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HIGHER DIMENSIONAL ALGEBRA VII: GROUPOIDIFICATION

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Abstract. Groupoidification is a form of categorification in which vector spaces are replaced by groupoids and linear operators are replaced by spans of groupoids. We introduce this idea with a detailed exposition of 'degroupoidification': a systematic process that turns groupoids and spans into vector spaces and linear operators. Then we present three applications of groupoidification. The first is to Feynman diagrams. The Hilbert space for the quantum harmonic oscillator arises naturally from degroupoidifying the groupoid of finite sets and bijections. This allows for a purely combinatorial interpretation of creation and annihilation operators, their commutation relations, field operators, their normal-ordered powers, and finally Feynman diagrams. The second application is to Hecke algebras. We explain how to groupoidify the Hecke algebra associated to a Dynkin diagram whenever the deformation parameter q is a prime power. We illustrate this with the simplest nontrivial example, coming from the A_2 Dynkin diagram. In this example we show that the solution of the Yang–Baxter equation built into the A_2 Hecke algebra arises naturally from the axioms of projective geometry applied to the projective plane over the finite field $\mathbb{F}_q$. The third application is to Hall algebras. We explain how the standard construction of the Hall algebra from the category of $\mathbb{F}_q$ representations of a simply-laced quiver can be seen as an example of degroupoidification. This in turn provides a new way to categorify—or more precisely, groupoidify—the positive part of the quantum group associated to the quiver.

1. Introduction

'Groupoidification' is an attempt to expose the combinatorial underpinnings of linear algebra—the hard bones of set theory underlying the flexibility of the continuum. One of the main lessons of modern algebra is to avoid choosing bases for vector spaces until you need them. As Hermann Weyl wrote, "The introduction of a coordinate system to geometry is an act of violence". But vector spaces often come equipped with a natural basis—and when this happens, there is no harm in taking advantage of it. The most obvious example is when our vector space has been defined to consist of formal linear combinations of the elements of some set. Then this set is our basis. But surprisingly often, the elements of this set are *isomorphism classes of objects in some groupoid*. This is when groupoidification can be useful. It lets us work directly with the groupoid, using tools analogous to those of linear algebra, without bringing in the real numbers (or any other ground field).

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For example, let E be the groupoid of finite sets and bijections. An isomorphism class of finite sets is just a natural number, so the set of isomorphism classes of objects in E can be identified with $\mathbb{N}$. Indeed, this is why natural numbers were invented in the first place: to count finite sets. The real vector space with $\mathbb{N}$ as basis is usually identified with the polynomial algebra $\mathbb{R}[z]$, since that has basis $z^0, z^1, z^2, \ldots$. Alternatively, we can work with *infinite* formal linear combinations of natural numbers, which form the algebra of formal power series, $\mathbb{R}[[z]]$. So, the vector space of formal power series is a kind of stand-in for the groupoid of finite sets.

Indeed, formal power series have long been used as 'generating functions' in combinatorics [46]. Given any combinatorial structure we can put on finite sets, its generating function is the formal power series whose nth coefficient says how many ways we can put this structure on an n-element set. André Joyal formalized the idea of 'a structure we can put on finite sets' in terms of *espèces de structures*, or 'structure types' [6, 22, 23]. Later his work was generalized to 'stuff types' [4], which are a key example of groupoidification.

Heuristically, a stuff type is a way of equipping finite sets with a specific type of extra stuff—for example a 2-coloring, or a linear ordering, or an additional finite set. Stuff types have generating functions, which are formal power series. Combinatorially interesting operations on stuff types correspond to interesting operations on their generating functions: addition, multiplication, differentiation, and so on. Joyal's great idea amounts to this: *work directly with stuff types as much as possible, and put off taking their generating functions.* As we shall see, this is an example of groupoidification.

To see how this works, we should be more precise. A **stuff type** is a groupoid over the groupoid of finite sets: that is, a groupoid Ψ equipped with a functor $v\colon \Psi \to E$. The reason for the funny name is that we can think of Ψ as a groupoid of finite sets 'equipped with extra stuff'. The functor v is then the 'forgetful functor' that forgets this extra stuff and gives the underlying set.

The generating function of a stuff type $v\colon \Psi \to E$ is the formal power series

$$\Psi(z) = \sum_{n=0}^{\infty} |v^{-1}(n)|\, z^n. \tag{1}$$

Here $v^{-1}(n)$ is the 'full inverse image' of any n-element set, say $n \in E$. We define this term later, but the idea is straightforward: $v^{-1}(n)$ is the groupoid of n-element sets equipped with the given type of stuff. The nth coefficient of the generating function measures the size of this groupoid.

But how? Here we need the concept of *groupoid cardinality*. It seems this concept first appeared in algebraic geometry [5, 28]. We rediscovered it by pondering the meaning of division [4]. Addition of natural numbers comes from disjoint union of finite sets, since

$$|S + T| = |S| + |T|.$$

Multiplication comes from cartesian product:

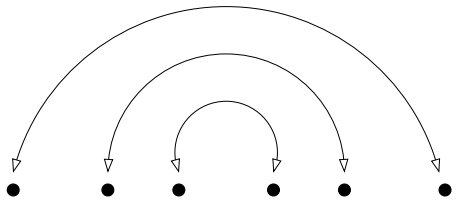
$$|S \times T| = |S| \times |T|.$$

But what about division?

If a group G acts on a set S, we can 'divide' the set by the group and form the quotient S/G. If S and G are finite and G acts freely on S, S/G really deserves the name 'quotient', since then

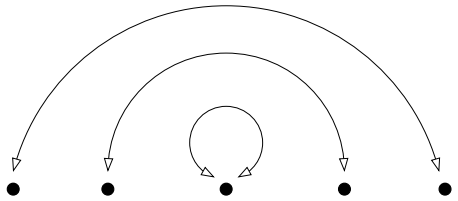
$$|S/G| = |S|/|G|.$$

Indeed, this fact captures some of our naive intuitions about division. For example, why is $6/2 = 3$? We can take a 6-element set S with a free action of the group $G = \mathbb{Z}/2$ and construct the set of orbits S/G:



Since we are 'folding the 6-element set in half', we get $|S/G| = 3$.

The trouble starts when the action of G on S fails to be free. Let's try the same trick starting with a 5-element set:



We don't obtain a set with $2\frac{1}{2}$ elements! The reason is that the point in the middle gets mapped to itself. To get the desired cardinality $2\frac{1}{2}$, we would need a way to count this point as 'folded in half'.

To do this, we should first replace the ordinary quotient S/G by the 'action groupoid' or **weak quotient** $S//G$. This is the groupoid where objects are elements of S, and a morphism from $s \in S$ to $s' \in S$ is an element $g \in G$ with $gs = s'$. Composition of morphisms works in the obvious way. Next, we should define the 'cardinality' of a groupoid as follows. For each isomorphism class of objects, pick a representative x and compute the reciprocal of the number of automorphisms of this object; then sum the result over isomorphism classes. In other words, define the **cardinality** of a groupoid X to be

$$|X| = \sum_{\text{isomorphism classes of objects [x]}} \frac{1}{|\mathrm{Aut}(x)|} \,. \tag{2}$$

With these definitions, our problematic example gives a groupoid $S//G$ with cardinality $2\frac{1}{2}$, since the point in the middle of the picture gets counted as 'half a point'. In fact,

$$|S//G| = |S|/|G|$$

whenever G is a finite group acting on a finite set S.

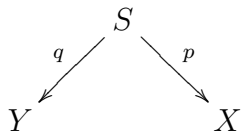
The concept of groupoid cardinality gives an elegant definition of the generating function of a stuff type—Equation 1—which matches the usual 'exponential generating function' from combinatorics. For the details of how this works, see Example 2.11.

Even better, we can vastly generalize the notion of generating function, by replacing E with an arbitrary groupoid. For any groupoid X we get a vector space: namely $\mathbb{R}^{\underline{X}}$, the space of functions $\psi\colon \underline{X} \to \mathbb{R}$, where $\underline{X}$ is the set of isomorphism classes of objects in X. Any sufficiently nice groupoid over X gives a vector in this vector space.

The question then arises: what about linear operators? Here it is good to take a lesson from Heisenberg's matrix mechanics. In his early work on quantum mechanics, Heisenberg did not know about matrices. He reinvented them based on this idea: a matrix S can describe a quantum process by letting the matrix entry $S_i^j \in \mathbb{C}$ stand for the 'amplitude' for a system to undergo a transition from its ith state to its jth state.

The meaning of complex amplitudes was somewhat mysterious—and indeed it remains so, much as we have become accustomed to it. However, the mystery evaporates if we have a matrix whose entries are natural numbers. Then the matrix entry $S_i^j \in \mathbb{N}$ simply counts the *number of ways* for the system to undergo a transition from its ith state to its jth state.

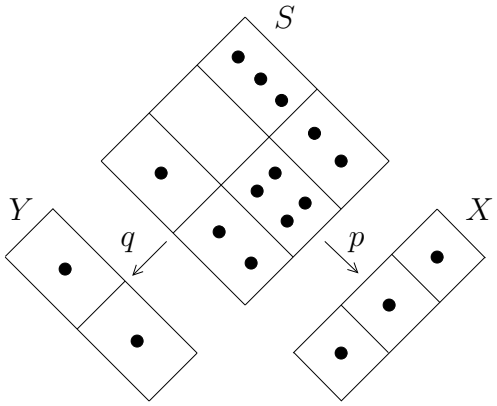
Indeed, let X be a set whose elements are possible 'initial states' for some system, and let Y be a set whose elements are possible 'final states'. Suppose S is a set equipped with maps to X and Y:



Mathematically, we call this setup a span of sets. Physically, we can think of S as a set of possible 'events'. Points in S sitting over $i \in X$ and $j \in Y$ form a subset

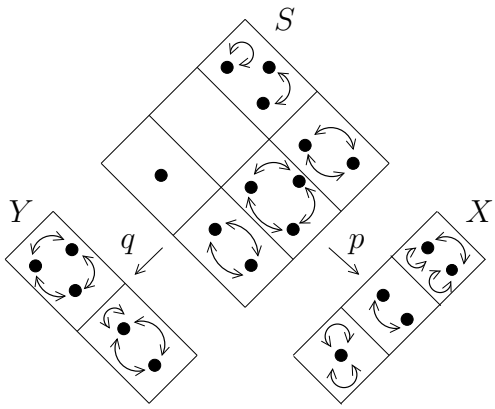
$$S_i^j = \{s\colon\ q(s) = j,\ p(s) = i\}.$$

We can think of this as the *set of ways* for the system to undergo a transition from its ith state to its jth state. Indeed, we can picture S more vividly as a matrix of sets:



If all the sets S_i^j are finite, we get a matrix of natural numbers $|S_i^j|$.

Of course, matrices of natural numbers only allow us to do a limited portion of linear algebra. We can go further if we consider, not spans of sets, but *spans of groupoids*. We can picture one of these roughly as follows:



If a span of groupoids is sufficiently nice—our technical term will be 'tame'—we can convert it into a linear operator from $\mathbb{R}^{\underline{X}}$ to $\mathbb{R}^{\underline{Y}}$. Viewed as a matrix, this operator will have nonnegative real matrix entries. So, we have not succeeded in 'groupoidifying' full-fledged quantum mechanics, where the matrices can be complex. Still, we have made some progress.

As a sign of this, it turns out that any groupoid X gives not just a vector space $\mathbb{R}^{\underline{X}}$, but a real Hilbert space $L^2(X)$. If $X = E$, the complexification of this Hilbert space is the Hilbert space of the quantum harmonic oscillator. The quantum harmonic oscillator is the simplest system where we can see the usual tools of quantum field theory at work: for example, Feynman diagrams. It turns out that large portions of the theory of Feynman diagrams can be done with spans of groupoids replacing operators [4]. The combinatorics of these diagrams then becomes vivid, stripped bare of the trappings of analysis. We sketch how this works in Section 4.1. A more detailed treatment can be found in the work of Jeffrey Morton [33].

To get complex numbers into the game, Morton generalizes groupoids to 'groupoids over U(1)': that is, groupoids X equipped with functors $v\colon X \to \mathrm{U}(1)$, where U(1) is the groupoid with unit complex numbers as objects and only identity morphisms. The cardinality of a groupoid over U(1) can be complex.

Other generalizations of groupoid cardinality are also interesting. For example, Leinster has generalized it to categories [29]. The cardinality of a category can be negative! More recently, Weinstein has generalized the concept of cardinality to Lie groupoids [45]. Getting a useful generalization of groupoids for which the cardinality is naturally complex, without putting in the complex numbers 'by hand', remains an elusive goal. However, the work of Fiore and Leinster suggests that it is possible [13].

In the last few years James Dolan, Todd Trimble and the authors have applied groupoidification to better understand the process of 'q-deformation' [2]. Many important algebraic structures can be systematically deformed in a way that depends on a parame-

ter q, with $q = 1$ being the 'default' case of no deformation at all. A beautiful story has begun to emerge in which q-deformation arises naturally from replacing the groupoid of pointed finite sets by the groupoid of finite-dimensional vector spaces over the field with q elements, $\mathbb{F}_q$, where q is a prime power. We hope to write up this material and develop it further in the years to come. This paper is just a first installment.

For example, any Dynkin diagram with n dots gives rise to a finite group of linear transformations of $\mathbb{R}^n$ which is generated by reflections, one for each dot of the Dynkin diagram, which satisfy some relations, one for each edge. These groups are called 'Coxeter groups' [20]. The simplest example is the symmetry group of the regular n-simplex, which arises from a Dynkin diagram with n dots in a row, like this:

This group is generated by n reflections s_d, one for each dot d. These generators obey the Yang–Baxter equation:

$$s_d s_{d'} s_d = s_{d'} s_d s_{d'}$$

when the dots d and d' are connected by an edge, and they commute otherwise. Indeed the symmetry group of the regular n-simplex is just the symmetric group S_{n+1}, which acts as permutations of the vertices, and the generator s_d is the transposition that switches the dth and $(d+1)$st vertices.

Coxeter groups are a rich and fascinating subject, and part of their charm comes from the fact that the group algebra of any Coxeter group admits a q-deformation, called a 'Hecke algebra', which has many of the properties of the original group (as expressed through its group algebra). The Hecke algebra again has one generator for each dot of the Dynkin diagram, now called σ_d. These generators obey the same relation for each edge that we had in the original Coxeter group. The only difference is that while the Coxeter group generators are reflections, and thus satisfy $s_d^2 = 1$, the Hecke algebra generators obey a q-deformed version of this equation:

$$\sigma_d^2 = (q-1)\sigma_d + q.$$

Where do Hecke algebras come from? They arise in a number of ways, but one enlightening description involves the theory of 'buildings', where each Dynkin diagram corresponds to a type of geometry [10, 15]. For example, the Dynkin diagram shown above (with n dots) corresponds to the geometry of projective n-space. Projective n-space makes sense over any field, and when q is a prime power, the Hecke algebra arises in the study of n-dimensional projective space over the field $\mathbb{F}_q$. We shall explain this in detail in the case of the projective plane. The n-simplex can be thought of as a '$q \to 1$ limit' of an n-dimensional projective space over $\mathbb{F}_q$. The idea is that the vertices, edges, triangles, and so on of the n-simplex play the role of points, lines, planes, and so on in a degenerate sort of projective space. In this limiting case, the Hecke algebra reduces to the group algebra of the symmetric group. As it turns out, this fact can be understood more clearly when we *groupoidify* the Hecke algebra. We shall sketch the idea in this paper, and give more details in the next paper of this series. In the meantime, see [18].

Any Dynkin diagram also gives a geometry over the field $\mathbb{C}$, and the symmetries of this geometry form a simple Lie group. The symmetry transformations close to the identity are described by the Lie algebra $\mathfrak{g}$ of this group—or equally well, by the universal enveloping algebra $U\mathfrak{g}$, which is a Hopf algebra. This universal enveloping algebra admits a q-deformation, a Hopf algebra $U_q\mathfrak{g}$ known as a 'quantum group'. There has been a lot of work attempting to categorify quantum groups, from the early ideas of Crane and Frenkel [11], to the work of Khovanov, Lauda and Rouqier [26, 27, 37], and beyond.

Here we sketch how to groupoidify, not the whole quantum group, but only its 'positive part' $U_q^+\mathfrak{g}$. When $q = 1$, this positive part is just the universal enveloping algebra of a chosen maximal nilpotent subalgebra of $\mathfrak{g}$. The advantage of restricting attention to the positive part is that $U_q^+\mathfrak{g}$ has a basis in which the formula for the product involves only *nonnegative* real numbers—and any such number is the cardinality of some groupoid.

The strategy for groupoidifying $U_q^+\mathfrak{g}$ is implicit in Ringel's work on Hall algebras [34]. Suppose we have a 'simply-laced' Dynkin diagram, meaning one where two generators of the Coxeter group obey the Yang-Baxter equation whenever the corresponding dots are connected by an edge. If we pick a direction for each edge of this Dynkin diagram, we obtain a directed graph. This in turn freely generates a category, say Q. The objects in this category are the dots of the Dynkin diagram, while the morphisms are paths built from directed edges.

For any prime power q, there is a category $\mathrm{Rep}(Q)$ whose objects are 'representations' of Q: that is, functors

$$R \colon Q \to \mathrm{FinVect}_q,$$

where $\mathrm{FinVect}_q$ is the category of finite-dimensional vector spaces over $\mathbb{F}_q$. The morphisms in $\mathrm{Rep}(Q)$ are natural transformations. Thanks to the work of Ringel, one can see that the underlying groupoid of $\mathrm{Rep}(Q)$—which has only natural *isomorphisms* as morphisms—groupoidifies the vector space $U_q^+\mathfrak{g}$. Even better, we can groupoidify the product in $U_q^+\mathfrak{g}$. The same sort of construction with the category of pointed finite sets replacing $\mathrm{FinVect}_q$ lets us handle the $q = 1$ case [43]. So yet again, q-deformation is related to the passage from pointed finite sets to finite-dimensional vector spaces over finite fields.

The plan of the paper is as follows. In Section 2, we present some basic facts about 'degroupoidification'. We describe a process that associates to any groupoid X the vector space $\mathbb{R}^{\underline{X}}$ consisting of real-valued functions on the set of isomorphism classes of objects of X, and associates to any 'tame' span of groupoids a linear operator. In Section 3, we describe a slightly different process, which associates to X the vector space $\mathbb{R}[\underline{X}]$ consisting of formal linear combinations of isomorphism classes of objects of X. Then we turn to some applications. Section 4.1 describes how to groupoidify the theory of Feynman diagrams, Section 4.2 describes how to groupoidify the theory of Hecke algebras, and Section 4.4 describes how to groupoidify Hall algebras. In Section 5 we prove that degroupoidifying a tame span gives a well-defined linear operator. We also give an explicit criterion for when a span of groupoids is tame, and an explicit formula for the operator coming from a tame span. Section 6 proves many other results stated earlier in the paper. Appendix A provides some basic definitions and useful lemmas regarding groupoids and

spans of groupoids. The goal is to make it easy for readers to try their own hand at groupoidification.

2. Degroupoidification

In this section we describe a systematic process for turning groupoids into vector spaces and tame spans into linear operators. This process, 'degroupoidification', is in fact a kind of functor. 'Groupoidification' is the attempt to *undo* this functor. To 'groupoidify' a piece of linear algebra means to take some structure built from vector spaces and linear operators and try to find interesting groupoids and spans that degroupoidify to give this structure. So, to understand groupoidification, we need to master degroupoidification.

We begin by describing how to turn a groupoid into a vector space. In what follows, all our groupoids will be **essentially small**. This means that they have a *set* of isomorphism classes of objects, not a proper class. We also assume our groupoids are **locally finite**: given any pair of objects, the set of morphisms from one object to the other is finite.

2.1. Definition. *Given a groupoid X, let $\underline{X}$ be the set of isomorphism classes of objects of X.*

2.2. Definition. *Given a groupoid X, let the* **degroupoidification** *of X be the vector space*

$$\mathbb{R}^{\underline{X}} = \{\Psi \colon \underline{X} \to \mathbb{R}\}.$$

A nice example is the groupoid of finite sets and bijections:

2.3. Example. Let E be the groupoid of finite sets and bijections. Then $\underline{E} \cong \mathbb{N}$, so

$$\mathbb{R}^{\underline{E}} \cong \{\psi \colon \mathbb{N} \to \mathbb{R}\} \cong \mathbb{R}[[z]],$$

where the formal power series associated to a function $\psi \colon \mathbb{N} \to \mathbb{R}$ is given by:

$$\sum_{n \in \mathbb{N}} \psi(n) z^n.$$

A sufficiently nice groupoid over a groupoid X will give a vector in $\mathbb{R}^{\underline{X}}$. To construct this, we use the concept of groupoid cardinality:

2.4. Definition. *The* **cardinality** *of a groupoid X is*

$$|X| = \sum_{[x] \in \underline{X}} \frac{1}{|\mathrm{Aut}(x)|}$$

where $|\mathrm{Aut}(x)|$ is the cardinality of the automorphism group of an object x in X. If this sum diverges, we say $|X| = \infty$.

The cardinality of a groupoid X is a well-defined nonnegative rational number whenever $\underline{X}$ and all the automorphism groups of objects in X are finite. More generally, we say:

2.5. Definition. *A groupoid X is* **tame** *if it is essentially small, locally finite, and $|X| < \infty$.*

We show in Lemma A.13 that given equivalent groupoids X and Y, $|X| = |Y|$. We give a useful alternative formula for groupoid cardinality in Lemma 5.6.

The reason we use $\mathbb{R}$ rather than $\mathbb{Q}$ as our ground field is that there are interesting groupoids whose cardinalities are irrational numbers. The following example is fundamental:

2.6. Example. The groupoid of finite sets E has cardinality

$$|E| \;=\; \sum_{n\in\mathbb{N}} \frac{1}{|S_n|} \;=\; \sum_{n\in\mathbb{N}} \frac{1}{n!} \;=\; e.$$

With the concept of groupoid cardinality in hand, we now describe how to obtain a vector in $\mathbb{R}^{\underline{X}}$ from a sufficiently nice groupoid over X.

2.7. Definition. *Given a groupoid X, a* **groupoid over** *X is a groupoid Ψ equipped with a functor $v\colon \Psi \to X$.*

2.8. Definition. *Given a groupoid over X, say $v\colon \Psi \to X$, and an object $x \in X$, we define the* **full inverse image** *of x, denoted $v^{-1}(x)$, to be the groupoid where:*

- *an object is an object $a \in \Psi$ such that $v(a) \cong x$;*
- *a morphism $f\colon a \to a'$ is any morphism in Ψ from a to a'.*

2.9. Definition. *A groupoid over X, say $v\colon \Psi \to X$, is* **tame** *if the groupoid $v^{-1}(x)$ is tame for all $x \in X$.*

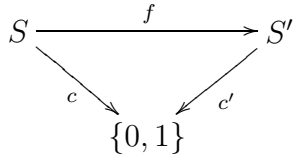
We sometimes loosely say that Ψ is a tame groupoid over X. When we do this, we are referring to a functor $v\colon \Psi \to X$ that is tame in the above sense. We do not mean that Ψ is tame as a groupoid.

2.10. Definition. *Given a tame groupoid over X, say $v\colon \Psi \to X$, there is a vector $\Psi \in \mathbb{R}^{\underline{X}}$ defined by:*

$$\Psi([x]) = |v^{-1}(x)|.$$

As discussed in Section 1, the theory of generating functions gives many examples of this construction. Here is one:

2.11. Example. Let Ψ be the groupoid of 2-colored finite sets. An object of Ψ is a '2-colored finite set': that is a finite set S equipped with a function $c : S \to 2$, where $2 = \{0, 1\}$. A morphism of Ψ is a function between 2-colored finite sets preserving the 2-coloring: that is, a commutative diagram of this sort:



There is a forgetful functor $v\colon \Psi \to E$ sending any 2-colored finite set $c\colon S \to 2$ to its underlying set S. It is a fun exercise to check that for any n-element set, say n for short, the groupoid $v^{-1}(n)$ is equivalent to the weak quotient $2^n//S_n$, where 2^n is the set of functions $c : n \to 2$ and the permutation group S_n acts on this set in the obvious way. It follows that

$$\underset{\sim}{\Psi}(n) = |v^{-1}(n)| = |2^n//S_n| = 2^n/n!$$

so the corresponding power series is

$$\underset{\sim}{\Psi} = \sum_{n\in\mathbb{N}} \frac{2^n}{n!} z^n = e^{2z} \in \mathbb{R}[[z]].$$

We call this the **generating function** of $v\colon \Psi \to E$, and indeed it is the usual generating function for 2-colored sets. Note that the $n!$ in the denominator, often regarded as a convention, arises naturally from the use of groupoid cardinality.

Both addition and scalar multiplication of vectors have groupoidified analogues. We can add two groupoids Φ, Ψ over X by taking their coproduct, i.e., the disjoint union of Φ and Ψ with the obvious map to X:

$$\begin{array}{c} \Phi + \Psi \\ \big\downarrow \\ X \end{array}$$

We then have:

PROPOSITION. *Given tame groupoids Φ and Ψ over X,*

$$\underset{\sim}{\Phi + \Psi} = \underset{\sim}{\Phi} + \underset{\sim}{\Psi}.$$

PROOF. This will appear later as part of Lemma 5.4, which also considers infinite sums. ∎

We can also multiply a groupoid over X by a 'scalar'—that is, a fixed groupoid. Given a groupoid over X, say $v\colon \Phi \to X$, and a groupoid Λ, the cartesian product $\Lambda \times \Psi$ becomes a groupoid over X as follows:

$$\begin{array}{c} \Lambda \times \Psi \\ \big\downarrow{\scriptstyle v\pi_2} \\ X \end{array}$$

where $\pi_2\colon \Lambda \times \Psi \to \Psi$ is projection onto the second factor. We then have:

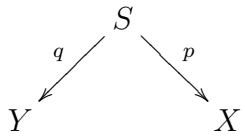
PROPOSITION. *Given a groupoid Λ and a groupoid Ψ over X, the groupoid $\Lambda \times \Psi$ over X satisfies*

$$\underset{\sim}{\Lambda \times \Psi} = |\Lambda| \underset{\sim}{\Psi}.$$

PROOF. This is proved as Proposition 6.3. ∎

We have seen how degroupoidification turns a groupoid X into a vector space $\mathbb{R}^{\underline{X}}$. Degroupoidification also turns any sufficiently nice span of groupoids into a linear operator.

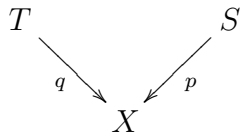
2.12. Definition. *Given groupoids X and Y, a* **span** *from X to Y is a diagram*



where S is groupoid and $p\colon S \to X$ and $q\colon S \to Y$ are functors.

To turn a span of groupoids into a linear operator, we need a construction called the 'weak pullback'. This construction will let us apply a span from X to Y to a groupoid over X to obtain a groupoid over Y. Then, since a tame groupoid over X gives a vector in $\mathbb{R}^{\underline{X}}$, while a tame groupoid over Y gives a vector in $\mathbb{R}^{\underline{Y}}$, a sufficiently nice span from X to Y will give a map from $\mathbb{R}^{\underline{X}}$ to $\mathbb{R}^{\underline{Y}}$. Moreover, this map will be linear.

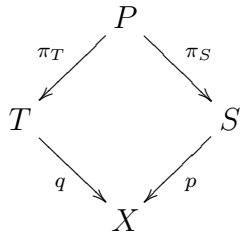
As a warmup for understanding weak pullbacks for groupoids, we recall ordinary pullbacks for sets, also called 'fibered products'. The data for constructing such a pullback is a pair of sets equipped with functions to the same set:



The pullback is the set

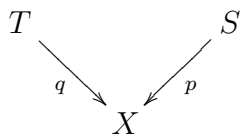
$$P = \{(s,t) \in S \times T \mid p(s) = q(t)\}$$

together with the obvious projections $\pi_S\colon P \to S$ and $\pi_T\colon P \to T$. The pullback makes this diamond commute:



and indeed it is the 'universal solution' to the problem of finding such a commutative diamond [30].

To generalize the pullback to groupoids, we need to weaken one condition. The data for constructing a weak pullback is a pair of groupoids equipped with functors to the same groupoid:



But now we replace the *equation* in the definition of pullback by a *specified isomorphism*. So, we define the weak pullback P to be the groupoid where an object is a triple (s, t, α) consisting of an object $s \in S$, an object $t \in T$, and an isomorphism $\alpha\colon p(s) \to q(t)$ in X. A morphism in P from (s, t, α) to (s', t', α') consists of a morphism $f\colon s \to s'$ in S and a morphism $g\colon t \to t'$ in T such that the following square commutes:

$$\begin{array}{ccc} p(s) & \xrightarrow{\alpha} & q(t) \\ {\scriptstyle p(f)}\downarrow & & \downarrow{\scriptstyle q(g)} \\ p(s') & \xrightarrow[\alpha']{} & q(t') \end{array}$$

Note that any set can be regarded as a **discrete** groupoid: one with only identity morphisms. For discrete groupoids, the weak pullback reduces to the ordinary pullback for sets. Using the weak pullback, we can apply a span from X to Y to a groupoid over X and get a groupoid over Y. Given a span of groupoids:

$$\begin{array}{ccccc} & & S & & \\ & {\scriptstyle q}\swarrow & & \searrow{\scriptstyle p} & \\ Y & & & & X \end{array}$$

and a groupoid over X:

$$\begin{array}{ccc} & & \Psi \\ & {\scriptstyle v}\swarrow & \\ X & & \end{array}$$

we can take the weak pullback, which we call $S\Psi$:

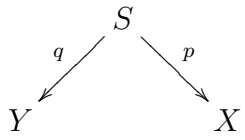
$$\begin{array}{ccccc} & & S\Psi & & \\ & {\scriptstyle \pi_S}\swarrow & & \searrow{\scriptstyle \pi_\Psi} & \\ & S & & & \Psi \\ {\scriptstyle q}\swarrow & & {\scriptstyle p}\searrow & {\scriptstyle v}\swarrow & \\ Y & & & X & \end{array}$$

and think of $S\Psi$ as a groupoid over Y:

$$\begin{array}{ccc} & & S\Psi \\ & {\scriptstyle q\pi_S}\swarrow & \\ Y & & \end{array}$$

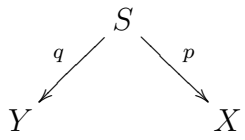
This process will determine a linear operator from $\mathbb{R}^{\underline{X}}$ to $\mathbb{R}^{\underline{Y}}$ if the span S is sufficiently nice:

2.13. DEFINITION. *A span*



is **tame** *if* $v\colon \Psi \to X$ *being tame implies that* $q\pi_S\colon S\Psi \to Y$ *is tame.*

THEOREM. *Given a tame span:*



there exists a unique linear operator

$$\underline{\underline{S}}\colon \mathbb{R}^{\underline{X}} \to \mathbb{R}^{\underline{Y}}$$

such that

$$\underline{\underline{S}}\underline{\underline{\Psi}} = \underline{\underline{S\Psi}}$$

whenever Ψ *is a tame groupoid over* X*.*

PROOF. This is Theorem 5.7. ∎

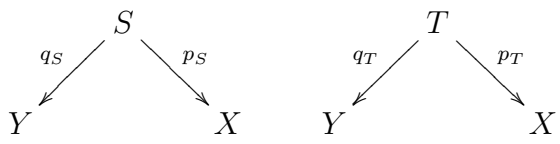
Theorem 5.10 provides an explicit criterion for when a span is tame. This theorem also gives an explicit formula for the the operator corresponding to a tame span S from X to Y. If $\underline{X}$ and $\underline{Y}$ are finite, then $\mathbb{R}^{\underline{X}}$ has a basis given by the isomorphism classes $[x]$ in X, and similarly for $\mathbb{R}^{\underline{Y}}$. With respect to these bases, the matrix entries of $\underline{\underline{S}}$ are given as follows:

$$\underline{\underline{S}}_{[y][x]} = \sum_{[s]\in \underline{p^{-1}(x)} \bigcap \underline{q^{-1}(y)}} \frac{|\mathrm{Aut}(x)|}{|\mathrm{Aut}(s)|} \tag{3}$$

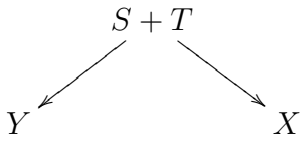
where $|\mathrm{Aut}(x)|$ is the set cardinality of the automorphism group of $x \in X$, and similarly for $|\mathrm{Aut}(s)|$. Even when $\underline{X}$ and $\underline{Y}$ are not finite, we have the following formula for $\underline{\underline{S}}$ applied to $\psi \in \mathbb{R}^{\underline{X}}$:

$$(\underline{\underline{S}}\psi)([y]) = \sum_{[x]\in\underline{X}} \sum_{[s]\in \underline{p^{-1}(x)} \bigcap \underline{q^{-1}(y)}} \frac{|\mathrm{Aut}(x)|}{|\mathrm{Aut}(s)|}\ \psi([x])\,. \tag{4}$$

As with vectors, there are groupoidified analogues of addition and scalar multiplication for operators. Given two spans from X to Y:



we can add them as follows. By the universal property of the coproduct we obtain from the right legs of the above spans a functor from the disjoint union $S+T$ to X. Similarly, from the left legs of the above spans, we obtain a functor from $S+T$ to Y. Thus, we obtain a span



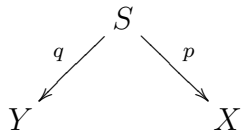
This addition of spans is compatible with degroupoidification:

PROPOSITION. *If S and T are tame spans from X to Y, then so is $S+T$, and*

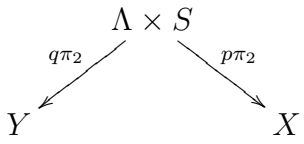
$$\underset{\sim}{S+T} = \underset{\sim}{S} + \underset{\sim}{T}.$$

PROOF. This is proved as Proposition 5.11. ∎

We can also multiply a span by a 'scalar': that is, a fixed groupoid. Given a groupoid Λ and a span

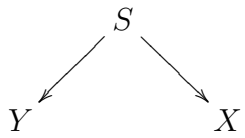


we can multiply them to obtain a span



Again, we have compatibility with degroupoidification:

PROPOSITION. *Given a tame groupoid Λ and a tame span*

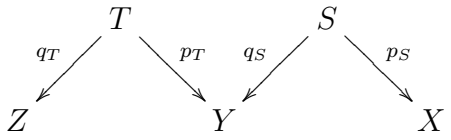


then $\Lambda \times S$ is tame and

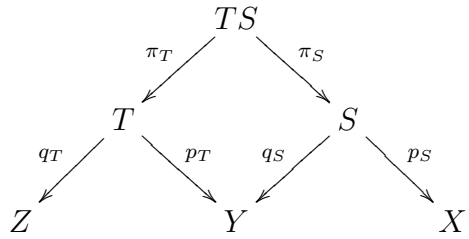
$$\underset{\sim}{\Lambda \times S} = |\Lambda|\, \underset{\sim}{S}.$$

PROOF. This is proved as Proposition 6.4. ∎

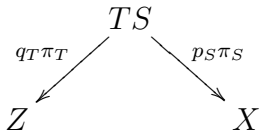
Next we turn to the all-important process of *composing* spans. This is the groupoidified analogue of matrix multiplication. Suppose we have a span from X to Y and a span from Y to Z:



Then we say these spans are **composable**. In this case we can form a weak pullback in the middle:



which gives a span from X to Z:



called the **composite** TS.

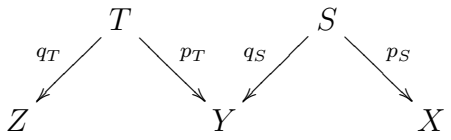
When all the groupoids involved are discrete, the spans S and T are just matrices of sets, as explained in Section 1. We urge the reader to check that in this case, the process of composing spans is really just matrix multiplication, with cartesian product of sets taking the place of multiplication of numbers, and disjoint union of sets taking the place of addition:

$$(TS)^k_j = \coprod_{j \in Y} T^k_j \times S^j_i.$$

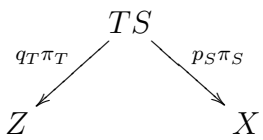
So, composing spans of groupoids is a generalization of matrix multiplication, with weak pullback playing the role of summing over the repeated index j in the formula above.

So, it should not be surprising that degroupoidification sends a composite of tame spans to the composite of their corresponding operators:

PROPOSITION. *If S and T are composable tame spans:*



then the composite span



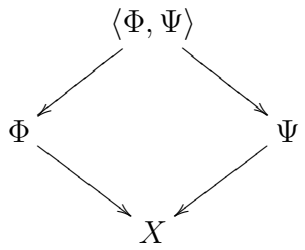
is also tame, and

$$\underset{\sim}{T}\underset{\sim}{S} = \underset{\sim}{T}\underset{\sim}{S}.$$

PROOF. This is proved as Lemma 6.9. ∎

Besides addition and scalar multiplication, there is an extra operation for groupoids over a groupoid X, which is the reason groupoidification is connected to quantum mechanics. Namely, we can take their inner product:

2.14. DEFINITION. *Given groupoids Φ and Ψ over X, we define the* **inner product** $\langle \Phi, \Psi \rangle$ *to be this weak pullback:*



2.15. DEFINITION. *A groupoid Ψ over X is called* **square-integrable** *if $\langle \Psi, \Psi \rangle$ is tame. We define $L^2(X)$ to be the subspace of $\mathbb{R}^{\underline{X}}$ consisting of finite real linear combinations of vectors $\underline{\Psi}$ where Ψ is square-integrable.*

Note that $L^2(X)$ is all of $\mathbb{R}^{\underline{X}}$ when $\underline{X}$ is finite. The inner product of groupoids over X makes $L^2(X)$ into a real Hilbert space:

THEOREM. *Given a groupoid X, there is a unique inner product $\langle \cdot, \cdot \rangle$ on the vector space $L^2(X)$ such that*

$$\langle \underline{\Phi}, \underline{\Psi} \rangle = |\langle \Phi, \Psi \rangle|$$

whenever Φ and Ψ are square-integrable groupoids over X. With this inner product $L^2(X)$ is a real Hilbert space.

PROOF. This is proven later as Theorem 6.11. ∎

We can always complexify $L^2(X)$ and obtain a complex Hilbert space. We work with real coefficients simply to admit that groupoidification as described here does not make essential use of the complex numbers. Morton's generalization involving groupoids over U(1) is one way to address this issue [33].

The inner product of groupoids over X has the properties one would expect:

PROPOSITION. *Given a groupoid Λ and square-integrable groupoids Φ, Ψ, and Ψ' over X, we have the following equivalences of groupoids:*

1.

$$\langle \Phi, \Psi \rangle \simeq \langle \Psi, \Phi \rangle.$$

2.

$$\langle \Phi, \Psi + \Psi' \rangle \simeq \langle \Phi, \Psi \rangle + \langle \Phi, \Psi' \rangle.$$

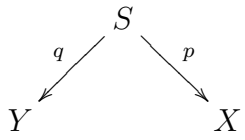
3.

$$\langle \Phi, \Lambda \times \Psi \rangle \simeq \Lambda \times \langle \Phi, \Psi \rangle.$$

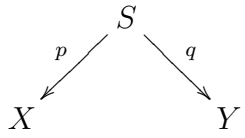
PROOF. Here equivalence of groupoids is defined in the usual way—see Definition A.7. This result is proved below as Proposition 6.15. ∎

Just as we can define the adjoint of an operator between Hilbert spaces, we can define the adjoint of a span of groupoids:

2.16. DEFINITION. *Given a span of groupoids from X to Y:*

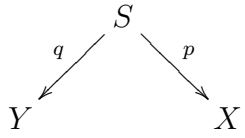


its **adjoint** *$S^\dagger$ is the following span of groupoids from Y to X:*



We warn the reader that the adjoint of a tame span may not be tame, due to an asymmetry in the criterion for tameness, Theorem 5.10. But of course a span of finite groupoids is tame, and so is its adjoint. Moreover, we have:

PROPOSITION. *Given a span*



and a pair $v\colon \Psi \to X$, $w\colon \Phi \to Y$ of groupoids over X and Y, respectively, there is an equivalence of groupoids

$$\langle \Phi, S\Psi \rangle \simeq \langle S^\dagger \Phi, \Psi \rangle.$$

PROOF. This is proven as Proposition 6.12. ∎

We say what it means for spans to be 'equivalent' in Definition A.12. Equivalent tame spans give the same linear operator: $S \simeq T$ implies $\underset{\sim}{S} = \underset{\sim}{T}$. Spans of groupoids obey many of the basic laws of linear algebra—up to equivalence. For example, we have these familiar properties of adjoints:

PROPOSITION. *Given spans*

and a groupoid Λ*, we have the following equivalences of spans:*

1. $(TS)^\dagger \simeq S^\dagger T^\dagger$
2. $(S+T)^\dagger \simeq S^\dagger + T^\dagger$
3. $(\Lambda S)^\dagger \simeq \Lambda S^\dagger$

PROOF. These will follow easily after we show addition and composition of spans and scalar multiplication are well defined. ∎

In fact, degroupoidification is a functor

$$\_\sim : \text{Span} \to \text{Vect}$$

where Vect is the category of real vector spaces and linear operators, and Span is a category with

- groupoids as objects,
- equivalence classes of tame spans as morphisms,

where composition comes from the method of composing spans we have just described. We prove this fact in Theorem 6.6. A deeper approach, which we shall explain elsewhere, is to think of Span as a weak 2-category (i.e., bicategory) with:

- groupoids as objects,
- tame spans as morphisms,
- isomorphism classes of maps of spans as 2-morphisms

Then degroupoidification becomes a functor between weak 2-categories:

$$\_\sim : \text{Span} \to \text{Vect}$$

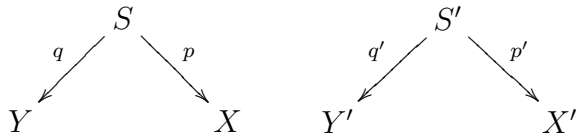
where Vect is viewed as a weak 2-category with only identity 2-morphisms. So, groupoidification is not merely a way of replacing linear algebraic structures involving the real numbers with purely combinatorial structures. It is also a form of 'categorification' [3], where we take structures defined in the category Vect and find analogues that live in the weak 2-category Span.

We could go even further and think of Span as a weak 3-category with

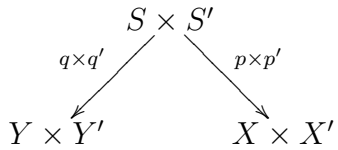
- groupoids as objects,
- tame spans as morphisms,
- maps of spans as 2-morphisms,
- maps of maps of spans as 3-morphisms.

However, we have not yet found a use for this further structure.

Lastly we would like to say a few words about tensors and traces. We can define the **tensor product** of groupoids X and Y to be their cartesian product $X \times Y$, and the **tensor product** of spans



to be the span



Defining the tensor product of maps of spans in a similar way, we conjecture that Span actually becomes a *symmetric monoidal* weak 2-category [32]. If this is true, then degroupoidification should be a 'lax symmetric monoidal functor', thanks to the natural map

$$\mathbb{R}^{\underline{X}} \otimes \mathbb{R}^{\underline{Y}} \to \mathbb{R}^{\underline{X \times Y}}.$$

The word 'lax' refers to the fact that this map is not an isomorphism of vector spaces unless either X or Y has finitely many isomorphism classes of objects. In the next section we present an alternative approach to degroupoidification that avoids this problem. The idea is simple: instead of working with the vector space $\mathbb{R}^{\underline{X}}$ consisting of all functions on $\underline{X}$, we work with the vector space $\mathbb{R}[\underline{X}]$ having $\underline{X}$ as its basis. Then we have

$$\mathbb{R}[\underline{X}] \otimes \mathbb{R}[\underline{Y}] \cong \mathbb{R}[\underline{X \times Y}].$$

In fact both approaches to groupoidification have their own advantages, and they are closely related, since

$$\mathbb{R}^{\underline{X}} \cong \mathbb{R}[\underline{X}]^*.$$

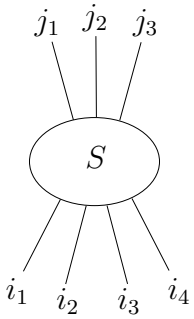
Regardless of these nuances, the important thing about the 'monoidal' aspect of degroupoidification is that it lets us mimic all the usual manipulations for tensors with groupoids replacing vector spaces. Physicists call a linear map

$$S \colon V_1 \otimes \cdots \otimes V_m \to W_1 \otimes \cdots \otimes W_n$$

a **tensor**, and denote it by an expression

$$S^{j_1 \cdots j_n}_{i_1 \cdots i_m}$$

with one subscript for each 'input' vector space $V_1, \ldots, V_m$, and one superscript for each 'output' vector space $W_1, \ldots, W_n$. In the traditional approach to tensors, these indices label bases of the vector spaces in question. Then the expression $S^{j_1 \cdots j_n}_{i_1 \cdots i_m}$ stands for an array of numbers: the components of the tensor S with respect to the chosen bases. This lets us describe various operations on tensors by multiplying such expressions and summing over indices that appear repeatedly, once as a superscript and once as a subscript. In the more modern 'string diagram' approach, these indices are simply names of input and output wires for a black box labelled S:

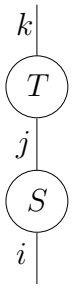


Here we are following physics conventions, where inputs are at the bottom and outputs are at the top. In this approach, when an index appears once as a superscript and once as a subscript, it means we attach an output wire of one black box to an input of another.

The most famous example is matrix multiplication:

$$(TS)^k_i = T^k_j S^j_i.$$

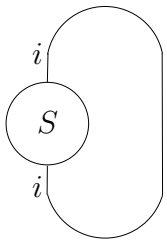
Here is the corresponding string diagram:



Another famous example is the trace of a linear operator $S \colon V \to V$, which is the sum of its diagonal entries:

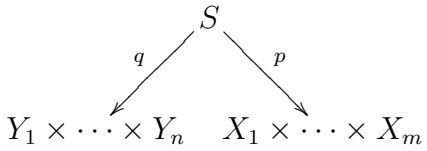
$$\mathrm{tr}(S) = S^i_i$$

As a string diagram, this looks like:



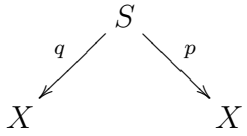
Here the sum is only guaranteed to converge if V is finite-dimensional, and indeed the full collection of tensor operations is defined only for finite-dimensional vector spaces.

All these ideas work just as well with spans of groupoids



taking the place of tensors. The idea is that *weak pullback takes the place of summation over repeated indices*. Even better, there is no need to impose any finiteness or tameness conditions until we degroupoidify.

We have already seen the simplest example: composition of spans via weak pullback is a generalization of matrix multiplication. For a trickier one, emphasized by Urs Schreiber [39], consider the trace of a span:



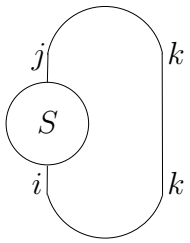
Here it is a bit hard to see which weak pullback to do! We can get around this problem using an alternate formula for the trace of a linear map $S\colon V \to V$:

$$\mathrm{tr}(S) = g_{jk} S_i^j g^{ik} \tag{5}$$

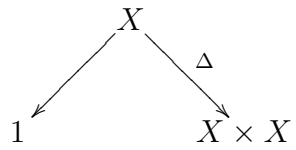
Here g_{jk} is the tensor corresponding to an arbitrary inner product $g\colon V \otimes V \to \mathbb{R}$. In the finite-dimensional case, any such inner product determines an isomorphism $V \cong V^*$, so we can interpret the adjoint of g as a linear map $\tilde{g}\colon \mathbb{R} \to V \otimes V$, and the tensor for this is customarily written as g with superscripts: g^{ik}. Equation 5 says that the operator

$$\mathbb{R} \xrightarrow{\tilde{g}} V \otimes V \xrightarrow{S \otimes 1} V \otimes V \xrightarrow{g} \mathbb{R}$$

is multiplication by $\mathrm{tr}(S)$. We can draw g as a 'cup' and $\tilde{g}$ as a 'cap', giving this string diagram:



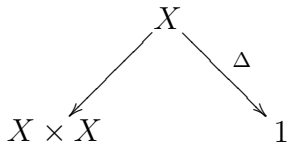
Now let us see how to implement this formula for the trace at the groupoidified level, to define the trace of a span of groupoids. Any groupoid X automatically comes equipped with a span



where Δ is the diagonal map and the left-hand arrow is the unique functor to the **terminal groupoid**—that is, the groupoid 1 with one object and one morphism. We can check that at least when $\underline{X}$ is finite, degroupoidifying this span gives an operator

$$\begin{array}{rccc} g\colon & \mathbb{R}^{\underline{X}} \otimes \mathbb{R}^{\underline{X}} & \to & \mathbb{R} \\ & \phi \otimes \psi & \mapsto & \langle \phi, \psi \rangle \end{array}$$

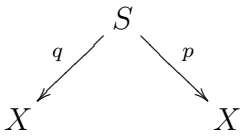
corresponding to the already described inner product on $\mathbb{R}^{\underline{X}}$. Similarly, the span



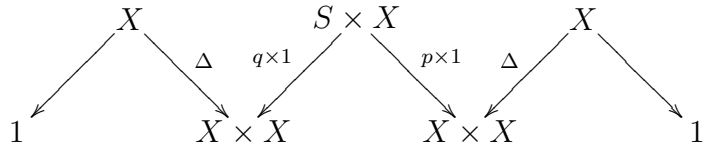
degroupoidifies to give the operator

$$\tilde{g}\colon \mathbb{R} \to \mathbb{R}^{\underline{X}} \otimes \mathbb{R}^{\underline{X}}.$$

So, to implement Equation 5 at the level of groupoids and define the trace of this span:

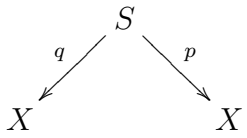


we should take the composite of these three spans:



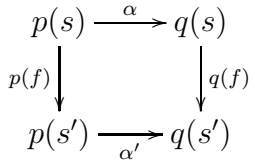
The result is a span from 1 to 1, whose apex is a groupoid we define to be the **trace** $\mathrm{tr}(S)$. We leave it as an exercise to check the following basic properties of the trace:

PROPOSITION. *Given a span of groupoids*



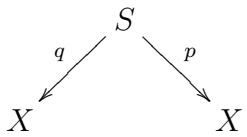
its trace $\mathrm{tr}(S)$ *is equivalent to the groupoid for which:*

- *an object is a pair* (s, α) *consisting of an object* $s \in S$ *and a morphism* $\alpha\colon p(s) \to q(s)$*;*
- *a morphism from* (s, α) *to* (s', α') *is a morphism* $f\colon s \to s'$ *such that*



  commutes.

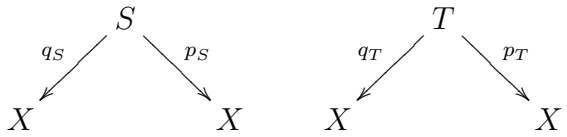
PROPOSITION. *Given a span of groupoids*



where $\underline{X}$ *is finite, we have*

$$|\mathrm{tr}(S)| = \mathrm{tr}(\underline{S}).$$

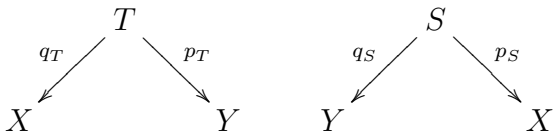
PROPOSITION. *Given spans of groupoids*



and a groupoid Λ*, we have the following equivalences of groupoids:*

1. $\mathrm{tr}(S + T) \simeq \mathrm{tr}(S) + \mathrm{tr}(T)$
2. $\mathrm{tr}(\Lambda \times S) \simeq \Lambda \times \mathrm{tr}(S)$

PROPOSITION. *Given spans of groupoids*



we have an equivalence of groupoids

$$\mathrm{tr}(ST) \simeq \mathrm{tr}(TS).$$

We could go even further generalizing ideas from vector spaces and linear operators to groupoids and spans, but at this point the reader is probably hungry for some concrete applications. For these, proceed directly to Section 4. Section 3 can be skipped on first reading, since we need it only for the application to Hall algebras in Section 4.4.

3. Homology versus Cohomology

The work we have described so far has its roots in the cohomology of groupoids. Any groupoid X can be turned into a topological space, namely the geometric realization of its nerve [16], and we can define the cohomology of X to be the cohomology of this space. The set of connected components of this space is just the set of isomorphism classes of X, which we have denoted $\underline{X}$. So, the **zeroth cohomology** of the groupoid X, with real coefficients, is precisely the vector space $\mathbb{R}^{\underline{X}}$ that we have been calling the degroupoidification of X.

Indeed, one reason degroupoidification has been overlooked until recently is that every groupoid is equivalent to a disjoint union of one-object groupoids, which we may think of as groups. To turn a groupoid into a topological space it suffices to do this for each of these groups and then take the disjoint union. The space associated to a group G is quite famous: it is the Eilenberg–Mac Lane space $K(G, 1)$. Similarly, the cohomology of groups is a famous and well-studied subject. But the zeroth cohomology of a group is always just $\mathbb{R}$. So, zeroth cohomology is not considered interesting. Zeroth cohomology only becomes interesting when we move from groups to groupoids—and then only when we consider how a tame span of groupoids induces a map on zeroth cohomology.

These reflections suggest an alternate approach to degroupoidification based on homology instead of cohomology:

3.1. DEFINITION. *Given a groupoid X, let the* **zeroth homology** *of X be the real vector space with the set $\underline{X}$ as basis. We denote this vector space as $\mathbb{R}[\underline{X}]$.*

We can also think of $\mathbb{R}[\underline{X}]$ as the space of real-valued functions on $\underline{X}$ with finite support. This makes it clear that the zeroth homology $\mathbb{R}[\underline{X}]$ can be identified with a subspace of the zeroth cohomology $\mathbb{R}^{\underline{X}}$. If X has finitely many isomorphism classes of objects, then the set $\underline{X}$ is finite, and the zeroth homology and zeroth cohomology are canonically isomorphic. For a groupoid with infinitely many isomorphism classes, however, the difference becomes important. The following example makes this clear:

3.2. Example. Let E be the groupoid of finite sets and bijections. In Example 2.3 we saw that

$$\mathbb{R}^{\underline{E}} \;\cong\; \{\psi\colon \mathbb{N} \to \mathbb{R}\} \;\cong\; \mathbb{R}[[z]].$$

So, elements of $\mathbb{R}[\underline{E}]$ may be identified with formal power series with only finitely many nonzero coefficients. But these are just polynomials:

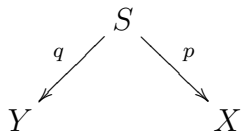
$$\mathbb{R}[\underline{E}] \;\cong\; \mathbb{R}[z].$$

Before pursuing a version of degroupoidification based on homology, we should ask if there are other choices built into our recipe for degroupoidification that we can change. The answer is yes. Recalling Equation 4, which describes the operator associated to a tame span:

$$(\underline{S}\psi)([y]) = \sum_{[x]\in\underline{X}} \sum_{[s]\in\underline{p^{-1}(x)}\bigcap\underline{q^{-1}(y)}} \frac{|\mathrm{Aut}(x)|}{|\mathrm{Aut}(s)|}\; \psi([x])\,.$$

one might wonder about the asymmetry of this formula. Specifically, one might wonder why this formula uses information about $\mathrm{Aut}(x)$ but not $\mathrm{Aut}(y)$. The answer is that we made an arbitrary choice of conventions. There is another equally nice choice, and in fact an entire family of choices interpolating between these two:

3.3. Proposition. *Given $\alpha \in \mathbb{R}$ and a tame span of groupoids:*



there is a linear operator called its **α-degroupoidification***:*

$$\underset{\sim}{S_\alpha}\colon \mathbb{R}^{\underline{X}} \to \mathbb{R}^{\underline{Y}}$$

given by:

$$(\underset{\sim}{S_\alpha}\psi)([y]) = \sum_{[x]\in\underline{X}} \sum_{[s]\in\underline{p^{-1}(x)}\bigcap\underline{q^{-1}(y)}} \frac{|\mathrm{Aut}(x)|^{1-\alpha}|\mathrm{Aut}(y)|^{\alpha}}{|\mathrm{Aut}(s)|}\; \psi([x])\,.$$

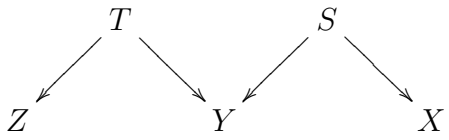
Proof. The only thing that needs to be checked is that the sums converge for any fixed choice of $y \in Y$. This follows from our explicit criterion for tameness of spans, Theorem 5.10. ∎

The most interesting choices of α are $\alpha = 0$, $\alpha = 1$, and the symmetrical choice $\alpha = 1/2$. The last convention has the advantage that for a tame span S with tame adjoint $S^\dagger$, the matrix for the degroupoidification of $S^\dagger$ is just the transpose of that for S. We can show:

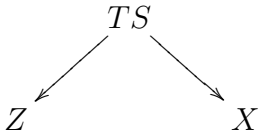
3.4. Proposition. *For any $\alpha \in \mathbb{R}$ there is a functor from the category of groupoids and equivalence classes of tame spans to the category of real vector spaces and linear operators, sending:*

- *each groupoid X to its zeroth cohomology $\mathbb{R}^{\underline{X}}$, and*
- *each tame span S from X to Y to the operator $\underset{\sim}{S_\alpha} \colon \mathbb{R}^{\underline{X}} \to \mathbb{R}^{\underline{Y}}$.*

In particular, if we have composable tame spans:



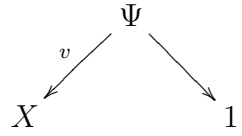
then their composite



is again tame, and

$$\underset{\sim}{(TS)_\alpha} = \underset{\sim}{T_\alpha}\underset{\sim}{S_\alpha}.$$

We omit the proof because it mimics that of Theorem 6.6. Note that a groupoid Ψ over X can be seen as a special case of a span, namely a span

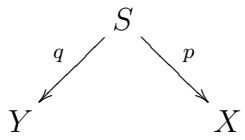


where 1 is the terminal groupoid—that is, the groupoid with one object and one morphism. So, α-degroupoidification also gives a recipe for turning Ψ into a vector in $\mathbb{R}^{\underline{X}}$:

$$\underset{\sim}{\Psi_\alpha}[x] = |\mathrm{Aut}(x)|^\alpha |v^{-1}(x)|\,. \tag{6}$$

This idea yields the following result as a special case of Proposition 3.4:

3.5. Proposition. *Given a tame span:*



and a tame groupoid over X, say $v\colon \Psi \to X$, then $\underset{\sim}{(S\Psi)}_\alpha = \underset{\sim}{S}_\alpha \underset{\sim}{\Psi}_\alpha$

Equation 6 also implies that we can compensate for a different choice of α by doing a change of basis. So, our choice of α is merely a matter of convenience. More precisely:

3.6. Proposition. *Regardless of the value of $\alpha \in \mathbb{R}$, the functors in Proposition 3.4 are all naturally isomorphic.*

Proof. Given $\alpha, \beta \in \mathbb{R}$, Equation 6 implies that

$$\underset{\sim}{\Psi}_\alpha[x] = |\mathrm{Aut}(x)|^{\alpha-\beta} \underset{\sim}{\Psi}_\beta[x]$$

for any tame groupoid Ψ over a groupoid X. So, for any groupoid X, define a linear operator

$$T_X\colon \mathbb{R}[\underline{X}] \to \mathbb{R}[\underline{X}]$$

by

$$(T_X\psi)([x]) = |\mathrm{Aut}(x)|^{\alpha-\beta}\psi([x]).$$

We thus have

$$\underset{\sim}{\Psi}_\alpha = T_X \underset{\sim}{\Psi}_\beta.$$

By Proposition 3.5, for any tame span S from X to Y and any tame groupoid Ψ over X we have

$$\begin{aligned} T_Y \underset{\sim}{S}_\alpha \underset{\sim}{\Psi}_\alpha &= T_Y \underset{\sim}{(S\Psi)}_\alpha \\ &= \underset{\sim}{(S\Psi)}_\beta \\ &= \underset{\sim}{S}_\beta \underset{\sim}{\Psi}_\beta \\ &= \underset{\sim}{S}_\beta T_X \underset{\sim}{\Psi}_\alpha \end{aligned}$$

Since this is true for all such Ψ, this implies

$$T_Y \underset{\sim}{S}_\alpha = \underset{\sim}{S}_\beta T_X.$$

So, T defines a natural isomorphism between α-degroupoidification and β-degroupoidification.

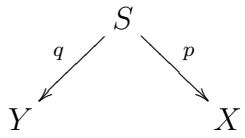
∎

Now let us return to homology. We can also do α-degroupoidification using zeroth homology instead of zeroth cohomology. Recall that while the zeroth cohomology of X consists of all real-valued functions on $\underline{X}$, the zeroth homology consists of such functions *with finite support*. So, we need to work with groupoids over X that give functions of this type:

3.7. Definition. *A groupoid Ψ over X is* **finitely supported** *if it is tame and $\underset{\sim}{\Psi}$ is a finitely supported function on $\underline{X}$.*

Similarly, we must use spans of groupoids that give linear operators preserving this finite support property:

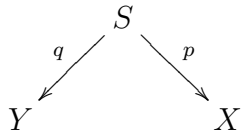
3.8. Definition. *A span:*



is of **finite type** *if it is a tame span of groupoids and for any finitely supported groupoid Ψ over X, the groupoid $S\Psi$ over Y (formed by weak pullback) is also finitely supported.*

With these definitions, we can refine the previous propositions so they apply to zeroth homology:

3.9. Proposition. *Given any fixed real number α and a span of finite type:*



there is a linear operator called its **α-degroupoidification***:*

$$\underset{\sim}{S_\alpha} \colon \mathbb{R}[\underline{X}] \to \mathbb{R}[\underline{Y}]$$

given by:

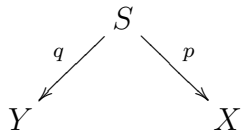
$$\underset{\sim}{S_\alpha}[x] = \sum_{[y] \in \underline{Y}} \sum_{[s] \in \underline{p^{-1}(x)} \bigcap \underline{q^{-1}(y)}} \frac{|\mathrm{Aut}(x)|^{1-\alpha} |\mathrm{Aut}(y)|^\alpha}{|\mathrm{Aut}(s)|} \; [y] \,.$$

3.10. Proposition. *For any $\alpha \in \mathbb{R}$ there is a functor from the category of groupoids and equivalence classes of spans of finite type to the category of real vector spaces and linear operators, sending:*

- *each groupoid X to its zeroth homology $\mathbb{R}[\underline{X}]$, and*
- *each span S of finite type from X to Y to the operator $\underset{\sim}{S_\alpha} \colon \mathbb{R}[\underline{X}] \to \mathbb{R}[\underline{Y}]$.*

Moreover, for all values of $\alpha \in \mathbb{R}$, these functors are naturally isomorphic.

3.11. Proposition. *Given a span of finite type:*



and a finitely supported groupoid over X, say $v\colon \Psi \to X$, then $S\Psi$ is a finitely supported groupoid over Y, and $\underset{\sim}{(S\Psi)_\alpha} = \underset{\sim}{S_\alpha}\underset{\sim}{\Psi_\alpha}$.

The moral of this section is that we have several choices to make before we apply degroupoidification to any specific example. The choice of α is merely a matter of convenience, but there is a real difference between homology and cohomology, at least for groupoids with infinitely many nonisomorphic objects. The process described in Section 2 is the combination of choosing to work with cohomology and the convention $\alpha = 0$ for degroupoidifying spans. This will suffice for the majority of this paper. However, we will use a different choice in our study of Hall algebras.

4. Groupoidification

Degroupoidification is a systematic process; groupoidification is the attempt to undo this process. The previous section explains degroupoidification—but not why groupoidification is interesting. The interest lies in its applications to concrete examples. So, let us sketch three: Feynman diagrams, Hecke algebras, and Hall algebras.

4.1. Feynman Diagrams. One of the first steps in developing quantum theory was Planck's new treatment of electromagnetic radiation. Classically, electromagnetic radiation in a box can be described as a collection of harmonic oscillators, one for each vibrational mode of the field in the box. Planck 'quantized' the electromagnetic field by assuming that the energy of each oscillator could only take discrete, evenly spaced values: if by fiat we say the lowest possible energy is 0, the allowed energies take the form $n\hbar\omega$, where n is any natural number, ω is the frequency of the oscillator in question, and $\hbar$ is Planck's constant.

Planck did not know what to make of the number n, but Einstein and others later interpreted it as the number of 'quanta' occupying the vibrational mode in question. However, far from being particles in the traditional sense of tiny billiard balls, quanta are curiously abstract entities—for example, all the quanta occupying a given mode are indistinguishable from each other.

In a modern treatment, states of a quantized harmonic oscillator are described as vectors in a Hilbert space called 'Fock space'. This Hilbert space consists of formal power series. For a full treatment of the electromagnetic field we would need power series in many variables, one for each vibrational mode. But to keep things simple, let us consider power series in one variable. In this case, the vector $z^n/n!$ describes a state in which n quanta are present. A general vector in Fock space is a convergent linear combination

of these special vectors. More precisely, the **Fock space** consists of $\psi \in \mathbb{C}[[z]]$ with $\langle \psi, \psi \rangle < \infty$, where the inner product is given by

$$\left\langle \sum a_n z^n \,,\, \sum b_n z^n \right\rangle \;=\; \sum n!\; \overline{a}_n b_n \,. \tag{7}$$

But what is the meaning of this inner product? It is precisely the inner product in $L^2(E)$, where E is the groupoid of finite sets! This is no coincidence. In fact, there is a deep relationship between the mathematics of the quantum harmonic oscillator and the combinatorics of finite sets. This relation suggests a program of *groupoidifying* mathematical tools from quantum theory, such as annihilation and creation operators, field operators and their normal-ordered products, Feynman diagrams, and so on. This program was initiated by Dolan and one of the current authors [4]. Later, it was developed much further by Morton [33]. Guta and Maassen [17] and Aguiar and Maharam [1] have also done relevant work. Here we just sketch some of the basic ideas.

First, let us see why the inner product on Fock space matches the inner product on $L^2(E)$ as described in Theorem 6.11. We can compute the latter inner product using a convenient basis. Let Ψ_n be the groupoid with n-element sets as objects and bijections as morphisms. Since all n-element sets are isomorphic and each one has the permutation group S_n as automorphisms, we have an equivalence of groupoids

$$\Psi_n \simeq 1 /\!/ S_n.$$

Furthermore, Ψ_n is a groupoid over E in an obvious way:

$$v \colon \Psi_n \to E.$$

We thus obtain a vector $\Psi_n \in \mathbb{R}^{\underline{E}}$ following the rule described in Definition 2.10. We can describe this vector as a formal power series using the isomorphism

$$\mathbb{R}^{\underline{E}} \cong \mathbb{R}[[z]]$$

described in Example 2.3. To do this, note that

$$v^{-1}(m) \simeq \begin{cases} 1 /\!/ S_n & m = n \\ 0 & m \neq n \end{cases}$$

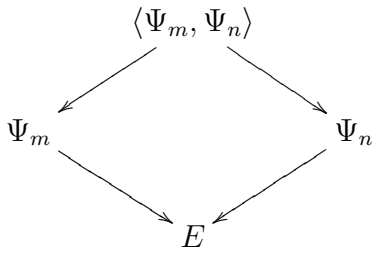
where 0 stands for the empty groupoid. It follows that

$$|v^{-1}(m)| = \begin{cases} 1/n! & m = n \\ 0 & m \neq n \end{cases}$$

and thus

$$\Psi_n = \sum_{m \in \mathbb{N}} |v^{-1}(m)|\, z^m = \frac{z^n}{n!}.$$

Next let us compute the inner product in $L^2(E)$. Since finite linear combinations of vectors of the form Ψ_n are dense in $L^2(E)$ it suffices to compute the inner product of two vectors of this form. We can use the recipe in Theorem 6.11. So, we start by taking the weak pullback of the corresponding groupoids over E:



An object of this weak pullback consists of an m-element set S, an n-element set T, and a bijection $\alpha \colon S \to T$. A morphism in this weak pullback consists of a commutative square of bijections:

$$\begin{array}{ccc} S & \xrightarrow{\alpha} & T \\ {\scriptstyle f}\downarrow & & \downarrow{\scriptstyle g} \\ S' & \xrightarrow[\alpha']{} & T' \end{array}$$

So, there are no objects in $\langle \Psi_m, \Psi_n \rangle$ when $n \neq m$. When $n = m$, all objects in this groupoid are isomorphic, and each one has $n!$ automorphisms. It follows that

$$\langle \underset{\sim}{\Psi}_m, \underset{\sim}{\Psi}_n \rangle = |\langle \Psi_m, \Psi_n \rangle| = \begin{cases} 1/n! & m = n \\ 0 & m \neq n \end{cases}$$

Using the fact that $\underset{\sim}{\Psi}_n = z^n/n!$, we see that this is precisely the inner product in Equation 7. So, as a complex Hilbert space, Fock space is the complexification of $L^2(E)$.

It is worth reflecting on the meaning of the computation we just did. The vector $\underset{\sim}{\Psi}_n = z^n/n!$ describes a state of the quantum harmonic oscillator in which n quanta are present. Now we see that this vector arises from the groupoid Ψ_n over E. In Section 1 we called a groupoid over E a **stuff type**, since it describes a way of equipping finite sets with extra stuff. The stuff type Ψ_n is a very simple special case, where the stuff is simply 'being an n-element set'. So, groupoidification reveals the mysterious 'quanta' to be simply elements of finite sets. Moreover, the formula for the inner product on Fock space arises from the fact that there are $n!$ ways to identify two n-element sets.

The most important operators on Fock space are the annihilation and creation operators. If we think of vectors in Fock space as formal power series, the **annihilation operator** is given by

$$(a\psi)(z) = \frac{d}{dz}\psi(z)$$

while the **creation operator** is given by

$$(a^*\psi)(z) = z\psi(z).$$

As operators on Fock space, these are only densely defined: for example, they map the dense subspace $\mathbb{C}[z]$ to itself. However, we can also think of them as operators from $\mathbb{C}[[z]]$ to itself. In physics these operators decrease or increase the number of quanta in a state, since

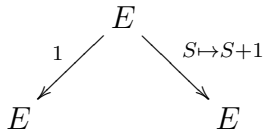
$$az^n = nz^{n-1}, \qquad a^* z^n = z^{n+1}.$$

Creating a quantum and then annihilating one is not the same as annihilating and then creating one, since

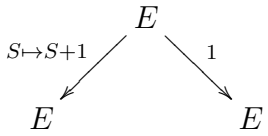
$$aa^* = a^* a + 1.$$

This is one of the basic examples of noncommutativity in quantum theory.

The annihilation and creation operators arise from spans by degroupoidification, using the recipe described in Theorem 5.7. The annihilation operator comes from this span:



where the left leg is the identity functor and the right leg is the functor 'disjoint union with a 1-element set'. Since it is ambiguous to refer to this span by the name of the groupoid on top, as we have been doing, we instead call it A. Similarly, we call its adjoint A^*:



A calculation [33] shows that indeed:

$$\underset{\sim}{A} = a, \qquad \underset{\sim}{A}^* = a^*.$$

Moreover, we have an equivalence of spans:

$$AA^* \simeq A^* A + 1.$$

Here we are using composition of spans, addition of spans and the identity span as defined in Section 2. If we unravel the meaning of this equivalence, it turns out to be very simple [4]. If you have an urn with n balls in it, there is one more way to put in a ball and then take one out than to take one out and then put one in. Why? Because in the first scenario there are $n + 1$ balls to choose from when you take one out, while in the second scenario there are only n. So, the noncommutativity of annihilation and creation operators is not a mysterious thing: it has a simple, purely combinatorial explanation.

We can go further and define a span

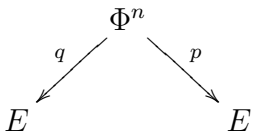
$$\Phi = A + A^*$$

which degroupoidifies to give the well-known **field operator**

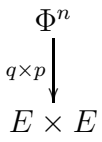
$$\phi = \underline{\Phi} = a + a^*$$

Our normalization here differs from the usual one in physics because we wish to avoid dividing by $\sqrt{2}$, but all the usual physics formulas can be adapted to this new normalization.

The powers of the span Φ have a nice combinatorial interpretation. If we write its nth power as follows:



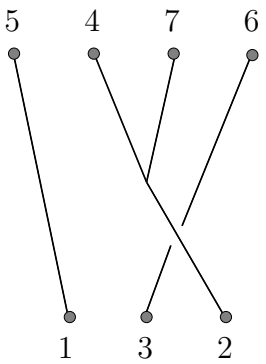
then we can reinterpret this span as a groupoid over $E \times E$:



Just as a groupoid over E describes a way of equipping a finite set with extra stuff, a groupoid over $E \times E$ describes a way of equipping a *pair* of finite sets with extra stuff. And in this example, the extra stuff in question is a very simple sort of diagram!

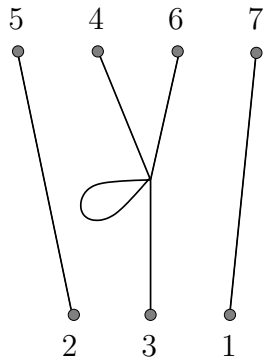
More precisely, we can draw an object of Φ^n as a i-element set S, a j-element set T, a graph with $i + j$ univalent vertices and a single n-valent vertex, together with a bijection between the $i + j$ univalent vertices and the elements of $S + T$. It is against the rules for vertices labelled by elements of S to be connected by an edge, and similarly for vertices labelled by elements of T. The functor $p \times q \colon \Phi^n \to E \times E$ sends such an object of Φ^n to the pair of sets $(S, T) \in E \times E$.

An object of Φ^n sounds like a complicated thing, but it can be depicted quite simply as a **Feynman diagram**. Physicists traditionally read Feynman diagrams from bottom to top. So, we draw the above graph so that the univalent vertices labelled by elements of S are at the bottom of the picture, and those labelled by elements of T are at the top. For example, here is an object of Φ^3, where $S = \{1, 2, 3\}$ and $T = \{4, 5, 6, 7\}$:



In physics, we think of this as a process where 3 particles come in and 4 go out.

Feynman diagrams of this sort are allowed to have **self-loops**: edges with both ends at the same vertex. So, for example, this is a perfectly fine object of Φ^5 with $S = \{1, 2, 3\}$ and $T = \{4, 5, 6, 7\}$:



To eliminate self-loops, we can work with the **normal-ordered powers** or 'Wick powers' of Φ, denoted $:\Phi^n:$. These are the spans obtained by taking Φ^n, expanding it in terms of the annihilation and creation operators, and moving all the annihilation operators to the right of all the creation operators 'by hand', ignoring the fact that they do not commute. For example:

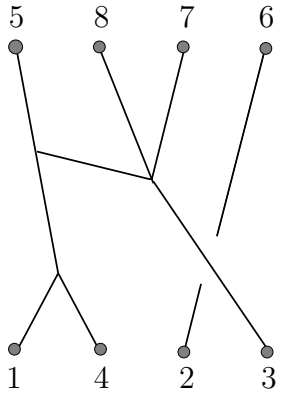
$$\begin{aligned} :\Phi^0: &= 1 \\ :\Phi^1: &= A + A^* \\ :\Phi^2: &= A^2 + 2A^*A + A^{*2} \\ :\Phi^3: &= A^3 + 3A^*A^2 + 3A^{*2}A + A^{*3} \end{aligned}$$

and so on. Objects of $:\Phi^n:$ can be drawn as Feynman diagrams just as we did for objects of Φ^n. There is just one extra rule: self-loops are not allowed.

In quantum field theory one does many calculations involving products of normal-ordered powers of field operators. Feynman diagrams make these calculations easy. In the groupoidified context, a product of normal-ordered powers is a span

$$\begin{array}{ccccc} & & :\Phi^{n_1}: \ \cdots \ :\Phi^{n_k}: & & \\ & \swarrow^{q} & & \searrow^{p} & \\ E & & & & E\,. \end{array}$$

As before, we can draw an object of the groupoid $:\Phi^{n_1}: \ \cdots \ :\Phi^{n_k}:$ as a Feynman diagram. But now these diagrams are more complicated, and closer to those seen in physics textbooks. For example, here is a typical object of $:\Phi^3::\Phi^3::\Phi^4:$, drawn as a Feynman diagram:



In general, a **Feynman diagram** for an object of $:\Phi^{n_1}: \cdots :\Phi^{n_k}:$ consists of an i-element set S, a j-element set T, a graph with k vertices of valence $n_1, \ldots, n_k$ together with $i + j$ univalent vertices, and a bijection between these univalent vertices and the elements of $S + T$. Self-loops are forbidden; it is against the rules for two vertices labelled by elements of S to be connected by an edge, and similarly for two vertices labelled by elements of T. As before, the forgetful functor $p \times q$ sends any such object to the pair of sets $(S, T) \in E \times E$.

The groupoid $:\Phi^{n_1}: \cdots :\Phi^{n_k}:$ also contains interesting automorphisms. These come from *symmetries* of Feynman diagrams: that is, graph automorphisms fixing the univalent vertices labelled by elements of S and T. These symmetries play an important role in computing the operator corresponding to this span:

$$\begin{array}{ccccc} & & :\Phi^{n_1}: \cdots :\Phi^{n_k}: & & \\ & {\scriptstyle q}\swarrow & & \searrow{\scriptstyle p} & \\ E & & & & E\,. \end{array}$$

As is evident from Theorem 5.10, when a Feynman diagram has symmetries, we need to divide by the number of symmetries when determining its contribution to the operator coming from the above span. This rule is well-known in quantum field theory; here we see it arising as a natural consequence of groupoid cardinality.

4.2. Hecke Algebras. Here we sketch how to groupoidify a Hecke algebra when the parameter q is a power of a prime number and the finite reflection group comes from a Dynkin diagram in this way. More details will appear in future work [2].

Let D be a Dynkin diagram. We write $d \in D$ to mean that d is a dot in this diagram. Associated to each unordered pair of dots $d, d' \in D$ is a number $m_{dd'} \in \{2, 3, 4, 6\}$. In the usual Dynkin diagram conventions:

- $m_{dd'} = 2$ is drawn as no edge at all,
- $m_{dd'} = 3$ is drawn as a single edge,
- $m_{dd'} = 4$ is drawn as a double edge,

- $m_{dd'} = 6$ is drawn as a triple edge.

For any nonzero number q, our Dynkin diagram gives a Hecke algebra. Since we are using real vector spaces in this paper, we work with the Hecke algebra over $\mathbb{R}$:

4.3. Definition. *Let D be a Dynkin diagram and q a nonzero real number. The* **Hecke algebra** *$H(D, q)$ corresponding to this data is the associative algebra over $\mathbb{R}$ with one generator σ_d for each $d \in D$, and relations:*

$$\sigma_d^2 = (q-1)\sigma_d + q$$

for all $d \in D$, and

$$\sigma_d \sigma_{d'} \sigma_d \cdots = \sigma_{d'} \sigma_d \sigma_{d'} \cdots$$

for all $d, d' \in D$, where each side has $m_{dd'}$ factors.

Hecke algebras are q-deformations of finite reflection groups, also known as Coxeter groups [20]. Any Dynkin diagram gives rise to a simple Lie group, and the Weyl group of this simple Lie algebra is a Coxeter group. To begin understanding Hecke algebras, it is useful to note that when $q = 1$, the Hecke algebra is simply the group algebra of the **Coxeter group** associated to D: that is, the group with one generator s_d for each dot $d \in D$, and relations

$$s_d^2 = 1, \qquad (s_d s_{d'})^{m_{dd'}} = 1.$$

So, the Hecke algebra can be thought of as a q-deformation of this Coxeter group.

If q is a power of a prime number, the Dynkin diagram D determines a simple algebraic group G over the field with q elements, $\mathbb{F}_q$. We choose a Borel subgroup $B \subseteq G$, i.e., a maximal solvable subgroup. This in turn determines a transitive G-set $X = G/B$. This set is a smooth algebraic variety called the **flag variety** of G, but we only need the fact that it is a finite set equipped with a transitive action of the finite group G. Starting from just this G-set X, we can groupoidify the Hecke algebra $H(D, q)$.

Recalling the concept of 'action groupoid' from Section 1, we define the **groupoidified Hecke algebra** to be

$$(X \times X)//G.$$

This groupoid has one isomorphism class of objects for each G-orbit in $X \times X$:

$$\underline{(X \times X)//G} \cong (X \times X)/G.$$

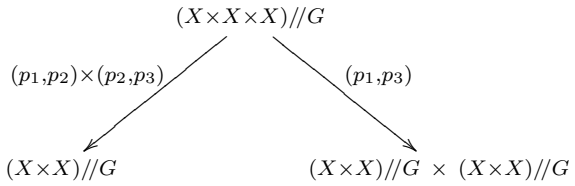
The well-known 'Bruhat decomposition' [9] of X/G shows there is one such orbit for each element of the Coxeter group associated to D. Since the Hecke algebra has a standard basis given by elements of the Coxeter group [20], it follows that $(X \times X)//G$ degroupoidifies to give the underlying vector space of the Hecke algebra. In other words, we obtain an isomorphism of vector spaces

$$\mathbb{R}^{(X \times X)/G} \cong H(D, q).$$

Even better, we can groupoidify the *multiplication* in the Hecke algebra. In other words, we can find a span that degroupoidifies to give the linear operator

$$\begin{array}{ccc} H(D,q) \otimes H(D,q) & \to & H(D,q) \\ a \otimes b & \mapsto & ab \end{array}$$

This span is very simple:



(8)

where p_i is projection onto the ith factor.

For a proof that this span degroupoidifies to give the desired linear operator, see [18]. The key is that for each dot $d \in D$ there is a special isomorphism class in $(X \times X)//G$, and the function

$$\psi_d \colon (X \times X)/G \to \mathbb{R}$$

that equals 1 on this isomorphism class and 0 on the rest corresponds to the generator $\sigma_d \in H(D,q)$.

To illustrate these ideas, let us consider the simplest nontrivial example, the Dynkin diagram A_2:

The Hecke algebra associated to A_2 has two generators, which we call P and L, for reasons soon to be revealed:

$$P = \sigma_1, \qquad L = \sigma_2.$$

The relations are

$$P^2 = (q-1)P + q, \qquad L^2 = (q-1)P + q, \qquad PLP = LPL.$$

It follows that this Hecke algebra is a quotient of the group algebra of the 3-strand braid group, which has two generators P and L and one relation $PLP = LPL$, called the **Yang–Baxter equation** or **third Reidemeister move**. This is why Jones could use traces on the A_n Hecke algebras to construct invariants of knots [21]. This connection to knot theory makes it especially interesting to groupoidify Hecke algebras.

So, let us see what the groupoidified Hecke algebra looks like, and where the Yang–Baxter equation comes from. The algebraic group corresponding to the A_2 Dynkin diagram and the prime power q is $G = \mathrm{SL}(3, \mathbb{F}_q)$, and we can choose the Borel subgroup B to consist of upper triangular matrices in $\mathrm{SL}(3, \mathbb{F}_q)$. Recall that a **complete flag** in the vector space $\mathbb{F}_q^3$ is a pair of subspaces

$$0 \subset V_1 \subset V_2 \subset \mathbb{F}_q^3.$$

The subspace V_1 must have dimension 1, while V_2 must have dimension 2. Since G acts transitively on the set of complete flags, while B is the subgroup stabilizing a chosen flag, the flag variety $X = G/B$ in this example is just the set of complete flags in $\mathbb{F}_q^3$—hence its name.

We can think of $V_1 \subset \mathbb{F}_q^3$ as a point in the projective plane $\mathbb{F}_q\mathrm{P}^2$, and $V_2 \subset \mathbb{F}_q^3$ as a line in this projective plane. From this viewpoint, a complete flag is a chosen point lying on a chosen line in $\mathbb{F}_q\mathrm{P}^2$. This viewpoint is natural in the theory of 'buildings', where each Dynkin diagram corresponds to a type of geometry [10, 15]. Each dot in the Dynkin diagram then stands for a 'type of geometrical figure', while each edge stands for an 'incidence relation'. The A_2 Dynkin diagram corresponds to projective plane geometry. The dots in this diagram stand for the figures 'point' and 'line':

$$\text{point} \bullet \!\!-\!\!-\!\!-\!\!-\!\!\bullet \text{ line}$$

The edge in this diagram stands for the incidence relation 'the point p lies on the line ℓ'.

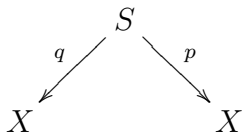
We can think of P and L as special elements of the A_2 Hecke algebra, as already described. But when we groupoidify the Hecke algebra, P and L correspond to *objects* of $(X \times X)/\!/G$. Let us describe these objects and explain how the Hecke algebra relations arise in this groupoidified setting.

As we have seen, an isomorphism class of objects in $(X \times X)/\!/G$ is just a G-orbit in $X \times X$. These orbits in turn correspond to spans of G-sets from X to X that are **irreducible**: that is, not a coproduct of other spans of G-sets. So, the objects P and L can be defined by giving irreducible spans of G-sets:

$$\begin{tikzcd} & P \arrow[dl] \arrow[dr] & \\ X & & X \end{tikzcd} \qquad \begin{tikzcd} & L \arrow[dl] \arrow[dr] & \\ X & & X \end{tikzcd}$$

In general, any span of G-sets

$$\begin{tikzcd} & S \arrow[dl, "q"'] \arrow[dr, "p"] & \\ X & & X \end{tikzcd}$$



such that $q \times p \colon S \to X \times X$ is injective can be thought of as G-invariant binary relation between elements of X. Irreducible G-invariant spans are always injective in this sense. So, such spans can also be thought of as G-invariant relations between flags. In these terms, we define P to be the relation that says two flags have the same line, but different points:

$$P = \{((p, \ell), (p', \ell)) \in X \times X \mid p \neq p'\}$$

Similarly, we think of L as a relation saying two flags have different lines, but the same point:

$$L = \{((p, \ell), (p, \ell')) \in X \times X \mid \ell \neq \ell'\}.$$

Given this, we can check that

$$P^2 \cong (q-1) \times P + q \times 1, \qquad L^2 \cong (q-1) \times L + q \times 1, \qquad PLP \cong LPL.$$

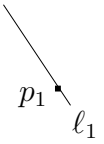
Here both sides refer to spans of G-sets, and we denote a span by its apex. Addition of spans is defined using coproduct, while 1 denotes the identity span from X to X. We use 'q' to stand for a fixed q-element set, and similarly for '$q-1$'. We compose spans of G-sets using the ordinary pullback. It takes a bit of thought to check that this way of composing spans of G-sets matches the product described by Equation 8, but it is indeed the case [18].

To check the existence of the first two isomorphisms above, we just need to count. In $\mathbb{F}_q\mathrm{P}^2$, the are $q+1$ points on any line. So, given a flag we can change the point in q different ways. To change it again, we have a choice: we can either send it back to the original point, or change it to one of the $q-1$ other points. So, $P^2 \cong (q-1)\times P + q \times 1$. Since there are also $q+1$ lines through any point, similar reasoning shows that $L^2 \cong (q-1)\times L + q \times 1$.

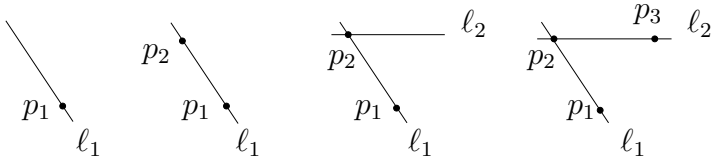
The Yang–Baxter isomorphism

$$PLP \cong LPL$$

is more interesting. We construct it as follows. First consider the left-hand side, PLP. So, start with a complete flag called (p_1, ℓ_1):

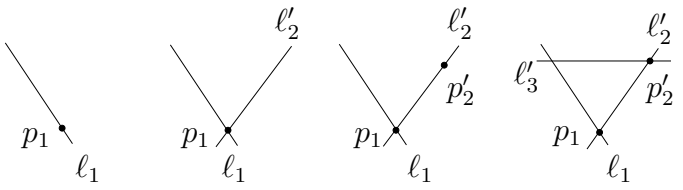


Then, change the point to obtain a flag (p_2, ℓ_1). Next, change the line to obtain a flag (p_2, ℓ_2). Finally, change the point once more, which gives us the flag (p_3, ℓ_2):



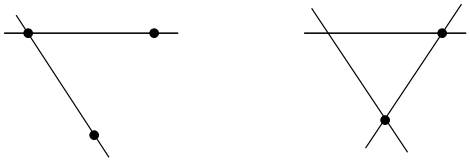
The figure on the far right is a typical element of PLP.

On the other hand, consider LPL. So, start with the same flag as before, but now change the line, obtaining (p_1, ℓ_2'). Next change the point, obtaining the flag (p_2', ℓ_2'). Finally, change the line once more, obtaining the flag (p_2', ℓ_3'):



The figure on the far right is a typical element of LPL.

Now, the axioms of projective plane geometry say that any two distinct points lie on a unique line, and any two distinct lines intersect in a unique point. So, any figure of the sort shown on the left below determines a unique figure of the sort shown on the right, and vice versa:



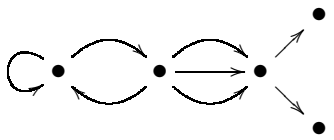
Comparing this with the pictures above, we see this bijection induces an isomorphism of spans $PLP \cong LPL$. So, we have derived the Yang–Baxter isomorphism from the axioms of projective plane geometry!

To understand groupoidified Hecke algebras, it is important to keep straight the two roles played by spans. On the one hand, objects of the groupoidified Hecke algebra $(X \times X)//G$ can be described as certain spans from X to X, namely the injective G-invariant ones. Multiplying these objects then corresponds to composing spans. On the other hand, Equation 8 gives a span describing the multiplication in $(X \times X)//G$. In fact, this span describes the process of composing spans. If this seems hopelessly confusing, remember that any matrix describes a linear operator, but there is also a linear operator describing the process of matrix multiplication. We are only groupoidifying that idea.

Other approaches to categorified Hecke algebras and their representations have been studied by a number of authors, building on Kazhdan–Lusztig theory [24]. One key step was Soergel's introduction of what are nowadays called Soergel bimodules [36, 42]. Also important were Khovanov's categorification of the Jones polynomial [25] and the work by Bernstein, Frenkel, Khovanov and Stroppel on categorifying Temperley–Lieb algebras, which are quotients of the type A Hecke algebras [7, 38]. A diagrammatic interpretation of the Soergel bimodule category was developed by Elias and Khovanov [12], and a geometric approach led Webster and Williamson [44] to deep applications in knot homology theory. This geometric interpretation can be seen as going beyond the simple form of groupoidification we consider here, and considering groupoids in the category of schemes.

4.4. Hall Algebras. The Hall algebra of a quiver is a very natural example of groupoidification, and a very important one, since it lets us groupoidify 'half of a quantum group'. However, to obtain the usual formula for the Hall algebra product, we need to exploit one of the alternative conventions explained in Section 3. In this section we begin by quickly reviewing the usual theory of Hall algebras and their relation to quantum groups [19, 41]. Then we explain how to groupoidify a Hall algebra.

We start by fixing a finite field $\mathbb{F}_q$ and a directed graph D, which might look like this:



We shall call the category Q freely generated by D a **quiver**. The objects of Q are the vertices of D, while the morphisms are edge paths, with paths of length zero serving as identity morphisms.

By a **representation** of the quiver Q we mean a functor

$$R\colon Q \to \mathrm{FinVect}_q,$$

where $\mathrm{FinVect}_q$ is the category of finite-dimensional vector spaces over $\mathbb{F}_q$. Such a representation simply assigns a vector space $R(d) \in \mathrm{FinVect}_q$ to each vertex of D and a linear operator $R(e)\colon R(d) \to R(d')$ to each edge e from d to d'. By a **morphism** between representations of Q we mean a natural transformation between such functors. So, a morphism $\alpha\colon R \to S$ assigns a linear operator $\alpha_d\colon R(d) \to S(d)$ to each vertex d of D, in such a way that

$$\begin{array}{ccc} R(d) & \xrightarrow{R(e)} & R(d') \\ {\scriptstyle \alpha_d}\downarrow & & \downarrow{\scriptstyle \alpha_{d'}} \\ S(d) & \xrightarrow[S(d)]{} & S(d') \end{array}$$

commutes for any edge e from d to d'. There is a category $\mathrm{Rep}(Q)$ where the objects are representations of Q and the morphisms are as above. This is an abelian category, so we can speak of indecomposable objects, short exact sequences, etc. in this category.

In 1972, Gabriel [14] discovered a remarkable fact. Namely: a quiver has finitely many isomorphism classes of indecomposable representations if and only if its underlying graph, ignoring the orientation of edges, is a finite disjoint union of Dynkin diagrams of type A, D or E. These are called **simply laced** Dynkin diagrams.

Henceforth, for simplicity, we assume the underlying graph of our quiver Q is a simply laced Dynkin diagram when we ignore the orientations of its edges. Let X be the underlying groupoid of $\mathrm{Rep}(Q)$: that is, the groupoid with representations of Q as objects and *isomorphisms* between these as morphisms. We will use this groupoid to construct the Hall algebra of Q.

As a vector space, the Hall algebra is just $\mathbb{R}[\underline{X}]$. Remember from Section 3 that this is the vector space whose basis consists of isomorphism classes of objects in X. In fancier language, it is the zeroth homology of X. So, we should use the homology approach to degroupoidification, instead of the cohomology approach used in our examples so far.

We now focus our attention on the Hall algebra product. Given three quiver representations M, N, and E, we define:

$$\mathcal{P}_{MN}^{E} = \{(f,g) : 0 \to N \xrightarrow{f} E \xrightarrow{g} M \to 0 \ \text{ is exact}\}.$$

The Hall algebra product counts these exact sequences, but with a subtle 'correction factor':

$$[M] \cdot [N] = \sum_{E \in \underline{X}} \frac{|\mathcal{P}^E_{MN}|}{|\mathrm{Aut}(M)|\,|\mathrm{Aut}(N)|}\,[E]\,.$$

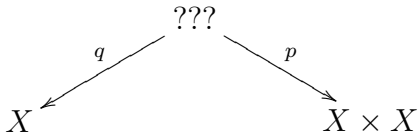
All the cardinalities in this formula are ordinary *set* cardinalities.

Somewhat suprisingly, the above product is associative. In fact, Ringel [34] showed that the resulting algebra is isomorphic to the positive part $U_q^+\mathfrak{g}$ of the quantum group corresponding to our simply laced Dynkin diagram! So, roughly speaking, the Hall algebra of a simply laced quiver is 'half of a quantum group'.

Since the Hall algebra product can be seen as a linear operator

$$\begin{array}{ccc} \mathbb{R}[\underline{X}] \otimes \mathbb{R}[\underline{X}] & \to & \mathbb{R}[\underline{X}] \\ a \otimes b & \mapsto & a \cdot b \end{array}$$

it is natural to seek a span of groupoids



that gives this operator. Indeed, there is a very natural span that gives this product. This will allow us to groupoidify the algebra $U_q^+\mathfrak{g}$.

We start by defining a groupoid $\mathrm{SES}(Q)$ to serve as the apex of this span. An object of $\mathrm{SES}(Q)$ is a short exact sequence in $\mathrm{Rep}(Q)$, and a morphism from

$$0 \to N \xrightarrow{f} E \xrightarrow{g} M \to 0$$

to

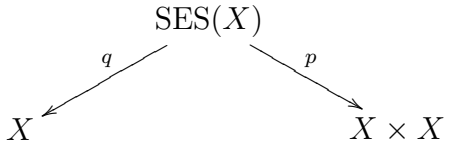
$$0 \to N' \xrightarrow{f'} E' \xrightarrow{g'} M' \to 0$$

is a commutative diagram

$$\begin{array}{ccccccccc} 0 & \longrightarrow & N & \xrightarrow{f} & E & \xrightarrow{g} & M & \longrightarrow & 0 \\ & & \downarrow{\scriptstyle \alpha} & & \downarrow{\scriptstyle \beta} & & \downarrow{\scriptstyle \gamma} & & \\ 0 & \longrightarrow & N' & \xrightarrow{f'} & E' & \xrightarrow{g'} & M' & \longrightarrow & 0 \end{array}$$

where α, β, and γ are isomorphisms of quiver representations.

Next, we define the span

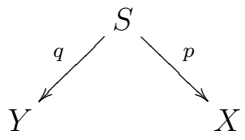


where p and q are given on objects by

$$\begin{aligned} p(0 \to N \xrightarrow{f} E \xrightarrow{g} M \to 0) &= (M, N) \\ q(0 \to N \xrightarrow{f} E \xrightarrow{g} M \to 0) &= E \end{aligned}$$

and defined in the natural way on morphisms. This span captures the idea behind the standard Hall algebra multiplication. Given two quiver representations M and N, this span relates them to every representation E that is an extension of M by N.

Before we degroupoidify this span, we need to decide on a convention. It turns out that the correct choice is α-degroupoidification with $\alpha = 1$, as described in Section 3. Recall from Proposition 3.9 that a span of finite type



yields an operator

$$\underset{\sim}{S_1} \colon \mathbb{R}[\underline{X}] \to \mathbb{R}[\underline{Y}]$$

given by:

$$\underset{\sim}{S_1}[x] = \sum_{[y] \in \underline{Y}} \sum_{[s] \in \underline{p^{-1}(x)} \bigcap \underline{q^{-1}(y)}} \frac{|\mathrm{Aut}(y)|}{|\mathrm{Aut}(s)|} \, [y] \,.$$

We can rewrite this using groupoid cardinality as follows:

$$\underset{\sim}{S_1}[x] = \sum_{[y] \in \underline{Y}} |\mathrm{Aut}(y)| \, |(p \times q)^{-1}(x, y)| \, [y] \,.$$

Applying this procedure to the span with $\mathrm{SES}(Q)$ as its apex, we get an operator

$$m \colon \mathbb{R}[\underline{X}] \otimes \mathbb{R}[\underline{X}] \to \mathbb{R}[\underline{X}]$$

with

$$m([M] \otimes [N]) = \sum_{E \in \mathcal{P}^E_{MN}} |\mathrm{Aut}(E)| \, |(p \times q)^{-1}(M, N, E)| \, [E].$$

We wish to show this matches the Hall algebra product $[M] \cdot [N]$.

For this, we must make a few observations. First, we note that the group $\mathrm{Aut}(N) \times \mathrm{Aut}(E) \times \mathrm{Aut}(M)$ acts on the set $\mathcal{P}^E_{MN}$. This action is not necessarily free, but this is just the sort of situation groupoid cardinality is designed to handle. Taking the weak quotient, we obtain a groupoid equivalent to the groupoid where objects are short exact sequences of the form $0 \to N \to E \to M \to 0$ and morphisms are isomorphisms of short

exact sequences. So, the weak quotient is equivalent to the groupoid $(p \times q)^{-1}(M, N, E)$. Remembering that groupoid cardinality is preserved under equivalence, we see:

$$\begin{aligned} |(p \times q)^{-1}(M, N, E)| &= |\mathcal{P}^E_{MN} /\!/ (\mathrm{Aut}(N) \times \mathrm{Aut}(E) \times \mathrm{Aut}(M))| \\ &= \frac{|\mathcal{P}^E_{MN}|}{|\mathrm{Aut}(N)|\,|\mathrm{Aut}(E)|\,|\mathrm{Aut}(M)|}. \end{aligned}$$

So, we obtain

$$m([M] \otimes [N]) = \sum_{E \in \mathcal{P}^E_{MN}} \frac{|\mathcal{P}^E_{MN}|}{|\mathrm{Aut}(M)|\,|\mathrm{Aut}(N)|}\ [E].$$

which is precisely the Hall algebra product $[M] \cdot [N]$.

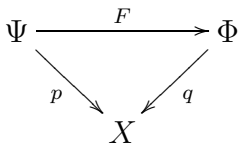
We can define a coproduct on $\mathbb{R}[\underline{X}]$ using the the adjoint of the span that gives the product. Unfortunately this coproduct does not make the Hall algebra into a bialgebra (and thus not a Hopf algebra). Ringel discovered how to fix this problem by 'twisting' the product and coproduct [35]. The resulting twisted Hall algebra is isomorphic *as a Hopf algebra* to $U_q^+\mathfrak{g}$. This adjustment also removes the dependency on the direction of the arrows in our original directed graph. We hope to groupoidify this construction in future work.

5. Degroupoidifying a Tame Span

In Section 2 we described a process for turning a tame span of groupoids into a linear operator. In this section we show this process is well-defined. The calculations in the proof yield an explicit criterion for when a span is tame. They also give an explicit formula for the the operator coming from a tame span. As part of our work, we also show that equivalent spans give the same operator.

5.1. Tame Spans Give Operators. To prove that a tame span gives a well-defined operator, we begin with three lemmas that are of some interest in themselves. We postpone to Appendix A some well-known facts about groupoids that do not involve the concept of degroupoidification. This Appendix also recalls the familiar concept of 'equivalence' of groupoids, which serves as a basis for this:

5.2. Definition. *Two groupoids over a fixed groupoid X, say $v\colon \Psi \to X$ and $w\colon \Phi \to X$, are* **equivalent** *as groupoids over X if there is an equivalence $F\colon \Psi \to \Phi$ such that this diagram*



commutes up to natural isomorphism.

5.3. LEMMA. *Let $v\colon \Psi \to X$ and $w\colon \Phi \to X$ be equivalent groupoids over X. If either one is tame, then both are tame, and $\underset{\sim}{\Psi} = \underset{\sim}{\Phi}$.*

PROOF. This follows directly from Lemmas A.13 and A.14 in Appendix A. ∎

5.4. LEMMA. *Given tame groupoids Φ and Ψ over X,*

$$\underset{\sim}{\Phi + \Psi} = \underset{\sim}{\Phi} + \underset{\sim}{\Psi}.$$

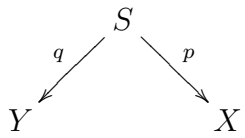
More generally, given any collection of tame groupoids Ψ_i over X, the coproduct $\sum_i \Psi_i$ is naturally a groupoid over X, and if it is tame, then

$$\underset{i}{\sum}\, \Psi_i = \sum_i \underset{\sim}{\Psi}_i$$

where the sum on the right hand side converges pointwise as a function on $\underline{X}$.

PROOF. The full inverse image of any object $x \in X$ in the coproduct $\sum_i \Psi_i$ is the coproduct of its fulll inverse images in each groupoid Ψ_i. Since groupoid cardinality is additive under coproduct, the result follows. ∎

5.5. LEMMA. *Given a span of groupoids*



we have

1. $S(\sum_i \Psi_i) \simeq \sum_i S\Psi_i$
2. $S(\Lambda \times \Psi) \simeq \Lambda \times S\Psi$

whenever $v_i\colon \Psi_i \to X$ are groupoids over X, $v\colon \Psi \to X$ is a groupoid over X, and Λ is a groupoid.

PROOF. To prove 1, we need to describe a functor

$$F\colon \sum_i S\Psi_i \to S(\sum_i \Psi_i)$$

that will provide our equivalence. For this, we simply need to describe for each i a functor $F_i\colon S\Psi_i \to S(\sum_i \Psi_i)$. An object in $S\Psi_i$ is a triple (s, z, α) where $s \in S$, $z \in \Psi_i$ and $\alpha\colon p(s) \to v_i(z)$. F_i simply sends this triple to the same triple regarded as an object of $S(\sum_i \Psi_i)$. One can check that F extends to a functor and that this functor extends to an equivalence of groupoids over S.

To prove 2, we need to describe a functor $F\colon S(\Lambda \times \Phi) \to \Lambda \times S\Phi$. This functor simply re-orders the entries in the quadruples which define the objects in each groupoid. One can check that this functor extends to an equivalence of groupoids over X. ∎

Finally we need the following lemma, which simplifies the computation of groupoid cardinality:

5.6. LEMMA. *If X is a tame groupoid with finitely many objects in each isomorphism class, then*

$$|X| = \sum_{x \in X} \frac{1}{|\mathrm{Mor}(x, -)|}$$

where $\mathrm{Mor}(x, -) = \bigcup_{y \in X} \hom(x, y)$ *is the set of morphisms whose source is the object* $x \in X$.

PROOF. We check the following equalities:

$$\sum_{[x] \in \underline{X}} \frac{1}{|\mathrm{Aut}(x)|} = \sum_{[x] \in \underline{X}} \frac{|[x]|}{|\mathrm{Mor}(x, -)|} = \sum_{x \in X} \frac{1}{|\mathrm{Mor}(x, -)|}.$$

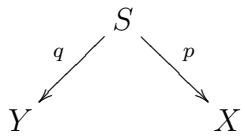
Here $[x]$ is the set of objects isomorphic to x, and $|[x]|$ is the ordinary cardinality of this set. To check the above equations, we first choose an isomorphism $\gamma_y \colon x \to y$ for each object y isomorphic to x. This gives a bijection from $[x] \times \mathrm{Aut}(x)$ to $\mathrm{Mor}(x, -)$ that takes $(y, f \colon x \to x)$ to $\gamma_y f \colon x \to y$. Thus

$$|[x]|\,|\mathrm{Aut}(x)| = |\mathrm{Mor}(x, -)|,$$

and the first equality follows. We also get a bijection between $\mathrm{Mor}(y, -)$ and $\mathrm{Mor}(x, -)$ that takes $f \colon y \to z$ to $f\gamma_y \colon x \to z$. Thus, $|\mathrm{Mor}(y, -)| = |\mathrm{Mor}(x, -)|$ whenever y is isomorphic to x. The second equation follows from this. ∎

Now we are ready to prove the main theorem of this section:

5.7. THEOREM. *Given a tame span of groupoids*



there exists a unique linear operator $\underline{\underline{S}} \colon \mathbb{R}^{\underline{X}} \to \mathbb{R}^{\underline{Y}}$ *such that* $\underline{\underline{S}}\,\underline{\Psi} = \underline{S\Psi}$ *for any vector* $\underline{\Psi}$ *obtained from a tame groupoid* Ψ *over* X.

PROOF. It is easy to see that these conditions uniquely determine $\underline{\underline{S}}$. Suppose $\psi \colon \underline{X} \to \mathbb{R}$ is any nonnegative function. Then we can find a groupoid Ψ over X such that $\underline{\Psi} = \psi$. So, $\underline{\underline{S}}$ is determined on nonnegative functions by the condition that $\underline{\underline{S}}\,\underline{\Psi} = \underline{S\Psi}$. Since every function is a difference of two nonnegative functions and $\underline{\underline{S}}$ is linear, this uniquely determines $\underline{\underline{S}}$.

The real work is proving that $\underline{\underline{S}}$ is well-defined. For this, assume we have a collection $\{v_i \colon \Psi_i \to X\}_{i \in I}$ of groupoids over X and real numbers $\{\alpha_i \in \mathbb{R}\}_{i \in I}$ such that

$$\sum_i \alpha_i \, \underline{\underline{\Psi_i}} = 0. \tag{9}$$

We need to show that

$$\sum_i \alpha_i \, \underset{\sim}{S\Psi_i} = 0. \tag{10}$$

We can simplify our task as follows. First, recall that a **skeletal** groupoid is one where isomorphic objects are equal. Every groupoid is equivalent to a skeletal one. Thanks to Lemmas 5.3 and A.16, we may therefore assume without loss of generality that S, X, Y and all the groupoids Ψ_i are skeletal.

Second, recall that a skeletal groupoid is a coproduct of groupoids with one object. By Lemma 5.4, degroupoidification converts coproducts of groupoids over X into sums of vectors. Also, by Lemma 5.5, the operation of taking weak pullback distributes over coproduct. As a result, we may assume without loss of generality that each groupoid Ψ_i has one object. Write $*_i$ for the one object of Ψ_i.

With these simplifying assumptions, Equation 9 says that for any $x \in X$,

$$0 = \sum_{i \in I} \alpha_i \, \underset{\sim}{\Psi_i}([x]) = \sum_{i \in I} \alpha_i \, |v_i^{-1}(x)| = \sum_{i \in J} \frac{\alpha_i}{|\mathrm{Aut}(*_i)|} \tag{11}$$

where J is the collection of $i \in I$ such that $v_i(*_i)$ is isomorphic to x. Since all groupoids in sight are now skeletal, this condition implies $v_i(*_i) = x$.

Now, to prove Equation 10, we need to show that

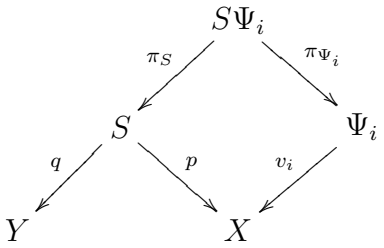
$$\sum_{i \in I} \alpha_i \, \underset{\sim}{S\Psi_i}([y]) = 0$$

for any $y \in Y$. But since the set I is partitioned into sets J, one for each $x \in X$, it suffices to show

$$\sum_{i \in J} \alpha_i \, \underset{\sim}{S\Psi_i}([y]) = 0. \tag{12}$$

for any fixed $x \in X$ and $y \in Y$.

To compute $\underset{\sim}{S\Psi_i}$, we need to take this weak pullback:



We then have

$$\underset{\sim}{S\Psi_i}([y]) = |(q\pi_S)^{-1}(y)|, \tag{13}$$

so to prove Equation 12 it suffices to show

$$\sum_{i \in J} \alpha_i \, |(q\pi_S)^{-1}(y)| = 0. \tag{14}$$

Using the definition of 'weak pullback', and taking advantage of the fact that Ψ_i has just one object, which maps down to x, we can see that an object of $S\Psi_i$ consists of an object $s \in S$ with $p(s) = x$ together with an isomorphism $\alpha\colon x \to x$. This object of $S\Psi_i$ lies in $(q\pi_S)^{-1}(y)$ precisely when we also have $q(s) = y$.

So, we may briefly say that an object of $(q\pi_S)^{-1}(y)$ is a pair (s, α), where $s \in S$ has $p(s) = x$, $q(s) = y$, and α is an element of $\mathrm{Aut}(x)$. Since S is skeletal, there is a morphism between two such pairs only if they have the same first entry. A morphism from (s, α) to (s, α') then consists of a morphism $f \in \mathrm{Aut}(s)$ and a morphism $g \in \mathrm{Aut}(*_i)$ such that

$$\begin{array}{ccc} x & \xrightarrow{\alpha} & x \\ {\scriptstyle p(f)}\downarrow & & \downarrow{\scriptstyle v_i(g)} \\ x & \xrightarrow[\alpha']{} & x \end{array}$$

commutes.

A morphism out of (s, α) thus consists of an arbitrary pair $f \in \mathrm{Aut}(s)$, $g \in \mathrm{Aut}(*_i)$, since these determine the target (s, α'). This fact and Lemma 5.6 allow us to compute:

$$\begin{aligned} |(q\pi_S)^{-1}(y)| &= \sum_{(s,\alpha)\in(q\pi_S)^{-1}(y)} \frac{1}{|\mathrm{Mor}((s,\alpha),-)|} \\ &= \sum_{s\in p^{-1}(y)\cap q^{-1}(y)} \frac{|\mathrm{Aut}(x)|}{|\mathrm{Aut}(s)||\mathrm{Aut}(*_i)|}\,. \end{aligned}$$

So, to prove Equation 14, it suffices to show

$$\sum_{i\in J} \sum_{s\in p^{-1}(x)\cap q^{-1}(y)} \frac{\alpha_i|\mathrm{Aut}(x)|}{|\mathrm{Aut}(s)||\mathrm{Aut}(*_i)|} = 0\,. \tag{15}$$

But this easily follows from Equation 11. So, the operator $\underset{\sim}{S}$ is well defined. ∎

In Definition A.12 we recall the natural concept of 'equivalence' for spans of groupoids. The next theorem says that our process of turning spans of groupoids into linear operators sends equivalent spans to the same operator:

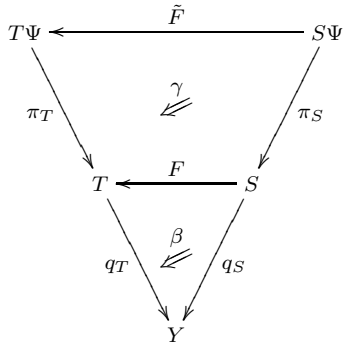
5.8. Theorem. *Given equivalent spans*

$$\begin{array}{ccccc} & & S & & \\ & {\scriptstyle q_S}\swarrow & & \searrow{\scriptstyle p_S} & \\ Y & & & & X \end{array} \qquad \begin{array}{ccccc} & & T & & \\ & {\scriptstyle q_T}\swarrow & & \searrow{\scriptstyle p_T} & \\ Y & & & & X \end{array}$$

the linear operators $\underset{\sim}{S}$ and $\underset{\sim}{T}$ are equal.

PROOF. Since the spans are equivalent, there is a functor providing an equivalence of groupoids $F\colon S \to T$ along with a pair of natural isomorphisms $\alpha\colon p_S \Rightarrow p_T F$ and $\beta\colon q_S \Rightarrow q_T F$. Thus, the diagrams

are equivalent pointwise. It follows from Lemma A.16 that the weak pullbacks $S\Psi$ and $T\Psi$ are equivalent groupoids with the equivalence given by a functor $\tilde{F}\colon S\Psi \to T\Psi$. From the universal property of weak pullbacks, along with F, we obtain a natural transformation $\gamma\colon F\pi_S \Rightarrow \pi_T\tilde{F}$. We then have a triangle

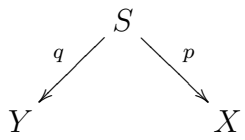


where the composite of γ and β is $(q_T{\cdot}\gamma)^{-1}\beta\colon q_S\pi_S \Rightarrow q_T\pi_T\tilde{F}$. Here $\cdot$ stands for whiskering: see Definition A.6.

We can now apply Lemma A.14. Thus, for every $y \in Y$, the full inverse images $(q_S\pi_S)^{-1}(y)$ and $(q_T\pi_T)^{-1}(y)$ are equivalent. It follows from Lemma A.13 that for each $y \in Y$, the groupoid cardinalities $|(q_S\pi_S)^{-1}(y)|$ and $|(q_T\pi_T)^{-1}(y)|$ are equal. Thus, the linear operators $\underset{\sim}{S}$ and $\underset{\sim}{T}$ are the same. ∎

5.9. AN EXPLICIT FORMULA. Our calculations in the proof of Theorem 5.7 yield an explicit formula for the operator coming from a tame span, and a criterion for when a span is tame:

5.10. THEOREM. *A span of groupoids*



is tame if and only if:

1. *For any object $y \in Y$, the groupoid $p^{-1}(x) \cap q^{-1}(y)$ is nonempty for objects x in only a finite number of isomorphism classes of X.*

2. For every $x \in X$ and $y \in Y$, the groupoid $p^{-1}(x) \cap q^{-1}(y)$ is tame.

Here $p^{-1}(x) \cap q^{-1}(y)$ is the subgroupoid of S whose objects lie in both $p^{-1}(x)$ and $q^{-1}(y)$, and whose morphisms lie in both $p^{-1}(x)$ and $q^{-1}(y)$.

If S is tame, then for any $\psi \in \mathbb{R}^{\underline{X}}$ we have

$$(\underbrace{S}\psi)([y]) = \sum_{[x] \in \underline{X}} \sum_{[s] \in \underline{p^{-1}(x)} \bigcap \underline{q^{-1}(y)}} \frac{|\mathrm{Aut}(x)|}{|\mathrm{Aut}(s)|} \, \psi([x]) \,.$$

Proof. First suppose the span S is tame and $v \colon \Psi \to X$ is a tame groupoid over X. Equations 13 and 15 show that if S, X, Y, and Ψ are skeletal, and Ψ has just one object $*$, then

$$\underbrace{S}\underbrace{\Psi}([y]) = \sum_{s \in p^{-1}(x) \cap q^{-1}(y)} \frac{|\mathrm{Aut}(v(*))|}{|\mathrm{Aut}(s)||\mathrm{Aut}(*)|}$$

On the other hand,

$$\underbrace{\Psi}([x]) = \begin{cases} \dfrac{1}{|\mathrm{Aut}(*)|} & \text{if } v(*) = x \\ \\ 0 & \text{otherwise.} \end{cases}$$

So in this case, writing $\underbrace{\Psi}$ as ψ, we have

$$(\underbrace{S}\psi)([y]) = \sum_{[x] \in X} \sum_{[s] \in p^{-1}(x) \bigcap \underline{q^{-1}(y)}} \frac{|\mathrm{Aut}(x)|}{|\mathrm{Aut}(s)|} \, \psi([x]) \,.$$

Since both sides are linear in ψ, and every nonnegative function in $\mathbb{R}^{\underline{X}}$ is a pointwise convergent nonnegative linear combination of functions of the form $\psi = \underbrace{\Psi}$ with Ψ as above, the above equation in fact holds for *all* $\psi \in \mathbb{R}^{\underline{X}}$.

Since all groupoids in sight are skeletal, we may equivalently write the above equation as

$$(\underbrace{S}\psi)([y]) = \sum_{[x] \in \underline{X}} \sum_{[s] \in \underline{p^{-1}(x)} \bigcap \underline{q^{-1}(y)}} \frac{|\mathrm{Aut}(x)|}{|\mathrm{Aut}(s)|} \, \psi([x]) \,.$$

The advantage of this formulation is that now both sides are unchanged when we replace X and Y by equivalent groupoids, and replace S by an equivalent span. So, this equation holds for all tame spans, as was to be shown.

If the span S is tame, the sum above must converge for all functions ψ of the form $\psi = \underbrace{\Psi}$. Any nonnegative function $\psi \colon \underline{X} \to \mathbb{R}$ is of this form. For the sum above to converge for *all* nonnegative ψ, this sum:

$$\sum_{[s] \in \underline{p^{-1}(x)} \bigcap \underline{q^{-1}(y)}} \frac{|\mathrm{Aut}(x)|}{|\mathrm{Aut}(s)|}$$

must have the following two properties:

1. For any object $y \in Y$, it is nonzero only for objects x in a finite number of isomorphism classes of X.

2. For every $x \in X$ and $y \in Y$, it converges to a finite number.

These conditions are equivalent to conditions 1) and 2) in the statement of the theorem. We leave it as an exercise to check that these conditions are not only necessary but also sufficient for S to be tame. ∎

The previous theorem has many nice consequences. For example:

5.11. Proposition. *Suppose S and T are tame spans from a groupoid X to a groupoid Y. Then $\underset{\sim}{S+T} = \underset{\sim}{S} + \underset{\sim}{T}$.*

Proof. This follows from the explicit formula given in Theorem 5.10. ∎

6. Properties of Degroupoidification

In this section we prove all the remaining results stated in Section 2. We start with results about scalar multiplication. Then we show that degroupoidification is a functor. Finally, we prove the results about inner products and adjoints.

6.1. Scalar Multiplication. To prove facts about scalar multiplication, we use the following lemma:

6.2. Lemma. *Given a groupoid Λ and a functor between groupoids $p\colon X \to Y$, then the functor $c \times p\colon \Lambda \times Y \to 1 \times X$ (where $c\colon \Lambda \to 1$ is the unique morphism from Λ to the terminal groupoid 1) satisfies:*

$$|(c \times p)^{-1}(1, x)| = |\Lambda|\, |p^{-1}(x)|$$

for all $x \in X$.

Proof. By the definition of full inverse image we have

$$(c \times p)^{-1}(1, x) \cong \Lambda \times p^{-1}(x).$$

In the product $\Lambda \times p^{-1}(x)$, an automorphism of an object (λ, y) is an automorphism of λ together with an automorphism of y. We thus obtain

$$|(c \times p)^{-1}(1, x)| = \sum_{[\lambda] \in \underline{\Lambda}} \sum_{[y] \in \underline{p^{-1}(x)}} \frac{1}{|\mathrm{Aut}(\lambda)|} \frac{1}{|\mathrm{Aut}(y)|}$$

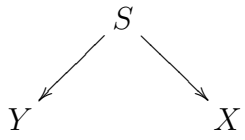
which is equal to $|\Lambda|\, |p^{-1}(x)|$, as desired. ∎

6.3. Proposition. *Given a groupoid Λ and a groupoid over X, say $v\colon \Psi \to X$, the groupoid $\Lambda \times \Psi$ over X satisfies*

$$\underset{\sim}{\Lambda \times \Psi} = |\Lambda| \underset{\approx}{\Psi}.$$

Proof. This follows from Lemma 6.2. ∎

6.4. Proposition. *Given a tame groupoid Λ and a tame span*



then $\Lambda \times S$ is tame and

$$\underset{\sim}{\Lambda \times S} = |\Lambda| \underset{\approx}{S}.$$

Proof. This follows from Lemma 6.2. ∎

6.5. Functoriality of Degroupoidification. In this section we prove that our process of turning groupoids into vector spaces and spans of groupoids into linear operators is indeed a functor. We first show that the process preserves identities, then show associativity of composition, from which many other things follow, including the preservation of composition. The lemmas in this section add up to a proof of the following theorem:

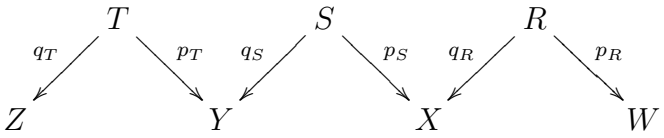
6.6. Theorem. *Degroupoidification is a functor from the category of groupoids and equivalence classes of tame spans to the category of real vector spaces and linear operators.*

Proof. As mentioned above, the proof follows from Lemmas 6.7 and 6.9. ∎

6.7. Lemma. *Degroupoidification preserves identities, i.e., given a groupoid X, $\underset{\sim}{1_X} = 1_{\mathbb{R}^{\underset{\sim}{X}}}$, where 1_X is the identity span from X to X and $1_{\mathbb{R}^{\underset{\sim}{X}}}$ is the identity operator on $\mathbb{R}^{\underset{\sim}{X}}$.*

Proof. This follows from the explicit formula given in Theorem 5.10. ∎

We now want to prove the associativity of composition of tame spans. Amongst the consequences of this proposition we can derive the preservation of composition under degroupoidification. Given a triple of composable spans:



we want to show that composing in the two possible orders—$T(SR)$ or $(TS)R$—will provide equivalent spans of groupoids. In fact, since groupoids, spans of groupoids, and isomorphism classes of maps between spans of groupoids naturally form a bicategory, there exists a natural isomorphism called the **associator**. This tells us that the spans $T(SR)$ and $(TS)R$ are in fact equivalent. But since we have not constructed this bicategory, we will instead give an explicit construction of the equivalence $T(SR) \xrightarrow{\sim} (TS)R$.

6.8. PROPOSITION. *Given a composable triple of tame spans, the operation of composition of tame spans by weak pullback is associative up to equivalence of spans of groupoids.*

PROOF. We consider the above triple of spans in order to construct the aforementioned equivalence. The equivalence is simple to describe if we first take a close look at the groupoids $T(SR)$ and $(TS)R$. The composite $T(SR)$ has objects $(t,(s,r,\alpha),\beta)$ such that $r \in R$, $s \in S$, $t \in T$, $\alpha\colon q_R(r) \to p_S(s)$, and $\beta\colon q_S(s) \to p_T(t)$, and morphisms $f\colon (t,(s,r,\alpha),\beta) \to (t',(s',r',\alpha'),\beta')$ which consist of a map $g\colon (s,r,\alpha) \to (s',r',\alpha')$ in SR and a map $h\colon t \to t'$ such that the following diagram commutes:

$$\begin{array}{ccc} q_S\pi_s((s,r,\alpha)) & \xrightarrow{\beta} & p_T(t) \\ {\scriptstyle q_S\pi_S(g)}\downarrow & & \downarrow{\scriptstyle p_T(h)} \\ q_S\pi_s((s',r',\alpha')) & \xrightarrow[\beta']{} & p_T(t') \end{array}$$

where π_S maps the composite SR to S. Further, g consists of a pair of maps $k\colon r \to r'$ and $j\colon s \to s'$ such that the following diagram commutes:

$$\begin{array}{ccc} q_R(r) & \xrightarrow{\alpha} & p_S(s) \\ {\scriptstyle q_S(k)}\downarrow & & \downarrow{\scriptstyle p_S(j)} \\ q_R(r') & \xrightarrow[\alpha']{} & p_S(s') \end{array}$$

The groupoid $(TS)R$ has objects $((t,s,\alpha),r,\beta)$ such that $r \in R$, $s \in S$, $t \in T$, $\alpha\colon q_S(s) \to p_T(t)$, and $\beta\colon q_R(r) \to p_S(s)$, and morphisms $f\colon ((t,s,\alpha),r,\beta) \to ((t',s',\alpha'),r',\beta')$, which consist of a map $g\colon (t,s,\alpha) \to (t',s',\alpha')$ in TS and a map $h\colon r \to r'$ such that the following diagram commutes:

$$\begin{array}{ccc} p_R(r) & \xrightarrow{\beta} & p_S\pi_s((t,s,\alpha)) \\ {\scriptstyle p_R(h)}\downarrow & & \downarrow{\scriptstyle p_S\pi_S(g)} \\ p_R(r') & \xrightarrow[\beta']{} & p_S\pi_s((t',s',\alpha')) \end{array}$$

Further, g consists of a pair of maps $k\colon s \to s'$ and $j\colon t \to t'$ such that the following diagram commutes:

$$\begin{array}{ccc} q_S(s) & \xrightarrow{\alpha} & p_T(t) \\ {\scriptstyle q_S(k)}\downarrow & & \downarrow{\scriptstyle p_T(j)} \\ q_S(s') & \xrightarrow[\alpha']{} & p_T(t') \end{array}$$

We can now write down a functor $F\colon T(SR) \to (TS)R$:

$$(t,(s,r,\alpha),\beta) \mapsto ((t,s,\beta),r,\alpha)$$

Again, a morphism $f\colon (t,(s,r,\alpha),\beta) \to (t',(s',r',\alpha'),\beta')$ consists of maps $k\colon r \to r'$, $j\colon s \to s'$, and $h\colon t \to t'$. We need to define $F(f)\colon ((t,s,\beta),r,\alpha) \to ((t',s',\beta'),r',\alpha')$. The first component $g'\colon (t,s,\beta) \to (t',s',\beta')$ consists of the maps $j\colon s \to s'$ and $h\colon t \to t'$, and the following diagram commutes:

$$\begin{array}{ccc} q_S(s) & \xrightarrow{\beta} & p_T(t) \\ {\scriptstyle q_S(j)}\downarrow & & \downarrow{\scriptstyle p_T(h)} \\ q_S(s') & \xrightarrow[\beta']{} & p_T(t') \end{array}$$

The other component map of $F(f)$ is $k\colon r \to r'$ and we see that the following diagram also commutes:

$$\begin{array}{ccc} p_R(r) & \xrightarrow{\alpha} & p_S\pi_s((t,s,\beta)) \\ {\scriptstyle p_R(k)}\downarrow & & \downarrow{\scriptstyle p_S\pi_S(g')} \\ p_R(r') & \xrightarrow[\alpha']{} & p_S\pi_s((t',s',\beta')) \end{array}$$

thus, defining a morphism in $(TS)R$.

We now just need to check that F preserves identities and composition and that it is indeed an isomorphism. We will then have shown that the apexes of the two spans are isomorphic. First, given an identity morphism $1\colon (t,(s,r,\alpha),\beta) \to (t,(s,r,\alpha),\beta)$, then $F(1)$ is the identity morphism on $((t,s,\beta),r,\alpha)$. The components of the identity morphism are the respective identity morphisms on the objects r,s, and t. By the construction of F, it is clear that $F(1)$ will then be an identity morphism.

Given a pair of composable maps $f\colon (t,(s,r,\alpha),\beta) \to (t',(s',r',\alpha'),\beta')$ and $f'\colon (t',(s',r',\alpha'),\beta') \to (t'',(s'',r'',\alpha''),\beta'')$ in $T(SR)$, the composite is a map $f'f$ with components $g'g\colon (s,r,\alpha) \to (s'',r'',\alpha'')$ and $h'h\colon t \to t''$. Further, $g'g$ has component morphisms $k'k\colon r \to r''$ and $j'j\colon s \to s'$. It is then easy to check that under the image of F this composition is preserved.

The construction of the inverse of F is implicit in the construction of F, and it is easy to verify that each composite FF^{-1} and $F^{-1}F$ is an identity functor. Further, the natural isomorphisms required for an equivalence of spans can each be taken to be the identity. ∎

It follows from the associativity of composition that degroupoidification preserves composition:

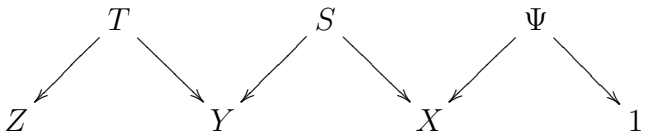
6.9. Lemma. *Degroupoidification preserves composition. That is, given a pair of composable tame spans:*

$$\begin{array}{ccccc} & T & & S & \\ \swarrow & & \searrow & \swarrow & \searrow \\ Z & & Y & & X \end{array}$$

we have

$$\underset{\sim}{T}\underset{\sim}{S} = \underset{\sim}{TS}.$$

PROOF. Consider the composable pair of spans above along with a groupoid Ψ over X:



We can consider the groupoid over X as a span by taking the right leg to be the unique map to the terminal groupoid. We can compose this triple of spans in two ways; either $T(S\Psi)$ or $(TS)\Psi$. By the Proposition 6.8 stated above, these spans are equivalent. By Theorem 5.8, degroupoidification produces the same linear operators. Thus, composition is preserved. That is,

$$\underset{\sim}{T}\underset{\sim}{S}\underset{\sim}{\Psi} = \underset{\sim}{T}\underset{\sim}{S}\underset{\sim}{\Psi}.$$

■

6.10. INNER PRODUCTS AND ADJOINTS. Now we prove our results about the inner product of groupoids over a fixed groupoid, and the adjoint of a span:

6.11. THEOREM. *Given a groupoid X, there is a unique inner product $\langle \cdot, \cdot \rangle$ on the vector space $L^2(X)$ such that*

$$\langle \underset{\sim}{\Phi}, \underset{\sim}{\Psi} \rangle = |\langle \Phi, \Psi \rangle|$$

whenever Φ and Ψ are square-integrable groupoids over X. With this inner product $L^2(X)$ is a real Hilbert space.

PROOF. Uniqueness of the inner product follows from the formula, since every vector in $L^2(X)$ is a finite-linear combination of vectors $\underset{\sim}{\Psi}$ for square-integrable groupoids Ψ over X. To show the inner product exists, suppose that Ψ_i, Φ_i are square-integrable groupoids over X and $\alpha_i, \beta_i \in \mathbb{R}$ for $1 \leq i \leq n$. Then we need to check that

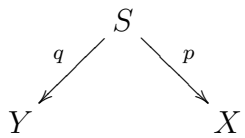
$$\sum_i \alpha_i \underset{\sim}{\Psi}_i = \sum_j \beta_j \underset{\sim}{\Phi}_j = 0$$

implies

$$\sum_{i,j} \alpha_i \beta_j \, |\langle \Psi_i, \Phi_j \rangle| = 0.$$

The proof here closely resembles the proof of existence in Theorem 5.7. We leave to the reader the task of checking that $L^2(X)$ is complete in the norm corresponding to this inner product. ■

6.12. PROPOSITION. *Given a span*



and a pair $v\colon \Psi \to X$, $w\colon \Phi \to Y$ of groupoids over X and Y, respectively, there is an equivalence of groupoids

$$\langle \Phi, S\Psi \rangle \simeq \langle S^\dagger \Phi, \Psi \rangle.$$

PROOF. We can consider the groupoids over X and Y as spans with one leg over the terminal groupoid 1. Then the result follows from the equivalence given by associtativity in Lemma 6.8 and Theorem 5.8. Explicitly, $\langle \Phi, S\Psi \rangle$ is the composite of spans $S\Psi$ and Φ, while $\langle S^\dagger \Phi, \Psi \rangle$ is the composite of spans $S^\dagger \Phi$ and Ψ. ∎

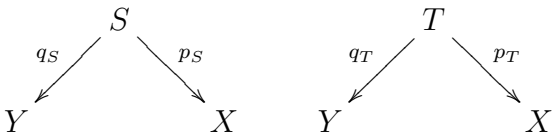
6.13. PROPOSITION. *Given spans*

there is an equivalence of spans

$$(ST)^\dagger \simeq T^\dagger S^\dagger.$$

PROOF. This is clear by the definition of composition. ∎

6.14. PROPOSITION. *Given spans*



there is an equivalence of spans

$$(S + T)^\dagger \simeq S^\dagger + T^\dagger.$$

PROOF. This is clear since the addition of spans is given by coproduct of groupoids. This construction is symmetric with respect to swapping the legs of the span. ∎

6.15. PROPOSITION. *Given a groupoid Λ and square-integrable groupoids Φ, Ψ, and Ψ' over X, we have the following equivalences of groupoids:*

1. $$\langle \Phi, \Psi \rangle \simeq \langle \Psi, \Phi \rangle.$$

2. $$\langle \Phi, \Psi + \Psi' \rangle \simeq \langle \Phi, \Psi \rangle + \langle \Phi, \Psi' \rangle.$$

3. $$\langle \Phi, \Lambda \times \Psi \rangle \simeq \Lambda \times \langle \Phi, \Psi \rangle.$$

PROOF. Each part will follow easily from the definition of weak pullback. First we label the maps for the groupoids over X as $v\colon \Phi \to X$, $w\colon \Psi \to X$, and $w'\colon \Psi' \to X$.

1. $\langle \Phi, \Psi \rangle \simeq \langle \Psi, \Phi \rangle$.
   By definition of weak pullback, an object of $\langle \Phi, \Psi \rangle$ is a triple (a, b, α) such that $a \in \Phi, b \in \Psi$, and $\alpha\colon v(a) \to w(b)$. Similarly, an object of $\langle \Psi, \Phi \rangle$ is a triple (b, a, β) such that $b \in \Psi, a \in \Phi$, and $\beta\colon w(b) \to v(a)$. Since α is invertible, there is an evident equivalence of groupoids.

2. $\langle \Phi, \Psi + \Psi' \rangle \simeq \langle \Phi, \Psi \rangle + \langle \Phi, \Psi' \rangle$.
   Recall that in the category of groupoids, the coproduct is just the disjoint union over objects and morphisms. With this it is easy to see that the definition of weak pullback will 'split' over union.

3. $\langle \Phi, \Lambda \times \Psi \rangle \simeq \Lambda \times \langle \Phi, \Psi \rangle$.
   This follows from the associativity (up to isomorphism) of the cartesian product.

∎

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A. Review of Groupoids

A.1. DEFINITION. *A* **groupoid** *is a category in which all morphisms are invertible.*

A.2. DEFINITION. *We denote the set of objects in a groupoid X by* $\mathrm{Ob}(X)$ *and the set of morphisms by* $\mathrm{Mor}(X)$.

A.3. DEFINITION. *A* **functor** $F\colon X \to Y$ *between categories is a pair of functions* $F\colon \mathrm{Ob}(X) \to \mathrm{Ob}(Y)$ *and* $F\colon \mathrm{Mor}(X) \to \mathrm{Mor}(Y)$ *such that* $F(1_x) = 1_{F(x)}$ *for* $x \in \mathrm{Ob}(X)$ *and* $F(gh) = F(g)F(h)$ *for* $g, h \in \mathrm{Mor}(X)$.

A.4. DEFINITION. *A* **natural transformation** $\alpha\colon F \Rightarrow G$ *between functors* $F, G\colon X \to Y$ *consists of a morphism* $\alpha_x\colon F(x) \to G(x)$ *in* $\mathrm{Mor}(Y)$ *for each* $x \in \mathrm{Ob}(X)$ *such that for each morphism* $h\colon x \to x'$ *in* $\mathrm{Mor}(X)$ *the following naturality square commutes:*

$$\begin{array}{ccc} F(x) & \xrightarrow{\alpha_x} & G(x) \\ {\scriptstyle F(h)}\downarrow & & \downarrow{\scriptstyle G(h)} \\ F(x') & \xrightarrow[\alpha_{x'}]{} & G(x') \end{array}$$

A.5. Definition. *A* **natural isomorphism** *is a natural transformation $\alpha\colon F \Rightarrow G$ between functors $F, G\colon X \to Y$ such that for each $x \in X$, the morphism α_x is invertible.*

Note that a natural transformation between functors between *groupoids* is necessarily a natural isomorphism.

In what follows, and throughout the paper, we write $x \in X$ as shorthand for $x \in \mathrm{Ob}(X)$. Also, several places throughout this paper we have used the notation $\alpha \cdot F$ or $F \cdot \alpha$ to denote operations combining a functor F and a natural transformation α. These operations are called 'whiskering':

A.6. Definition. *Given groupoids X, Y and Z, functors $F\colon X \to Y$, $G\colon Y \to Z$ and $H\colon Y \to Z$, and a natural transformation $\alpha\colon G \Rightarrow H$, there is a natural transformation $\alpha \cdot F\colon GF \Rightarrow HF$ called the* **right whiskering** *of α by F. This assigns to any object $x \in X$ the morphism $\alpha_{F(x)}\colon G(F(x)) \to H(F(x))$ in Z, which we denote as $(\alpha \cdot F)_x$. Similarly, given a groupoid W and a functor $J\colon Z \to W$, there is a natural transformation $J \cdot \alpha\colon JG \Rightarrow JH$ called the* **left whiskering** *of α by J. This assigns to any object $y \in Y$ the morphism $J(\alpha_y)\colon JG(y) \to JH(y)$ in W, which we denote as $(J \cdot \alpha)_y$.*

A.7. Definition. *A functor $F\colon X \to Y$ between groupoids is called an* **equivalence** *if there exists a functor $G\colon Y \to X$, called the* **weak inverse** *of F, and natural isomorphisms $\eta\colon GF \Rightarrow 1_X$ and $\rho\colon FG \Rightarrow 1_Y$. In this case we say X and Y are* **equivalent**.

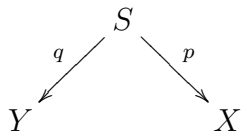
A.8. Definition. *A functor $F\colon X \to Y$ between groupoids is called* **faithful** *if for each pair of objects $x, y \in X$ the function $F\colon \hom(x,y) \to \hom(F(x),F(y))$ is injective.*

A.9. Definition. *A functor $F\colon X \to Y$ between groupoids is called* **full** *if for each pair of objects $x, y \in X$, the function $F\colon \hom(x,y) \to \hom(F(x),F(y))$ is surjective.*

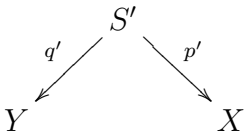
A.10. Definition. *A functor $F\colon X \to Y$ between groupoids is called* **essentially surjective** *if for each object $y \in Y$, there exists an object $x \in X$ and a morphism $f\colon F(x) \to y$ in Y.*

A functor has all three of the above properties if and only if the functor is an equivalence. It is often convenient to prove two groupoids are equivalent by exhibiting a functor which is full, faithful and essentially surjective.

A.11. Definition. *A* **map** *from the span of groupoids*

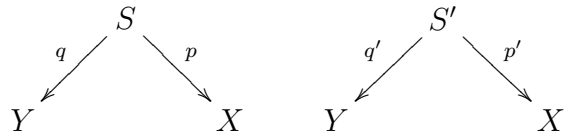


to the span of groupoids



is a functor $F\colon S \to S'$ together with natural transformations $\alpha\colon p \Rightarrow p'F$, $\beta\colon q \Rightarrow q'F$.

A.12. Definition. *An* **equivalence** *of spans of groupoids*



is a map of spans (F, α, β) *from* S *to* S' *together with a map of spans* (G, α', β') *from* S' *to* S *and natural isomorphisms* $\gamma\colon GF \Rightarrow 1$ *and* $\gamma'\colon FG \Rightarrow 1$ *such that the following equations hold:*

$$1_p = (p \cdot \gamma)(\alpha' \cdot F)\alpha \qquad 1_q = (q \cdot \gamma)(\beta' \cdot F)\beta$$
$$1_{p'} = (p' \cdot \gamma')(\alpha \cdot G)\alpha' \qquad 1_{q'} = (q' \cdot \gamma')(\beta \cdot G)\beta'.$$

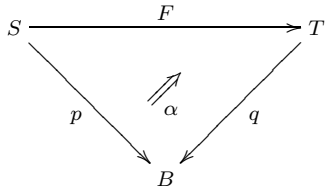
A.13. Lemma. *Given equivalent groupoids* X *and* Y, $|X| = |Y|$.

Proof. From a functor $F\colon X \to Y$ between groupoids, we can obtain a function $\underline{F}\colon \underline{X} \to \underline{Y}$. If F is an equivalence, $\underline{F}$ is a bijection. Since these are the indexing sets for the sum in the definition of groupoid cardinality, we just need to check that for a pair of elements $[x] \in \underline{X}$ and $[y] \in \underline{Y}$ such that $\underline{F}([x]) = [y]$, we have $|\mathrm{Aut}(x)| = |\mathrm{Aut}(y)|$. This follows from F being full and faithful, and that the cardinality of automorphism groups is an invariant of an isomorphism class of objects in a groupoid. Thus,

$$|X| = \sum_{x \in \underline{X}} \frac{1}{|\mathrm{Aut}(x)|} = \sum_{y \in \underline{Y}} \frac{1}{|\mathrm{Aut}(y)|} = |Y|.$$

■

A.14. Lemma. *Given a diagram of groupoids*



where F *is an equivalence of groupoids, the restriction of* F *to the full inverse image* $p^{-1}(b)$

$$F|_{p^{-1}(b)}\colon p^{-1}(b) \to q^{-1}(b)$$

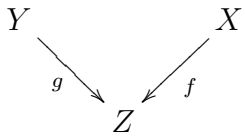
is an equivalence of groupoids, for any object $b \in B$.

Proof. It is sufficient to check that $F|_{p^{-1}(b)}$ is a full, faithful, and essentially surjective functor from $p^{-1}(b)$ to $q^{-1}(b)$. First we check that the image of $F|_{p^{-1}(b)}$ indeed lies in $q^{-1}(b)$. Given $b \in B$ and $x \in p^{-1}(b)$, there is a morphism $\alpha_x\colon p(x) \to qF(x)$ in B. Since $p(x) \in [b]$, then $qF(x) \in [b]$. It follows that $F(x) \in q^{-1}(b)$. Next we check that $F|_{p^{-1}(b)}$ is full and faithful. This follows from the fact that full inverse images are full subgroupoids. It is clear that a full and faithful functor restricted to a full subgroupoid will again be full

and faithful. We are left to check only that $F|_{p^{-1}(b)}$ is essentially surjective. Let $y \in q^{-1}(b)$. Then, since F is essentially surjective, there exists $x \in S$ such that $F(x) \in [y]$. Since $qF(x) \in [b]$ and there is an isomorphism $\alpha_x \colon p(x) \to qF(x)$, it follows that $x \in q^{-1}(b)$. So $F|_{p^{-1}(b)}$ is essentially surjective. We have shown that $F|_{p^{-1}(b)}$ is full, faithful, and essentially surjective, and, thus, is an equivalence of groupoids. ∎

The data needed to construct a weak pullback of groupoids is a 'cospan':

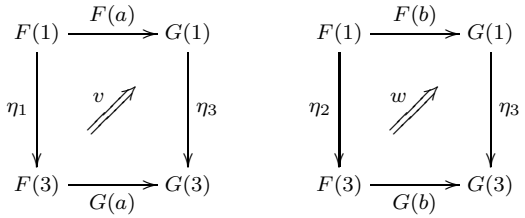
A.15. Definition. *Given groupoids X and Y, a* **cospan** *from X to Y is a diagram*



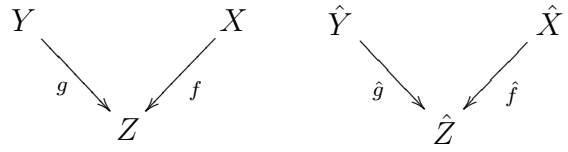
where Z is groupoid and $f \colon X \to Z$ and $g \colon Y \to Z$ are functors.

We next prove a lemma stating that the weak pullbacks of equivalent cospans are equivalent. Weak pullbacks, also called *iso-comma objects*, are part of a much larger family of limits called *flexible limits*. To read more about flexible limits, see the work of Street [40] and Bird [8]. A vastly more general theorem than the one we intend to prove holds in this class of limits. Namely: for any pair of parallel functors F, G from an indexing category to Cat with a pseudonatural equivalence $\eta \colon F \Rightarrow G$, the pseudo-limits of F and G are equivalent. But to make the paper self-contained, we strip this theorem down and give a hands-on proof of the case we need.

To show that equivalent cospans of groupoids have equivalent weak pullbacks, we need to say what it means for a pair of cospans to be equivalent. As stated above, this means that they are given by a pair of parallel functors F, G from the category consisting of a three-element set of objects $\{1, 2, 3\}$ and two morphisms $a \colon 1 \to 3$ and $b \colon 2 \to 3$. Further there is a pseudonatural equivalence $\eta \colon F \to G$. In simpler terms, this means that we have equivalences $\eta_i \colon F(i) \to G(i)$ for $i = 1, 2, 3$, and squares commuting up to natural isomorphism:

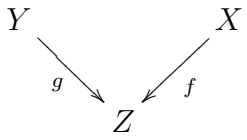


For ease of notation we will consider the equivalent cospans:

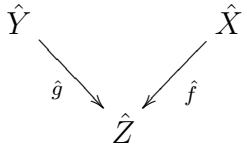


with equivalences $\hat{x} \colon X \to \hat{X}$, $\hat{y} \colon Y \to \hat{Y}$, and $\hat{z} \colon Z \to \hat{Z}$ and natural isomorphisms $v \colon \hat{z}f \Rightarrow \hat{f}\hat{x}$ and $w \colon \hat{z}g \Rightarrow \hat{g}\hat{y}$.

A.16. LEMMA. *Given equivalent cospans of groupoids as described above, the weak pullback of the cospan*



is equivalent to the weak pullback of the cospan



PROOF. We construct a functor F between the weak pullbacks XY and $\hat{X}\hat{Y}$ and show that this functor is an equivalence of groupoids, i.e., that it is full, faithful and essentially surjective. We recall that an object in the weak pullback XY is a triple (r, s, α) with $r \in X$, $s \in Y$ and $\alpha\colon f(r) \to g(s)$. A morphism in $\rho\colon (r, s, \alpha) \to (r', s', \alpha')$ in XY is given by a pair of morphisms $j\colon r \to r'$ in X and $k\colon s \to s'$ in Y such that $g(k)\alpha = \alpha' f(j)$. We define

$$F\colon XY \to \hat{X}\hat{Y}$$

on objects by

$$(r, s, \alpha) \mapsto (\hat{x}(r), \hat{y}(s), w_s^{-1}\hat{z}(\alpha)v_r)$$

and on a morphism ρ by sending j to $\hat{x}(j)$ and k to $\hat{y}(k)$. To check that this functor is well-defined we consider the following diagram:

$$\begin{array}{ccccccc}
\hat{f}\hat{x}(r) & \xrightarrow{v_r} & \hat{z}f(r) & \xrightarrow{\hat{z}(\alpha)} & \hat{z}g(s) & \xrightarrow{w_s^{-1}} & \hat{g}\hat{y}(s) \\
\downarrow{\scriptstyle \hat{f}\hat{x}(j)} & & \downarrow{\scriptstyle \hat{z}f(j)} & & \downarrow{\scriptstyle \hat{z}g(k)} & & \downarrow{\scriptstyle \hat{g}\hat{y}(k)} \\
\hat{f}\hat{x}(r') & \xrightarrow[v_{r'}]{} & \hat{z}f(r') & \xrightarrow[\hat{z}(\alpha')]{} & \hat{z}g(s') & \xrightarrow[w_{s'}^{-1}]{} & \hat{g}\hat{y}(s')
\end{array}$$

The inner square commutes by the assumption that ρ is a morphism in XY. The outer squares commute by the naturality of v and w. Showing that F respects identities and composition is straightforward.

We first check that F is faithful. Let $\rho, \sigma\colon (r, s, \alpha) \to (r', s', \alpha')$ be morphisms in XY such that $F(\rho) = F(\sigma)$. Assume ρ consists of morphisms $j\colon r \to r'$, $k\colon s \to s'$ and σ consists of morphisms $l\colon r \to r'$ and $m\colon s \to s'$. It follows that $\hat{x}(j) = \hat{x}(l)$ and $\hat{y}(k) = \hat{y}(m)$. Since $\hat{x}$ and $\hat{y}$ are faithful we have that $j = l$ and $k = m$. Thus, we have shown that $\rho = \sigma$ and F is faithful.

To show that F is full, we assume (r, s, α) and (r', s', α') are objects in XY and $\rho\colon (\hat{x}(r), \hat{y}(s), \hat{z}(\alpha)) \to (\hat{x}(r'), \hat{y}(s'), \hat{z}(\alpha'))$ is a morphism in $\hat{X}\hat{Y}$ consisting of morphisms $j\colon \hat{x}(r) \to \hat{x}(r')$ and $k\colon \hat{y}(s) \to \hat{y}(s')$. Since $\hat{x}$ and $\hat{y}$ are full, there exist morphisms

$\tilde{j}\colon r \to r'$ and $\tilde{k}\colon s \to s'$ such that $\hat{x}(\tilde{j}) = j$ and $\hat{y}(\tilde{k}) = k$. We consider the following diagram:

$$\begin{array}{ccccccc}
\hat{z}(f(r)) & \xrightarrow{v_r^{-1}} & \hat{f}\hat{x}(r) & \xrightarrow{\hat{z}(\alpha)} & \hat{g}\hat{y}(s) & \xrightarrow{w_s} & \hat{z}(g(s)) \\
\downarrow{\scriptstyle \hat{z}(f(\tilde{j}))} & & \downarrow{\scriptstyle \hat{f}\hat{x}(\tilde{j})} & & \downarrow{\scriptstyle \hat{g}\hat{y}(\tilde{k})} & & \downarrow{\scriptstyle \hat{z}(g(\tilde{k}))} \\
\hat{z}(f(r')) & \xrightarrow[v_{r'}^{-1}]{} & \hat{f}\hat{x}(r') & \xrightarrow[\hat{z}(\alpha')]{} & \hat{g}\hat{y}(s') & \xrightarrow[w_s]{} & \hat{z}(g(s'))
\end{array}$$

The center square commutes by the assumption that ρ is a morphism in $\hat{X}\hat{Y}$, and the outer squares commute by naturality of v and w. Since $\hat{z}$ is full, there exists morphisms $\bar{\alpha}\colon f(r) \to g(s)$ and $\bar{\alpha'}\colon f(r') \to g(s')$ such that $\hat{z}(\bar{\alpha}) = w_s \hat{z}(\alpha) v_r^{-1}$ and $\hat{z}(\bar{\alpha'}) = w_{s'} \hat{z}(\alpha') v_{r'}^{-1}$. Now since $\hat{z}$ is faithful, we have that

$$\begin{array}{ccc}
f(r) & \xrightarrow{\bar{\alpha}} & g(s) \\
\downarrow{\scriptstyle f(\tilde{j})} & & \downarrow{\scriptstyle g(\tilde{k})} \\
f(r') & \xrightarrow[\bar{\alpha'}]{} & g(s')
\end{array}$$

commutes. Hence, F is full.

To show F is essentially surjective we let (r, s, α) be an object in $\hat{X}\hat{Y}$. Since $\hat{x}$ and $\hat{y}$ are essentially surjective, there exist $\tilde{r} \in X$ and $\tilde{s} \in Y$ with isomorphisms $\beta\colon \hat{x}(\tilde{r}) \to r$ and $\gamma\colon \hat{y}(\tilde{s}) \to s$. We thus have the isomorphism:

$$\hat{z}(f(\tilde{r})) \xrightarrow{v_{\tilde{r}}^{-1}} \hat{f}(\hat{x}(\tilde{r})) \xrightarrow{\hat{f}(\beta)} \hat{f}(r) \xrightarrow{\alpha} \hat{g}(s) \xrightarrow{\hat{g}(\gamma^{-1})} \hat{g}(\hat{y}(\tilde{s})) \xrightarrow{w_{\tilde{s}}} \hat{z}(g(\tilde{s}))$$

Since $\hat{z}$ is full, there exists an isomorphism $\mu\colon f(\tilde{r}) \to g(\tilde{s})$ such that $\hat{z}(\mu) = w_s \hat{g}(\gamma^{-1}) \alpha \hat{f}(\beta) v_r^{-1}$. We have constructed an object $(\tilde{r}, \tilde{s}, \mu)$ in XY and we need to find an isomorphism from $F((\tilde{r}, \tilde{s}, \mu) = (\hat{x}(\tilde{r}), \hat{y}(\tilde{s}), w_s^{-1} \hat{z}(\mu) v_r)$ to (r, s, α). This morphism consists of $\beta\colon \hat{x}(\tilde{r}) \to r$ and $\gamma\colon \hat{y}(\tilde{s}) \to s$. That this is an isomorphism follows from β, γ being isomorphisms and the following calculation:

$$\begin{aligned}
\hat{g}(\gamma) w_s^{-1} \hat{z}(\mu) v_r &= \hat{g}(\gamma) w_{\tilde{s}}^{-1} w_{\tilde{s}} \hat{g}(\gamma^{-1}) \alpha \hat{f}(\beta) v_{\tilde{r}}^{-1} v_{\tilde{r}} \\
&= \alpha \hat{f}(\beta)
\end{aligned}$$

We have now shown that F is essentially surjective, and thus an equivalence of groupoids.

■

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