_3 + o_4, & [e_0, o_4] &= 0, & [e_1, o_4] &= 0, & [e_2, o_4] &= 0, \\
[e_{-2}, o_4] &= o_2 + o_4.
\end{aligned}$$

We have

$$\begin{aligned}
[(\mathfrak{g}^{(1)})_{\bar{0}}, (\mathfrak{g}^{(1)})_{\bar{0}}] &= \text{Span}(e_{-1}, e_0, e_1), \\
[(\mathfrak{g}^{(1)})_{\bar{0}}, [(\mathfrak{g}^{(1)})_{\bar{0}}, (\mathfrak{g}^{(1)})_{\bar{0}}]] &= [(\mathfrak{g}^{(1)})_{\bar{0}}, (\mathfrak{g}^{(1)})_{\bar{0}}].
\end{aligned}$$

The ideal $[(\mathfrak{g}^{(1)})_{\bar{0}}, (\mathfrak{g}^{(1)})_{\bar{0}}]$ is isomorphic to $\mathfrak{o}^{(1)}(3)$. The $\mathfrak{o}^{(1)}(3)$ -module $(\mathfrak{g}^{(1)})_{\bar{1}}$ is irreducible, it has no lowest weight vectors and has highest vectors o_3 and o_4 , cf. [11].

6.4 Summary of computer-aided experiments

Let L_k and $L^{(k)}$ be given by equation (6.15); in tables below, $k = 1, 2, \dots$ up to first stable term. Theorem 6.2 implies the following fact:

$$\begin{aligned}
\text{sdim } \mathfrak{s}(\mathfrak{g}, D_{u(c)}) &= (2^{n-1} + 1|2^{n-1}) \quad \text{and} \\
\dim [(\mathfrak{g}^{(1)})_{\bar{0}}, (\mathfrak{g}^{(1)})_{\bar{0}}] &= 2^{n-1} - 1.
\end{aligned}$$

Recall that \mathfrak{v}_n is defined by (6.1); the symbol “solv” below means that the corresponding Lie algebra is solvable, see Corollary 6.4. Computer-aided experiments show that

| | $(\mathfrak{g}^{(1)})_{\bar{0}}$ | $\dim L_k$ | $\dim L^{(k)}$ | parameters |
|---|----------------------------------|------------|----------------|------------------|
| $\mathfrak{vect}^{(1)}(1; \underline{2})$ | Heisenberg | 1, 0 | 1, 0 | (00) |
| | solv, see (6.13) | 1 | 1, 0 | (01), (10), (11) |

| | $(\mathfrak{g}^{(1)})_{\bar{0}}$ | $\dim L_k$ | $\dim L^{(k)}$ | parameters |
|---|--|------------|----------------|--|
| $\mathfrak{vect}^{(1)}(1; \underline{3})$ | $\mathfrak{o}(3)/\mathfrak{c} \simeq \mathfrak{v}_3$ | 3 | 3 | (1ab) |
| | solv | 3, 2, 1, 0 | 3, 0 | (000) |
| | solv | 3, 2 | 3, 0 | (010), (010), (0 α 0), where $\alpha \neq 0$ |
| | solv | 3 | 3, 0 | (001), (011), (0 $\alpha\beta$), where $\beta \neq 0$ |

| | $\mathfrak{g}_{\bar{0}}^{(1)}$ | $\dim L_k$ | $\dim L^{(k)}$ | parameters |
|---|--------------------------------|------------------------|----------------|--------------------------------|
| $\mathfrak{vect}^{(1)}(1; \underline{4})$ | \mathfrak{v}_4 | 7 | 7 | (1abc) |
| | solv | 7, 6, 5, 4, 3, 2, 1, 0 | 7, 0 | (0000) |
| | solv | 7, 6, 4 | 7, 0 | (0100) |
| | solv | 7, 6 | 7, 0 | (0010), (0110) |
| | solv | 7 | 7, 0 | (0001), (0011), (0101), (0111) |

| $\mathfrak{g}_0^{(1)}$ | $\dim L_k$ | $\dim L^{(k)}$ | parameters |
|---|------------|---|---|
| \mathfrak{v}_5 | 15 | 15 | (1abcd) |
| $\mathbf{vect}^{(1)}(1; \underline{5})$ | solv | 15, 14, 13, 12, 11, 10, 9, 8, 7, 6, 5, 4, 3, 2, 1, 0 | (00000) |
| | solv | 15, 14, 13, 12, 11, 10, 9, 8 | (01000) |
| | solv | 15, 14, 13, 12 | (00100), (01100) |
| | solv | 15, 14 | (00010), (00110), (01010), (01110) |
| | solv | 15 | (00001), (00011), (00101), (00111), (01001), (01011), (01101), (01111) |

Let \mathbf{i} be the last term of the sequence L_k , see (6.15), for the even part \mathfrak{g}_0 of the corresponding Lie superalgebra \mathfrak{g} . Set

$$c(i) := (0 \dots 010 \dots 0) \quad \text{with a 1 in the } (i+1)\text{st slot.}$$

Conjecture 6.9. *Grading $c(k)$ with the corresponding generating function $u = x^{(2^k)}$, where $k = 1, \dots, n-1$, yields the Lie superalgebras such that $\dim \mathbf{i} = 2^{n-1} - 2^{n-1-k}$.*

The following two conjectures concern $\mathbf{vect}^{(1)}(1; \underline{n})$, where $n \geq 3$.

Conjecture 6.10. *Let $u = \sum_{1 \leq i \leq n-1} c_i x^{(2^i)}$, i.e., $c_0 = 0$. If all c_i are equal to 0, then let k be 0; otherwise, let k be the maximal number such that $c_k \neq 0$. Then the grading given by D_u yields the Lie superalgebras such that $\dim \mathbf{i} = 2^{n-1} - 2^{n-1-k}$.*

6.5 The derivations of $\mathbf{vect}^{(1)}(1; \underline{n})$

The result of this subsection is probably known, but we'd like to draw attention to Sierpiński sieves here. Observe that solutions of the linear equations (1.8b), i.e., derivations of $\mathbf{vect}^{(1)}(1; \underline{n})$, form the Sierpiński sieve of order \underline{n} under the main diagonal, i.e., for $i \geq j$, we have

$$c_{i,j} = \binom{i}{j-1} c_{i-j+1,1}, \quad \text{which corresponds to the derivation } \text{ad}_{x^{(i-j+1)}\partial},$$

and for $i < j$ we have nonzero diagonals with parameters $c_{1,2^k+1}$, where $k = 0, \dots, n-1$, which correspond to the derivations $\text{ad}_{\partial^{2^k}}$, e.g.,

$$\begin{aligned} c_{1,j} &= 0 & \text{if } j \neq 2^k + 1, \text{ where } k \text{ is a non-negative integer,} \\ c_{i,j} &= c_{i-1,j-1} & \text{for } i > 1. \end{aligned}$$

Namely, for $\underline{n} = 3$, we have the following solution of linear equations (1.8b), and its schematic form (here $*$ represents any nonzero entry and the empty entries represent zeros):

$$U_{\text{lin}} = \begin{pmatrix} c_{1,1} & c_{1,2} & c_{1,3} & 0 & c_{1,5} & 0 & 0 \\ c_{2,1} & 0 & c_{1,2} & c_{1,3} & 0 & c_{1,5} & 0 \\ c_{3,1} & c_{2,1} & c_{1,1} & c_{1,2} & c_{1,3} & 0 & c_{1,5} \\ c_{4,1} & 0 & 0 & 0 & c_{1,2} & c_{1,3} & 0 \\ c_{5,1} & c_{4,1} & 0 & 0 & c_{1,1} & c_{1,2} & c_{1,3} \\ c_{6,1} & 0 & c_{4,1} & 0 & c_{2,1} & 0 & c_{1,2} \\ c_{7,1} & c_{6,1} & c_{5,1} & c_{4,1} & c_{3,1} & c_{2,1} & c_{1,1} \end{pmatrix}, \quad \begin{pmatrix} * & * & * & * & & & \\ * & & * & * & * & & \\ * & * & * & * & * & * & \\ * & & & * & * & & \\ * & * & & * & * & * & \\ * & & * & * & * & * & \\ * & * & * & * & * & * & * \end{pmatrix}.$$

Since $o^{\{i,k\}} = [o^{\{i,j\}}, o^{\{j,k\}}]$, we have

$$\begin{aligned} (Do^{\{i,k\}})_{ik} &= (D[o^{\{i,j\}}, o^{\{j,k\}}])_{ik} = [Do^{\{i,j\}}, o^{\{j,k\}}]_{ik} + [o^{\{i,j\}}, Do^{\{j,k\}}]_{ik} \\ &= (Do^{\{i,j\}})_{ij} + (Do^{\{k,j\}})_{jk}, \end{aligned}$$

which proves (A.1).

Note that (A.2) and (A.3) are vacuously true for $n = 3$, since in this case, there exist no four pairwise distinct indices. In case of $n \geq 5$, let m be an index different from all of i, j, k, l . Then $[o^{\{i,j\}}, o^{\{l,m\}}] = 0$, which means that

$$0 = (D[o^{\{i,j\}}, o^{\{l,m\}}])_{km} = [Do^{\{i,j\}}, o^{\{l,m\}}]_{km} + [o^{\{i,j\}}, Do^{\{l,m\}}]_{km} = (Do^{\{i,j\}})_{kl} + 0,$$

which proves (A.2). Since $o^{\{i,k\}} = [o^{\{i,j\}}, o^{\{j,k\}}]$, we have

$$(Do^{\{i,k\}})_{il} = (D[o^{\{i,j\}}, o^{\{j,k\}}])_{il} = [Do^{\{i,j\}}, o^{\{j,k\}}]_{il} + [o^{\{i,j\}}, Do^{\{j,k\}}]_{il} = 0 + (Do^{\{j,k\}})_{jl},$$

which proves the first equality in (A.3). And since $o^{\{i,k\}} = [o^{\{i,l\}}, o^{\{k,l\}}]$, we have

$$(Do^{\{i,k\}})_{il} = (D[o^{\{i,l\}}, o^{\{k,l\}}])_{il} = [Do^{\{i,l\}}, o^{\{k,l\}}]_{il} + [o^{\{i,l\}}, Do^{\{k,l\}}]_{il} = (Do^{\{i,l\}})_{ik} + 0,$$

which proves the second equality in (A.3).

Now consider matrix A_D whose entries are as follows:

$$\begin{aligned} (A_D)_{11} &= 0, & (A_D)_{ii} &= (Do^{\{1,i\}})_{1i} & \text{for } i \neq 1, \\ (A_D)_{ij} &= (Do^{\{k,i\}})_{kj} & & & \text{for } i \neq j, \text{ and some } k \neq i, j. \end{aligned}$$

Note that (A.3) shows that $(A_D)_{ij}$ does not depend on the choice of k and that the matrix is symmetric, i.e., $(A_D)_{ij} = (A_D)_{ji}$.

Then it follows from (A.1), (A.2) and (A.3) that $Do^{\{i,j\}} = [A_D, o^{\{i,j\}}]$ for an arbitrary $o^{\{i,j\}}$. Since the $o^{\{i,j\}}$ form a basis of $\mathfrak{o}_I^{(1)}(n)$, it means that D coincides with the restriction of ad_{A_D} to $\mathfrak{o}_I^{(1)}(n)$. On the other hand, it is easy to check that for any matrix $A \in \mathfrak{o}_I(n)$, the restriction of ad_A to $\mathfrak{o}_I^{(1)}(n)$ is a derivation of $\mathfrak{o}_I^{(1)}(n)$, and that two matrices $A, A' \in \mathfrak{o}_I(n)$ determine the same derivation of $\mathfrak{o}_I^{(1)}(n)$ if and only if $A - A' = c1_n$ for some $c \in \mathbb{K}$. This proves our claim. ■

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